#### UNITED STATES PATENT AND TRADEMARK OFFICE

#### BEFORE THE PATENT TRIAL AND APPEAL BOARD

PARROT S.A., PARROT DRONES S.A.S., and PARROT INC., Petitioners

V.

QFO LABS, INC., Patent Owner

U.S. Patent No. 7,931,239

"Homeostatic Flying Hovercraft"

Inter Partes Review No. 2016-01550

PETITIONERS' OPPOSITION TO PATENT OWNER'S CONTINGENT MOTION TO AMEND



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## **Cases**

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## **LIST OF PETITIONERS' EXHIBITS**

No.	Description
Ex. 1001	U.S. Patent No. 7,931,239 to Pedersen et al.
Ex. 1002	File History of U.S. Patent No. 7,931,239
Ex. 1003	Declaration of Dr. Girish Chowdhary
Ex. 1004	U.S. Patent Application No. 2002/0104921 to Louvel
Ex. 1005	M. Gordon <i>et al.</i> , "Rotorcraft Aerial Robot – Challenges and Solutions," Georgia Institute of Technology, School of Aerospace Engineering (October 25-28, 1993)
Ex. 1006	U.S. Patent No. 5,128,671 to Thomas, Jr.
Ex. 1007	U.S. Patent Application No. 2002/0106966 to Jimenez et al.
Ex. 1008	U.S. Patent No. 6,847,865 to Carroll
Ex. 1009	U.S. Patent No. 6,588,701 to Yavnai
Ex. 1010	Declaration of Coral Sheldon-Hess
Ex. 1011	Printout of Website at http://www.aerialroboticscompetition.org/
Ex. 1012	Printout of Website at http://www.aerialroboticscompetition.org/pastmissions.php
Ex. 1013	Printout of Website at http://www.aviastar.org/helicopters_eng/bothezat.php
Ex. 1014	U.S. Provisional Patent Application No. 60/324,931
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	https://upload.wikimedia.org/wikipedia/commons/thumb/ 5/59/Quadrotorhover.svg/220px-Quadrotorhover.svg.png
Ex. 1019	Gavrilets, Vladislav, <i>Avionics systems development for small unmanned aircraft</i> , Diss. Massachusetts Institute of Technology, 1998.
Ex. 1020	Weilenmann, Martin F., Urs Christen, and Hans P. Geering, "Robust helicopter position control at hover," <i>American Control Conference</i> , 1994. Vol. 3. IEEE, 1994.
Ex. 1021	Shim, David Hyunchul, Hyoun Jin Kim, and Shankar Sastry, "Hierarchical control system synthesis for rotorcraft-based unmanned aerial vehicles," <i>AIAA Guidance, Navigation and Control Conference</i> . 2000.
Ex. 1022	Shim, H., et al., "A comprehensive study of control design for an autonomous helicopter," <i>In: Proc. 37th IEEE Conf. on Decision and Control (CDC'98)</i> , 1998.
Ex. 1023	Frazzoli, Emilio, Munther A. Dahleh, and Eric Feron, "Real-time motion planning for agile autonomous vehicles," Journal of Guidance, Control, and Dynamics 25.1 (2002): 116-129 (Ex. 1022).
Ex. 1024	U.S. Patent No. 3,053,480 to Vanderlip et al.
Ex. 1025	Declaration of Gregory C. Wyckoff in Support of Petitioners' Unopposed Motion for Pro Hac Vice Admission
Ex. 1026	Petition for Inter Partes Review in IPR2017-01400
Ex. 1027	Complaint and Jury Demand, filed on October 12, 2016 in Case No. 0:16-cv-03443-JRT-HB (D. Minn.)
Ex. 1028	U.S. Patent No. 5,590,062 to Nagamitsu et al.
Ex. 1029	I. Kroo <i>et al.</i> , "Mesoscale Flight and Miniature Rotorcraft Development," Stanford University, <i>published in</i> T.J. Mueller, "Fixed and Flapping Wing Aerodynamics for Micro Air Vehicle Applications, Progress in Astronautics and Aeronautics," pp. 503-



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