Entered: October 28, 2014

### UNITED STATES PATENT AND TRADEMARK OFFICE

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### BEFORE THE PATENT TRIAL AND APPEAL BOARD

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PARROT S.A. and PARROT, INC., Petitioner,

v.

DRONE TECHNOLOGIES, INC., Patent Owner.

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Case IPR2014-00730 Patent 7,584,071 B2

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Before HOWARD B. BLANKENSHIP, MATTHEW R. CLEMENTS, and CHRISTOPHER M. KAISER, *Administrative Patent Judges*.

BLANKENSHIP, Administrative Patent Judge.

## DECISION Institution of *Inter Partes* Review 37 C.F.R. § 42.108

### I. BACKGROUND

Parrot S.A. and Parrot, Inc. (collectively, "Petitioner") filed a petition requesting an *inter partes* review of claims 1–15 of U.S. Patent No. 7,584,071 B2 (Ex. 1001, "the '071 patent") under 35 U.S.C. §§ 311–319. Paper 1 ("Petition" or "Pet."). Patent Owner, Drone Technologies, Inc.,



filed a preliminary response as permitted by 37 C.F.R. § 42.107. Paper 7 ("Prelim. Resp."). We have jurisdiction under 35 U.S.C. § 314. Section 314 provides that an *inter partes* review may not be instituted "unless . . . the information presented in the petition . . . shows that there is a reasonable likelihood that the petitioner would prevail with respect to at least 1 of the claims challenged in the petition."

For the reasons that follow, we institute an *inter partes* review of claims 1–15 of the '071 patent.

### A. Related Proceedings

According to Petitioner, the '071 patent is involved in the following lawsuit: *Drone Technologies, Inc. v. Parrot S.A.*, No. 2:05-mc-02025 (W.D. Pa.). Pet. 4.

### B. The '071 Patent

The '071 patent relates to a remote control system in which a remote control apparatus transmits a target motion signal to a remote-controlled motion apparatus. Ex. 1001, Abstract.

Figure 2 of the '071 patent is reproduced below.



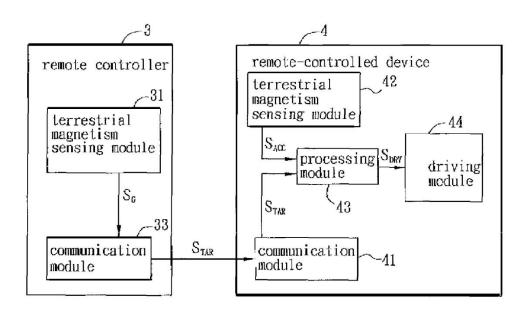


FIG. 2

Figure 2 is a system diagram of a remote control system. Ex. 1001, col. 3, ll. 13–14. Remote-controlled device 4 consists of communication module 41, terrestrial magnetism sensing module 42, processing module 43, and driving module 44. Communication module 41 receives target motion signal  $S_{TAR}$  from remote controller 3. *Id.* at col. 3, ll. 28–35. Remote controller 3 consists of terrestrial magnetism sensing module 31 and communication module 33. The terrestrial magnetism module detects the terrestrial magnetism of the remote controller and outputs terrestrial magnetism sensing signal  $S_G$ . Communication module 33 connects to terrestrial magnetism module 31 and transmits target motion signal  $S_{TAR}$  according to the terrestrial magnetism sensing signal. Target motion signal  $S_{TAR}$  is used to control remote-controlled device 4 to keep its detected terrestrial magnetism aligned with the target motion signal. *Id.* at col. 3, ll. 47–58.



C. Illustrative Claim

Claim 1, the sole independent claim, is illustrative and reproduced below.

1. A remote control system, comprising:

a remote controller, comprising:

a motion detecting module, which detects the remote controller's motion and outputs a motion detecting signal; and

a first communication module, which connects to the motion detecting module and receives the motion detecting signal, and transmits a target motion signal according to the motion detecting signal; and

a remote-controlled device, which is controlled by the remote controller, comprising:

a second communication module, which receives the target motion signal from the remote controller;

a terrestrial magnetism sensing module, which detects the remote-controlled device's terrestrial magnetism and outputs a terrestrial magnetism sensing signal;

a processing module, which has a first input connected to the terrestrial magnetism sensing module and receives the terrestrial magnetism sensing signal, and a second input connected to the second communication module and receives the target motion signal, and processes the terrestrial magnetism sensing signal and the target motion signal to output a driving control signal; and

a driving module, which connects to the processing module and receives the driving control signal, and adjusts the remote-controlled device's motion according to the driving control signal.



### IPR2014-00730 Patent 7,584,071 B2

### D. Prior Art

| Smith, III et al. ("Smith")<br>(Ex. 1002)             | US 5,043,646       | Aug. 27, 1991 |
|---|--------------------|---------------|
| Potiron et al. ("Potiron")<br>(Ex. 1004) <sup>1</sup> | FR 2 789 765 A1    | Aug. 18, 2000 |
| Barr (Ex. 1005)                                       | US 7,219,861 B1    | May 22, 2007  |
| Fouche (Ex. 1006)                                     | US 6,751,529 B1    | June 15, 2004 |
| Spirov et al. ("Spirov")<br>(Ex. 1007)                | US 2006/0144994 A1 | July 6, 2006  |
| Bathiche et al. ("Bathiche")<br>(Ex. 1008)            | US 7,145,551 B1    | Dec. 5, 2006  |
| Shkolnikov<br>(Ex. 1009)                              | US 2004/0263479 A1 | Dec. 30, 2004 |

## E. Asserted Grounds of Unpatentability

Petitioner asserts the following grounds of unpatentability against claims 1–15:

| Reference(s)   | Basis (35 U.S.C.) | Claim(s)      |
|----------------|-------------------|---------------|
| Smith          | § 102(b)          | 1–5 and 10–14 |
| Smith          | § 103(a)          | 2, 4, and 10  |
| Smith and Barr | § 103(a)          | 6 and 7       |

<sup>&</sup>lt;sup>1</sup> Exhibit 1004 is a certified translation of the French published patent application (Ex. 1003).



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