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This is a request for filing a patent application under 37 CFR § 1.53(b) in the name of inventors: Sir: Adam J. Cheyer and David L. Martin

SOFTWARE-BASED ARCHITECTURE FOR COMMUNICATION AND COOPERATION AMONG For: DISTRIBUTED ELECTRONIC AGENTS

Application Elements:

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4 , B 59 Pages of Specification, Claims and Abstract

16 Sheets of Drawings

01 Pages Combined Declaration and Power of Attorney

Accompanying Application Parts:

Assignment and Assignment Recordation Cover Sheet (recording fee not enclosed)

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Fee Calculation (37 CFR § 1.16)

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| BASIC FEE | | | \$395 \$ | OR | \$760 \$760.00 |
| TOTAL CLAIMS | <u>89</u> -20 = _ | 69 | x11 = \$ | OR | x18 = \$1242.00 |
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Software-Based Architecture for Communication and Cooperation Among Distributed Electronic Agents

By: Adam J. Cheyer and David L. Martin

BACKGROUND OF THE INVENTION

10 Field of the Invention

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The present invention is related to distributed computing environments and the completion of tasks within such environments. In particular, the present invention teaches a variety of software-based architectures for communication and cooperation among distributed electronic agents. Certain embodiments teach interagent

15 communication languages enabling client agents to make requests in the form of arbitrarily complex goal expressions that are solved through facilitation by a facilitator agent.

Context and Motivation for Distributed Software Systems

- 20 The evolution of models for the design and construction of distributed software systems is being driven forward by several closely interrelated trends: the adoption of a *networked computing model*, rapidly rising expectations for *smarter*, *longer-lived*, *more autonomous software applications* and an ever increasing demand for *more accessible and intuitive user interfaces*.
- 25 Prior Art Figure 1 illustrates a *networked computing model* 100 having a plurality of client and server computer systems 120 and 122 coupled together over a physical transport mechanism 140. The adoption of the *networked computing model* 100 has lead to a greatly increased reliance on distributed sites for both data and processing resources. Systems such as the networked computing model 100 are based
- upon at least one physical transport mechanism 140 coupling the multiple computer
 systems 120 and 122 to support the transfer of information between these computers.
 Some of these computers basically support using the network and are known as *client*

computers (*clients*). Some of these computers provide resources to other computers and are known as *server computers* (*servers*). The servers 122 can vary greatly in the resources they possess, access they provide and services made available to other computers across a network. Servers may service other servers as well as clients.

5 The Internet is a computing system based upon this network computing model. The Internet is continually growing, stimulating a paradigm shift for computing away from requiring all relevant data and programs to reside on the user's desktop machine. The data now routinely accessed from computers spread around the world has become increasingly rich in format, comprising multimedia documents, and audio and video

streams. With the popularization of programming languages such as JAVA, data transported between local and remote machines may also include programs that can be downloaded and executed on the local machine. There is an ever increasing reliance on networked computing, necessitating software design approaches that allow for flexible composition of distributed processing elements in a dynamically changing and relatively unstable environment.

In an increasing variety of domains, application designers and users are coming to expect the deployment of *smarter, longer-lived, more autonomous, software applications.* Push technology, persistent monitoring of information sources, and the maintenance of user models, allowing for personalized responses and sharing of preferences, are examples of the simplest manifestations of this trend. Commercial enterprises are introducing significantly more advanced approaches, in many cases employing recent research results from artificial intelligence, data mining, machine learning, and other fields.

- More than ever before, the increasing complexity of systems, the development of new technologies, and the availability of multimedia material and environments are creating a demand for *more accessible and intuitive user interfaces*. Autonomous, distributed, multi-component systems providing sophisticated services will no longer lend themselves to the familiar "direct manipulation" model of interaction, in which an individual user masters a fixed selection of commands provided by a single
- 30 application. Ubiquitous computing, in networked environments, has brought about a situation in which the typical user of many software services is likely to be a non-expert, who may access a given service infrequently or only a few times.

Accommodating such usage patterns calls for new approaches. Fortunately, input modalities now becoming widely available, such as speech recognition and pen-based handwriting/gesture recognition, and the ability to manage the presentation of systems' responses by using multiple media provide an opportunity to fashion a style

5 of human-computer interaction that draws much more heavily on our experience with human-human interactions.

PRIOR RELATED ART

Existing approaches and technologies for distributed computing include 10 distributed objects, mobile objects, blackboard-style architectures, and agent-based software engineering.

The Distributed Object Approach

Object-oriented languages, such as C++ or JAVA, provide significant advances over standard procedural languages with respect to the reusability and modularity of code: encapsulation, inheritance and polymorhpism. Encapsulation 15 encourages the creation of library interfaces that minimize dependencies on underlying algorithms or data structures. Changes to programming internals can be made at a later date with requiring modifications to the code that uses the library. Inheritance permits the extension and modification of a library of routines and data 20 without requiring source code to the original library. Polymorphism allows one body of code to work on an arbitrary number of data types. For the sake of simplicity traditional objects may be seen to contain both methods and data. Methods provide the mechanisms by which the internal state of an object may be modified or by which communication may occur with another object or by which the instantiation or 25 removal of objects may be directed.

With reference to Figure 2, a distributed object technology based around an Object Request Broker will now be described. Whereas "standard" object-oriented programming (OOP) languages can be used to build monolithic programs out of many object building blocks, distributed object technologies (DOOP) allow the creation of

30 programs whose components may be spread across multiple machines. As shown in Figure 2, an object system 200 includes client objects 210 and server objects 220. To implement a client-server relationship between objects, the distributed object system 200 uses a registry mechanism (CORBA's registry is called an Object Request Broker, or ORB) 230 to store the interface descriptions of available objects. Through the services of the ORB 230, a client can transparently invoke a method on a remote server object. The ORB 230 is then responsible for finding the object 220 that can

5 implement the request, passing it the parameters, invoking its method, and returning the results. In the most sophisticated systems, the client 210 does not have to be aware of where the object is located, its programming language, its operating system, or any other system aspects that are not part of the server object's interface.

Although distributed objects offer a powerful paradigm for creating networked
applications, certain aspects of the approach are not perfectly tailored to the
constantly changing environment of the Internet. A major restriction of the DOOP
approach is that the interactions among objects are fixed through explicitly coded
instructions by the application developer. It is often difficult to reuse an object in a
new application without bringing along all its inherent dependencies on other objects
(embedded interface definitions and explicit method calls). Another restriction of the
DOOP approach is the result of its reliance on a remote procedure call (RPC) style of
communication. Although easy to debug, this single thread of execution model does
not facilitate programming to exploit the potential for parallel computation that one
would expect in a distributed environment. In addition, RPC uses a blocking

20 (synchronous) scheme that does not scale well for high-volume transactions.

Mobile Objects

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Mobile objects, sometimes called mobile agents, are bits of code that can move to another execution site (presumably on a different machine) under their own programmatic control, where they can then interact with the local environment. For certain types of problems, the mobile object paradigm offers advantages over more traditional distributed object approaches. These advantages include network bandwidth and parallelism. Network bandwidth advantages exist for some database queries or electronic commerce applications, where it is more efficient to perform tests on data by bringing the tests to the data than by bringing large amounts of data to the testing program. Parallelism advantages include situations in which mobile agents

30 the testing program. Parallelism advantages include situations in which mobile agents can be spawned in parallel to accomplish many tasks at once.

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Some of the disadvantages and inconveniences of the mobile agent approach include the programmatic specificity of the agent interactions, lack of coordination support between participant agents and execution environment irregularities regarding specific programming languages supported by host processors upon which agents

- 5 reside. In a fashion similar to that of DOOP programming, an agent developer must programmatically specify where to go and how to interact with the target environment. There is generally little coordination support to encourage interactions among multiple (mobile) participants. Agents must be written in the programming language supported by the execution environment, whereas many other distributed
- 10 technologies support heterogeneous communities of components, written in diverse programming languages.

Blackboard Architectures

Blackboard architectures typically allow multiple processes to communicate by reading and writing tuples from a global data store. Each process can watch for items of interest, perform computations based on the state of the blackboard, and then add partial results or queries that other processes can consider. Blackboard architectures provide a flexible framework for problem solving by a dynamic community of distributed processes. A blackboard architecture provides one solution to eliminating the tightly bound interaction links that some of the other distributed

20 technologies require during interprocess communication. This advantage can also be a disadvantage: although a programmer does not need to refer to a specific process during computation, the framework does not provide programmatic control for doing so in cases where this would be practical.

Agent-based Software Engineering

25 Several research communities have approached distributed computing by casting it as a problem of modeling communication and cooperation among autonomous entities, or agents. Effective communication among independent agents requires four components: (1) a transport mechanism carrying messages in an asynchronous fashion, (2) an interaction protocol defining various types of

30 communication interchange and their social implications (for instance, a response is expected of a question), (3) a content language permitting the expression and interpretation of utterances, and (4) an agreed-upon set of shared vocabulary and

meaning for concepts (often called an *ontology*). Such mechanisms permit a much richer style of interaction among participants than can be expressed using a distributed object's RPC model or a blackboard architecture's centralized exchange approach.

Agent-based systems have shown much promise for flexible, fault-tolerant, distributed problem solving. Several agent-based projects have helped to evolve the notion of facilitation. However, existing agent-based technologies and architectures are typically very limited in the extent to which agents can specify complex goals or influence the strategies used by the facilitator. Further, such prior systems are not sufficiently attuned to the importance of integrating human agents (i.e., users) through natural language and other human-oriented user interface technologies.

The initial version of SRI International's Open Agent ArchitectureTM
("OAA[@]") technology provided only a very limited mechanism for dealing with compound goals. Fixed formats were available for specifying a flat list of either conjoined (AND) sub-goals or disjoined (OR) sub-goals; in both cases, parallel goal solving was hard-wired in, and only a single set of parameters for the entire list could be specified. More complex goal expressions involving (for example) combinations of different boolean connectors, nested expressions, or conditionally interdependent ("IF ... THEN") goals were not supported. Further, system scalability was not adequately addressed in this prior work.

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SUMMARY OF INVENTION

A first embodiment of the present invention discloses a highly flexible, software-based architecture for constructing distributed systems. The architecture supports cooperative task completion by flexible, dynamic configurations of autonomous electronic agents. Communication and cooperation between agents are brokered by one or more facilitators, which are responsible for matching requests, from users and agents, with descriptions of the capabilities of other agents. It is not generally required that a user or agent know the identities, locations, or number of other agents involved in satisfying a request, and relatively minimal effort is involved

in incorporating new agents and "wrapping" legacy applications. Extreme flexibility is achieved through an architecture organized around the declaration of capabilities by service-providing agents, the construction of arbitrarily complex goals by users and service-requesting agents, and the role of facilitators in delegating and coordinating the satisfaction of these goals, subject to advice and constraints that may accompany them. Additional mechanisms and features include facilities for creating and

5 maintaining shared repositories of data; the use of triggers to instantiate commitments within and between agents; agent-based provision of multi-modal user interfaces, including natural language; and built-in support for including the user as a privileged member of the agent community. Specific embodiments providing enhanced scalability are also described.

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BRIEF DESCRIPTION OF THE DRAWINGS

Prior Art

Prior Art FIGURE 1 depicts a networked computing model;

Prior Art FIGURE 2 depicts a distributed object technology based around an
 Object Resource Broker;

Examples of the Invention

FIGURE 3 depicts a distributed agent system based around a facilitator agent;

FIGURE 4 presents a structure typical of one small system of the present 20 invention;

FIGURE 5 depicts an Automated Office system implemented in accordance with an example embodiment of the present invention supporting a mobile user with a laptop computer and a telephone;

FIGURE 6 schematically depicts an Automated Office system implemented as a network of agents in accordance with a preferred embodiment of the present invention;

FIGURE 7 schematically shows data structures internal to a facilitator in accordance with a preferred embodiment of the present invention;

FIGURE 8 depicts operations involved in instantiating a client agent with its parent facilitator in accordance with a preferred embodiment of the present invention; FIGURE 9 depicts operations involved in a client agent initiating a service request and receiving the response to that service request in accordance with a certain preferred embodiment of the present invention;

FIGURE 10 depicts operations involved in a client agent responding to a
service request in accordance with another preferable embodiment of the present invention;

FIGURE 11 depicts operations involved in a facilitator agent response to a service request in accordance with a preferred embodiment of the present invention;

FIGURE 12 depicts an Open Agent ArchitectureTM based system of agents
implementing a unified messaging application in accordance with a preferred embodiment of the present invention;

FIGURE 13 depicts a map oriented graphical user interface display as might be displayed by a multi-modal map application in accordance with a preferred embodiment of the present invention;

FIGURE 14 depicts a peer to peer multiple facilitator based agent system supporting distributed agents in accordance with a preferred embodiment of the present invention;

FIGURE 15 depicts a multiple facilitator agent system supporting at least a limited form of a hierarchy of facilitators in accordance with a preferred embodiment of the present invention; and

FIGURE 16 depicts a replicated facilitator architecture in accordance with one embodiment of the present invention.

BRIEF DESCRIPTION OF THE APPENDICES

25 The Appendices provide source code for an embodiment of the present invention written in the PROLOG programming language.

APPENDIX A: Source code file named compound.pl.

APPENDIX B: Source code file named fac.pl.

APPENDIX C: Source code file named libcom_tcp.pl.

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APPENDIX D: Source code file named liboaa.pl.

APPENDIX E: Source code file named translations.pl.

DETAILED DESCRIPTION OF THE INVENTION

Figure 3 illustrates a distributed agent system 300 in accordance with one embodiment of the present invention. The agent system 300 includes a facilitator agent 310 and a plurality of agents 320. The illustration of Figure 3 provides a high level view of one simple system structure contemplated by the present invention. The facilitator agent 310 is in essence the "parent" facilitator for its "children" agents 320. The agents 320 forward service requests to the facilitator agent 310. The facilitator agent 310 interprets these requests, organizing a set of goals which are then delegated to appropriate agents for task completion.

The system 300 of Figure 3 can be expanded upon and modified in a variety of ways consistent with the present invention. For example, the agent system 300 can be distributed across a computer network such as that illustrated in Figure 1. The facilitator agent 310 may itself have its functionality distributed across several different computing platforms. The agents 320 may engage in interagent communication (also called peer to peer communications). Several different systems 300 may be coupled together for enhanced performance. These and a variety of other structural configurations are described below in greater detail.

Figure 4 presents the structure typical of a small system 400 in one
embodiment of the present invention, showing user interface agents 408, several
application agents 404 and meta-agents 406, the system 400 organized as a
community of peers by their common relationship to a facilitator agent 402. As will
be appreciated, Figure 4 places more structure upon the system 400 than shown in
Figure 3, but both are valid representations of structures of the present invention. The
facilitator 402 is a specialized server agent that is responsible for coordinating agent
communications and cooperative problem-solving. The facilitator 402 may also
provide a global data store for its client agents, allowing them to adopt a blackboard

30 style of interaction. Note that certain advantages are found in utilizing two or more facilitator agents within the system 400. For example, larger systems can be assembled from multiple facilitator/client groups, each having the sort of structure shown in Figure 4. All agents that are not facilitators are referred to herein generically as *client* agents -- so called because each acts (in some respects) as a client of some facilitator, which provides communication and other essential services for the client.

5 The variety of possible client agents is essentially unlimited. Some typical categories of client agents would include application agents 404, meta-agents 406, and user interface agents 408, as depicted in Figure 4. Application agents 404 denote specialists that provide a collection of services of a particular sort. These services could be domain-independent technologies (such as speech recognition, natural

- language processing 410, email, and some forms of data retrieval and data mining) or user-specific or domain-specific (such as a travel planning and reservations agent). Application agents may be based on legacy applications or libraries, in which case the agent may be little more than a wrapper that calls a pre-existing API 412, for example. Meta-agents 406 are agents whose role is to assist the facilitator agent 402
 in coordinating the activities of other agents. While the facilitator 402 possesses domain-independent coordination strategies, meta-agents 406 can augment these by
 - using domain- and application-specific knowledge or reasoning (including but not limited to rules, learning algorithms and planning).
- With further reference to Figure 4, user interface agents 408 can play an
 extremely important and interesting role in certain embodiments of the present invention. By way of explanation, in some systems, a user interface agent can be implemented as a collection of "micro-agents", each monitoring a different input modality (point-and-click, handwriting, pen gestures, speech), and collaborating to produce the best interpretation of the current inputs. These micro-agents are depicted in Figure 4, for example, as Modality Agents 414. While describing such subcategories of client agents is useful for purposes of illustration and understanding, they need not be formally distinguished within the system in preferred implementations of the present invention.

The operation of one preferred embodiment of the present invention will be discussed in greater detail below, but may be briefly outlined as follows. When invoked, a client agent makes a connection to a facilitator, which is known as its *parent facilitator*. These connections are depicted as a double headed arrow between the client agent and the facilitator agent in Figure 3 and 4, for example. Upon connection, an agent registers with its parent facilitator a specification of the capabilities and services it can provide. For example, a natural language agent may register the characteristics of its available natural language vocabulary. (For more

- 5 details regarding client agent connections, see the discussion of Figure 8 below.) Later during task completion, when a facilitator determines that the registered services 416 of one of its client agents will help satisfy a goal, the facilitator sends that client a request expressed in the Interagent Communication Language (*ICL*) 418. (See Figure 11 below for a more detailed discussion of the facilitator operations involved.) The
- 10 agent parses this request, processes it, and returns answers or status reports to the facilitator. In processing a request, the client agent can make use of a variety of infrastructure capabilities provided in the preferred embodiment. For example, the client agent can use *ICL* 418 to request services of other agents, set triggers, and read or write shared data on the facilitator or other client agents that maintain shared data.
- 15 (See the discussion of Figures 9-11 below for a more detailed discussion of request processing.)

The functionality of each client agent are made available to the agent community through registration of the client agent's capabilities with a facilitator 402. A software "wrapper" essentially surrounds the underlying application program performing the services offered by each client. The common infrastructure for constructing agents is preferably supplied by an *agent library*. The agent library is preferably accessible in the runtime environment of several different programming languages. The agent library preferably minimizes the effort required to construct a new system and maximizes the ease with which legacy systems can be "wrapped" and made compatible with the agent-based architecture of the present invention.

By way of further illustration, a representative application is now briefly presented with reference to Figures 5 and 6. In the Automated Office system depicted in Figure 5, a mobile user with a telephone and a laptop computer can access and task commercial applications such as calendars, databases, and email systems running

30 back at the office. A user interface (UI) agent 408, shown in Figure 6, runs on the user's local laptop and is responsible for accepting user input, sending requests to the facilitator 402 for delegation to appropriate agents, and displaying the results of the distributed computation. The user may interact directly with a specific remote application by clicking on active areas in the interface, calling up a form or window for that application, and making queries with standard interface dialog mechanisms. Conversely, a user may express a task to be executed by using typed, handwritten, or

5 spoken (over the telephone) English sentences, without explicitly specifying which agent or agents should perform the task.

For instance, if the question "What is my schedule?" is written 420 in the user interface 408, this request will be sent 422 by the UI 408 to the facilitator 402, which in turn will ask 424 a natural language (NL) agent 426 to translate the query into *ICL*10 18. To accomplish this task, the NL agent 426 may itself need to make requests of the agent community to resolve unknown words such as "me" 428 (the UI agent 408 can respond 430 with the name of the current user) or "schedule" 432 (the calendar agent 434 defines this word 436). The resulting *ICL* expression is then routed by the facilitator 402 to appropriate agents (in this case, the calendar agent 434) to execute the request. Results are sent back 438 to the UI agent 408 for display.

The spoken request "When mail arrives for me about security, notify me immediately." produces a slightly more complex example involving communication among all agents in the system. After translation into *ICL* as described above, the facilitator installs a trigger 440 on the mail agent 442 to look for new messages about security. When one such message does arrive in its mail spool, the trigger fires, and the facilitator matches the action part of the trigger to capabilities published by the notification agent 446. The notification agent 446 is a meta-agent, as it makes use of rules concerning the optimal use of different output modalities (email, fax, speech generation over the telephone) plus information about an individual user's preferences 448 to determine the best way of relaying a message through available media transfer application agent 434 and database agent 450 may have different guesses as to where to find the user) and some cooperative parallelism to produce required information

30 speech representation of the email message), a telephone agent 452 calls the user, verifying its identity through touchtones, and then play the message.

(telephone number of location, user password, and an audio file containing a text-to-

The above example illustrates a number of inventive features. As new agents connect to the facilitator, registering capability specifications and natural language vocabulary, what the user can say and do dynamically changes; in other words, the ICL is dynamically *expandable*. For example, adding a calendar agent to the system

- 5 in the previous example and registering its capabilities enables users to ask natural language questions about their "schedule" without any need to revise code for the facilitator, the natural language agents, or any other client agents. In addition, the interpretation and execution of a task is a distributed process, with no single agent defining the set of possible inputs to the system. Further, a single request can produce
- 10 cooperation and flexible communication among many agents, written in different programming languages and spread across multiple machines.

Design Philosophy and Considerations

One preferred embodiment provides an integration mechanism for heterogeneous applications in a distributed infrastructure, incorporating some of the dynamism and extensibility of blackboard approaches, the efficiency associated with mobile objects, plus the rich and complex interactions of communicating agents. Design goals for preferred embodiments of the present invention may be categorized under the general headings of *interoperation and cooperation, user interfaces*, and *software engineering*. These design goals are not absolute requirements, nor will they necessarily be satisfied by all embodiments of the present invention, but rather simply reflect the inventor's currently preferred design philosophy.

Versatile mechanisms of interoperation and cooperation

Interoperation refers to the ability of distributed software components - agents - to communicate meaningfully. While every system-building framework must provide mechanisms of interoperation at some level of granularity, agent-based frameworks face important new challenges in this area. This is true primarily because autonomy, the hallmark of *individual* agents, necessitates greater flexibility in interactions within *communities* of agents. *Coordination* refers to the mechanisms by

30 which a community of agents is able to work together productively on some task. In these areas, the goals for our framework are to *provide flexibility in assembling*

communities of autonomous service providers, provide flexibility in structuring cooperative interactions, impose the right amount of structure, as well as include legacy and "owned-elsewhere" applications.

Provide flexibility in assembling communities of autonomous service providers
-- both at development time and at runtime. Agents that conform to the linguistic and ontological requirements for effective communication should be able to participate in an agent community, in various combinations, with minimal or near minimal prerequisite knowledge of the characteristics of the other players. Agents with duplicate and overlapping capabilities should be able to coexist within the same community, with the system making optimal or near optimal use of the redundancy.

Provide flexibility in structuring cooperative interactions among the members of a community of agents. A framework preferably provides an economical mechanism for setting up a variety of interaction patterns among agents, without requiring an inordinate amount of complexity or infrastructure within the individual agents. The provision of a service should be independent or minimally dependent upon a particular configuration of agents.

Impose the right amount of structure on individual agents. Different
approaches to the construction of multi-agent systems impose different requirements
on the individual agents. For example, because KQML is neutral as to the content of
messages, it imposes minimal structural requirements on individual agents. On the
other hand, the BDI paradigm tends to impose much more demanding requirements,
by making assumptions about the nature of the programming elements that are
meaningful to individual agents. Preferred embodiments of the present invention
should fall somewhere between the two, providing a rich set of interoperation and
coordination capabilities, without precluding any of the software engineering goals
defined below.

Include legacy and "owned-elsewhere" applications. Whereas legacy usually implies reuse of an established system fully controlled by the agent-based system developer, owned-elsewhere refers to applications to which the developer has partial

30 access, but no control. Examples of owned-elsewhere applications include data sources and services available on the World Wide Web, via simple form-based

interfaces, and applications used cooperatively within a virtual enterprise, which remain the properties of separate corporate entities. Both classes of application must preferably be able to interoperate, more or less as full-fledged members of the agent community, without requiring an overwhelming integration effort.

5 Human-oriented user interfaces

Systems composed of multiple distributed components, and possibly dynamic configurations of components, require the crafting of intuitive user interfaces to provide conceptually natural interaction mechanisms, treat users as privileged members of the agent community and support collaboration.

10 Provide conceptually natural interaction mechanisms with multiple distributed components. When there are numerous disparate agents, and/or complex tasks implemented by the system, the user should be able to express requests without having detailed knowledge of the individual agents. With speech recognition, handwriting recognition, and natural language technologies becoming more mature, 15 agent architectures should preferably support these forms of input playing increased roles in the tasking of agent communities.

Preferably treat *users as privileged members* of the agent community by providing an appropriate level of task specification within *software* agents, and reusable translation mechanisms between this level and the level of *human* requests, supporting constructs that seamlessly incorporate interactions between both humaninterface and software types of agents.

Preferably support *collaboration* (simultaneous work over shared data and processing resources) between users and agents.

Realistic software engineering requirements

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System-building frameworks should preferably address the practical concerns of real-world applications by the specification of requirements which preferably include: *Minimize the effort* required to create new agents, and to wrap existing applications. *Encourage reuse*, both of domain-independent and domain-specific components. The concept of *agent orientation*, like that of object orientation, provides

30 a natural conceptual framework for reuse, so long as mechanisms for encapsulation

and interaction are structured appropriately. *Support lightweight, mobile platforms.* Such platforms should be able to serve as hosts for agents, without requiring the installation of a massive environment. It should also be possible to construct individual agents that are relatively small and modest in their processing

5 requirements. *Minimize platform and language barriers*. Creation of new agents, as well as wrapping of existing applications, should not require the adoption of a new language or environment.

Mechanisms of Cooperation

Cooperation among agents in accordance with the present invention is preferably achieved via messages expressed in a common language, *ICL*. Cooperation among agent is further preferably structured around a three-part approach: providers of services register capabilities specifications with a facilitator, requesters of services construct goals and relay them to a facilitator, and facilitators coordinate the efforts of the appropriate service providers in satisfying these goals.

15 The Interagent Communication Language (ICL)

Interagent Communication Language ("ICL") 418 refers to an interface, communication, and task coordination language preferably shared by all agents, regardless of what platform they run on or what computer language they are programmed in. ICL may be used by an agent to task itself or some subset of the agent community. Preferably, ICL allows agents to specify explicit control parameters while simultaneously supporting expression of goals in an underspecified, loosely constrained manner. In a further preferred embodiment, agents employ ICL to perform queries, execute actions, exchange information, set triggers, and manipulate data in the agent community.

In a further preferred embodiment, a program element expressed in *ICL* is the *event*. The activities of every agent, as well as communications between agents, are preferably structured around the transmission and handling of events. In communications, events preferably serve as messages between agents; in regulating the activities of individual agents, they may preferably be thought of as goals to be

30 satisfied. Each event preferably has a type, a set of parameters, and content. For example, the agent library procedure *oaa_Solve* can be used by an agent to request services of other agents. A call to *oaa_Solve*, within the code of agent A, results in an event having the form

ev_post_solve(Goal, Params)

going from A to the facilitator, where *ev_post_solve* is the type, *Goal* is the content, and *Params* is a list of parameters. The allowable content and parameters preferably vary according to the type of the event.

The *ICL* preferably includes a layer of conversational protocol and a content layer. The conversational layer of *ICL* is defined by the event types, together with the parameter lists associated with certain of these event types. The content layer consists of the specific goals, triggers, and data elements that may be embedded within various events.

The *ICL* conversational protocol is preferably specified using an orthogonal, parameterized approach, where the conversational aspects of each element of an interagent conversation are represented by a selection of an event type and a selection
of values from at least one orthogonal set of parameters. This approach offers greater expressiveness than an approach based solely on a fixed selection of *speech acts*, such as embodied in KQML. For example, in KQML, a request to satisfy a query can employ either of the performatives *ask_all* or *ask_one*. In *ICL*, on the other hand, this type of request preferably is expressed by the event type *ev_post_solve*, together with
the *solution_limit(N)* parameter - where N can be any positive integer. (A request for all solutions is indicated by the omission of the *solution_limit* parameter.) The request can also be accompanied by other parameters, which combine to further refine its semantics. In KQML, then, this example forces one to choose between two possible conversational options, neither of which may be precisely what is desired. In either

- case, the performative chosen is a single value that must capture the entire conversational characterization of the communication. This requirement raises a difficult challenge for the language designer, to select a set of performatives that provides the desired functionality without becoming unmanageably large.
 Consequently, the debate over the right set of performatives has consumed much
- 30 discussion within the KQML community.

The content layer of the *ICL* preferably supports unification and other features found in logic programming language environments such as PROLOG. In some

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embodiments, the content layer of the *ICL* is simply an extension of at least one programming language. For example, the Applicants have found that PROLOG is suitable for implementing and extending into the content layer of the *ICL*. The agent libraries preferably provide support for constructing, parsing, and manipulating *ICL*

5 expressions. It is possible to embed content expressed in other languages within an *ICL* event. However, expressing content in *ICL* simplifies the facilitator's access to the content, as well as the conversational layer, in delegating requests. This gives the facilitator more information about the nature of a request and helps the facilitator decompose compound requests and delegate the sub-requests.

Further, *ICL* expressions preferably include, in addition to events, at least one of the following: capabilities declarations, requests for services, responses to requests, trigger specifications, and shared data elements. A further preferred embodiment of the present invention incorporates *ICL* expressions including at least all of the following: events, capabilities declarations, requests for services, responses to requests, trigger specifications, and shared data elements.

Providing Services: Specifying "Solvables"

In a preferred embodiment of the present invention, every participating agent defines and publishes a set of capability declarations, expressed in *ICL*, describing the services that it provides. These declarations establish a high-level interface to the agent. This interface is used by a facilitator in communicating with the agent, and, most important, in delegating service requests (or parts of requests) to the agent. Partly due to the use of PROLOG as a preferred basis for *ICL*, these capability declarations are referred as *solvables*. The agent library preferably provides a set of procedures allowing an agent to add, remove, and modify its solvables, which it may preferably do at any time after connecting to its facilitator.

There are preferably at least two major types of solvables: *procedure* solvables and *data* solvables. Intuitively, a procedure solvable performs a test or action, whereas a data solvable provides access to a collection of data. For example, in creating an agent for a mail system, procedure solvables might be defined for sending

30 a message to a person, testing whether a message about a particular subject has arrived in the mail queue, or displaying a particular message onscreen. For a database wrapper agent, one might define a distinct data solvable corresponding to each of the relations present in the database. Often, a data solvable is used to provide a *shared* data store, which may be not only queried, but also updated, by various agents having the required permissions.

5 There are several primary technical differences between these two types of solvables. First, each procedure solvable must have a handler declared and defined for it, whereas this is preferably not necessary for a data solvable. The handling of requests for a data solvable is preferably provided transparently by the agent library. Second, data solvables are preferably associated with a dynamic collection of facts (or clauses), which may be further preferably modified at runtime, both by the agent providing the solvable, and by other agents (provided they have the required permissions). Third, special features, available for use with data solvables, preferably facilitate maintaining the associated facts. In spite of these differences, it should be noted that the mechanism of *use* by which an agent requests a service is the same for the two types of solvables.

In one embodiment, a request for one of an agent's services normally arrives in the form of an event from the agent's facilitator. The appropriate handler then deals with this event. The handler may be coded in whatever fashion is most appropriate, depending on the nature of the task, and the availability of task-specific libraries or legacy code, if any. The only hard requirement is that the handler return an appropriate response to the request, expressed in *ICL*. Depending on the nature of the request, this response could be an indication of success or failure, or a list of solutions (when the request is a data query).

A solvable preferably has three parts: a *goal*, a list of *parameters*, and a list of *permissions*, which are declared using the format:

solvable(Goal, Parameters, Permissions)

The goal of a solvable, which syntactically takes the preferable form of an *ICL* structure, is a logical representation of the service provided by the solvable. (An *ICL* structure consists of a *functor* with 0 or more arguments. For example, in the structure

30 a(b,c), `a' is the functor, and `b' and `c' the arguments.) As with a PROLOG structure, the goal's arguments themselves may preferably be structures. Various options can be included in the parameter list, to refine the semantics associated with the solvable. The *type* parameter is preferably used to say whether the solvable is *data* or *procedure*. When the type is *procedure*, another parameter may be used to indicate the handler to be associated with the solvable. Some of the

5 parameters appropriate for a *data* solvable are mentioned elsewhere in this application. In either case (procedure or data solvable), the *private* parameter may be preferably used to restrict the use of a solvable to the declaring agent when the agent intends the solvable to be solely for its internal use but wishes to take advantage of the mechanisms in accordance with the present invention to access it, or when the agent

10 wants the solvable to be available to outside agents only at selected times. In support of the latter case, it is preferable for the agent to change the status of a solvable from private to non-private at any time.

The permissions of a solvable provide mechanisms by which an agent may preferably control access to its services allowing the agent to restrict calling and writing of a solvable to itself and/or other selected agents. (*Calling* means requesting the service encapsulated by a solvable, whereas *writing* means modifying the collection of facts associated with a data solvable.) The default permission for every solvable in a further preferred embodiment of the present invention is to be callable by anyone, and for data solvables to be writable by anyone. A solvable's permissions can preferably be changed at any time, by the agent providing the solvable.

For example, the solvables of a simple email agent might include:

```
solvable(send_message(email, +ToPerson, +Params),
      [type(procedure), callback(send_mail)],
      [])
25 solvable(last_message(email, -MessageId),
      [type(data), single_value(true)],
      [write(true)]),
      solvable(get_message(email, +MessageId, -
      Msg),
30 [type(procedure), callback(get_mail)],
      [])
```

The symbols `+' and `-', indicating input and output arguments, are at present used only for purposes of documentation. Most parameters and permissions have default values, and specifications of default values may be omitted from the

³⁵ parameters and permissions lists.

Defining an agent's capabilities in terms of solvable declarations effectively creates a vocabulary with which other agents can communicate with the new agent. Ensuring that agents will speak the same language and share a common, unambiguous semantics of the vocabulary involves *ontology*. Agent development tools and services

- 5 (automatic translations of solvables by the facilitator) help address this issue; additionally, a preferred embodiment of the present invention will typically rely on vocabulary from either formally engineered ontologies for specific domains or from ontologies constructed during the incremental development of a body of agents for several applications or from both specific domain ontologies and incrementally
- 10 developed ontologies. Several example tools and services are described in Cheyer et al.'s paper entitled "Development Tools for the Open Agent Architecture," as presented at the Practical Application of Intelligent Agents and Multi-Agent Technology (PAAM 96), London, April 1996.

Although the present invention imposes no hard restrictions on the form of solvable declarations, two common usage conventions illustrate some of the utility associated with solvables.

Classes of services are often preferably tagged by a particular type. For instance, in the example above, the "last_message" and "get_message" solvables are specialized for email, not by modifying the *names* of the services, but rather by the use of the `email' parameter, which serves during the execution of an *ICL* request to select (or not) a specific type of message.

Actions are generally written using an imperative verb as the functor of the solvable in a preferred embodiment of the present invention, the direct object (or item class) as the first argument of the predicate, required arguments following, and then an extensible parameter list as the last argument. The parameter list can hold optional information usable by the function. The *ICL* expression generated by a natural language parser often makes use of this parameter list to store prepositional phrases and adjectives.

As an illustration of the above two points, "Send mail to Bob about lunch" will be translated into an *ICL* request send_message(email, `Bob Jones', [subject(lunch)]), whereas "Remind Bob about lunch" would leave the transport unspecified

Attornev Docket No: SRI1P016(3477)/BRC/EWJ Page 23 of 778

(send_message(KIND, `Bob Jones', [subject(lunch)])), enabling all available message transfer agents (e.g., fax, phone, mail, pager) to compete for the opportunity to carry out the request.

Requesting Services

5 An agent preferably requests services of the community of agent by delegating tasks or goals to its facilitator. Each request preferably contains calls to one or more agent solvables, and optionally specifies parameters containing advice to help the facilitator determine how to execute the task. Calling a solvable preferably does *not* require that the agent specify (or even know of) a particular agent or agents to handle

- 10 the call. While it is possible to specify one or more agents using an address parameter (and there are situations in which this is desirable), in general it is advantageous to leave this delegation to the facilitator. This greatly reduces the hard-coded component dependencies often found in other distributed frameworks. The agent libraries of a preferred embodiment of the present invention provide an agent with a
- 15 single, unified point of entry for requesting services of other agents: the library procedure *oaa_Solve*. In the style of logic programming, *oaa_Solve* may preferably be used both to retrieve data and to initiate actions, so that calling a *data* solvable looks the same as calling a *procedure* solvable.

Complex Goal Expressions

- 20 A powerful feature provided by preferred embodiments of the present invention is the ability of a client agent (or a user) to submit compound goals of an arbitrarily complex nature to a facilitator. A compound goal is a single goal expression that specifies multiple sub-goals to be performed. In speaking of a "complex goal expression" we mean that a single goal expression that expresses
- 25 multiple sub-goals can potentially include more than one type of logical connector (e.g., AND, OR, NOT), and/or more than one level of logical nesting (e.g., use of parentheses), or the substantive equivalent. By way of further clarification, we note that when speaking of an *"arbitrarily complex goal expression"* we mean that goals are expressed in a language or syntax that allows expression of such complex goals
- 30 when appropriate or when desired, not that every goal is itself necessarily complex.

It is contemplated that this ability is provided through an interagent communication language having the necessary syntax and semantics. In one example, the goals may take the form of compound goal expressions composed using operators similar to those employed by PROLOG, that is, the comma for conjunction, the

semicolon for disjunction, the arrow for conditional execution, etc. The present invention also contemplates significant extensions to PROLOG syntax and semantics. For example, one embodiment incorporates a "parallel disjunction" operator indicating that the disjuncts are to be executed by different agents concurrently. A further embodiment supports the specification of whether a given sub-goal is to be executed breadth-first or depth-first.

A further embodiment supports each sub-goal of a compound goal optionally having an address and/or a set of parameters attached to it. Thus, each sub-goal takes the form

Address:Goal::Parameters

15 where both Address and Parameters are optional.

An address, if present, preferably specifies one or more agents to handle the given goal, and may employ several different types of referring expression: unique names, symbolic names, and shorthand names. Every agent has preferably a unique name, assigned by its facilitator, which relies upon network addressing schemes to ensure its global uniqueness. Preferably, agents also have self-selected symbolic names (for example, "mail"), which are not guaranteed to be unique. When an address includes a symbolic name, the facilitator preferably takes this to mean that all agents having that name should be called upon. Shorthand names include `self' and `parent' (which refers to the agent's facilitator). The address associated with a goal or sub-goal is preferably always optional. When an address is not present, it is the facilitator's job to supply an appropriate address.

The distributed execution of compound goals becomes particularly powerful when used in conjunction with natural language or speech-enabled interfaces, as the query itself may specify how functionality from distinct agents will be combined. As a simple example, the spoken utterance "Fax it to Bill Smith's manager." can be

translated into the following compound ICL request:

oaa_Solve((manager('Bill Smith', M), fax(it,M,[])), [strategy(action)])

Note that in this ICL request there are two sub-goals, "manager('Bill Smith',M)" and "fax(it,M,[])," and a single global parameter "strategy(action)." According to the present invention, the facilitator is capable of mapping global parameters in order to apply the constraints or advice across the separate sub-goals in

- a meaningful way. In this instance, the global parameter strategy(action) implies a
 parallel constraint upon the first sub-goal; i.e., when there are multiple agents that
 can respond to the manager sub-goal, each agent should receive a request for service.
 In contrast, for the second sub-goal, parallelism should not be inferred from the global
 parameter strategy(action) because such an inference would possibly result in the
 transmission of duplicate facsimiles.

Refining Service Requests

In a preferred embodiment of the present invention, parameters associated with a goal (or sub-goal) can draw on useful features to refine the request's meaning. For example, it is frequently preferred to be able to specify whether or not solutions are to be returned synchronously; this is done using the *reply* parameter, which can take any of the values *synchronous, asynchronous*, or *none*. As another example, when the goal is a non-compound query of a data solvable, the *cache* parameter may preferably be used to request local caching of the facts associated with that solvable. Many of the remaining parameters fall into two categories: feedback and advice.

Feedback parameters allow a service requester to receive information from the facilitator about how a goal was handled. This feedback can include such things as the identities of the agents involved in satisfying the goal, and the amount of time expended in the satisfaction of the goal.

- Advice parameters preferably give constraints or guidance to the facilitator in completing and interpreting the goal. For example, a *solution_limit* parameter preferably allows the requester to say how many solutions it is interested in; the facilitator and/or service providers are free to use this information in optimizing their efforts. Similarly, a *time_limit* is preferably used to say how long the requester is willing to wait for solutions to its request, and, in a multiple facilitator system, a
- 30 *level_limit* may preferably be used to say how remote the facilitators may be that are consulted in the search for solutions. A *priority* parameter is preferably used to

indicate that a request is more urgent than previous requests that have not yet been satisfied. Other preferred advice parameters include but are not limited to parameters used to tell the facilitator whether parallel satisfaction of the parts of a goal is appropriate, how to combine and filter results arriving from multiple solver agents,

and whether the requester itself may be considered a candidate solver of the sub-goals

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of a request.

Advice parameters preferably provide an extensible set of low-level, orthogonal parameters capable of combining with the *ICL* goal language to fully

10 embodiments of the present invention, multiple parameters can be grouped together and given a group name. The resulting *high-level advice parameters* can preferably be used to express concepts analogous to KQML's performatives, as well as define classifications of problem types. For instance, KQML's "ask_all" and "ask_one" performatives would be represented as combinations of values given to the parameters

express how information should flow among participants. In certain preferred

reply, parallel_ok, and *solution_limit*. As an example of a higher-level problem type, the strategy "math_problem" might preferably send the query to all appropriate math solvers in parallel, collect their responses, and signal a conflict if different answers are returned. The strategy "essay_question" might preferably send the request to all appropriate participants, and signal a problem (i.e., cheating) if any of the returned answers are identical.

Facilitation

In a preferred embodiment of the present invention, when a facilitator receives a compound goal, its job is to construct a goal satisfaction plan and oversee its satisfaction in an optimal or near optimal manner that is consistent with the specified advice. The facilitator of the present invention maintains a knowledge base that records the capabilities of a collection of agents, and uses that knowledge to assist requesters and providers of services in making contact.

Figure 7 schematically shows data structures 700 internal to a facilitator in accordance with one embodiment of the present invention. Consider the function of a

30 Agent Registry 702 in the present invention. Each registered agent may be seen as associated with a collection of fields found within its parent facilitator such as shown in the figure. Each registered agent may optionally possess a Symbolic Name which would be entered into field 704. As mentioned elsewhere, Symbolic Names need not be unique to each instance of an agent. Note that an agent may in certain preferred embodiments of the present invention possess more than one Symbolic Name. Such Symbolic Names would each be found through their associations in the Agent

5 Registry entries. Each agent, when registered, must possess a Unique Address, which is entered into the Unique Address field 706.

With further reference to Figure 7, each registered agent may be optionally associated with one or more capabilities, which have associated Capability Declaration fields 708 in the parent facilitator Agent Registry 702. These capabilities

- may define not just functionality, but may further provide a utility parameter indicating, in some manner (e.g., speed, accuracy, etc), how effective the agent is at providing the declared capability. Each registered agent may be optionally associated with one or more data components, which have associated Data Declaration fields 710 in the parent facilitator Agent Registry 702. Each registered agent may be optionally associated through their associated Trigger Declaration fields 712 in the parent facilitator Agent Registry 702. Each registered agent may be optionally associated Tild with one or more tasks, which preferably could be referenced through their associated Task Declaration fields 714 in the parent facilitator Agent Registry 702. Each registered agent may be optionally associated with one or more tasks, which preferably could be referenced through their associated Task Declaration fields 714 in the parent facilitator Agent Registry 702. Each registered agent may be optionally associated with one or more tasks, which preferably could be referenced through their associated Task Declaration fields 714 in the parent facilitator Agent Registry 702. Each registered agent may be
 optionally associated with one or more Process Characteristics, which preferably
- could be referenced through their associated Process Characteristics Declaration fields
 716 in the parent facilitator Agent Registry 702. Note that these characteristics in certain preferred embodiments of the present invention may include one or more of the following: Machine Type (specifying what type of computer may run the agent),
 Language (both computer and human interface).

A facilitator agent in certain preferred embodiments of the present invention further includes a Global Persistent Database 720. The database 720 is composed of data elements which do not rely upon the invocation or instantiation of client agents for those data elements to persist. Examples of data elements which might be present in such a database include but are not limited to the network address of the facilitator agent's server, facilitator agent's server accessible network port list, firewalls, user

lists, and security options regarding the access of server resources accessible to the facilitator agent.

A simplified walk through of operations involved in creating a client agent, a client agent initiating a service request, a client agent responding to a service request and a facilitator agent responding to a service request are including hereafter by way of illustrating the use of such a system. These figures and their accompanying discussion are provided by way of illustration of one preferred embodiment of the present invention and are not intended to limit the scope of the present invention.

Figure 8 depicts operations involved in instantiating a client agent with its parent facilitator in accordance with a preferred embodiment of the present invention. The operations begin with starting the Agent Registration in a step 800. In a next step 802, the Installer, such as a client or facilitator agent, invokes a new client agent. It will be appreciated that any computer entity is capable of invoking a new agent. The system then instantiates the new client agent in a step 804. This operation may

- 15 involve resource allocations somewhere in the network on a local computer system for the client agent, which will often include memory as well as placement of references to the newly instantiated client agent in internal system lists of agents within that local computing system. Once instantiated, the new client and its parent facilitator establish a communications link in a step 806. In certain preferred
- 20 embodiments, this communications link involves selection of one or more physical transport mechanisms for this communication. Once established, the client agent transmits it profile to the parent facilitator in a step 808. When received, the parent facilitator registers the client agent in a step 810. Then, at a step 812, a client agent has been instantiated in accordance with one preferred embodiment of the present invention.

Figure 9 depicts operations involved in a client agent initiating a service request and receiving the response to that service request in accordance with a preferred embodiment of the present invention. The method of Figure 9 begins in a step 900, wherein any initialization or other such procedures may be performed.

30 Then, in a step 902, the client agent determines a goal to be achieved (or solved). This goal is then translated in a step 904 into *ICL*, if it is not already formulated in it. The goal, now stated in *ICL*, is then transmitted to the client agent's parent facilitator in a step 906. The parent facilitator responds to this service request and at a later time, the client agent receives the results of the request in a step 908, operations of Figure 9 being complete in a done step 910.

FIGURE 10 depicts operations involved in a client agent responding to a
service request in accordance with a preferred embodiment of the present invention.
Once started in a step 1000, the client agent receives the service request in a step
1002. In a next step 1004, the client agent parses the received request from ICL. The
client agent then determines if the service is available in a step 1006. If it is not, the
client agent returns a status report to that effect in a step 1008. If the service is

available, control is passed to a step 1010 where the client performs the requested service. Note that in completing step 1010 the client may form complex goal expressions, requesting results for these solvables from the facilitator agent. For example, a fax agent might fax a document to a certain person only after requesting and receiving a fax number for that person. Subsequently, the client agent either
 returns the results of the service and/or a status report in a step 1012. The operations of Figure 10 are complete in a done step 1014.

FIGURE 11 depicts operations involved in a facilitator agent response to a service request in accordance with a preferred embodiment of the present invention. The start of such operations in step 1100 leads to the reception of a goal request in a
step 1102 by the facilitator. This request is then parsed and interpreted by the facilitator in a step 1104. The facilitator then proceeds to construct a goal satisfaction plan in a next step 1106. In steps 1108 and 1110, respectively, the facilitator determines the required sub-goals and then selects agents suitable for performing the required sub-goals. The facilitator then transmits the sub-goal requests to the selected

- 25 agents in a step 1112 and receives the results of these transmitted requests in a step 1114. It should be noted that the actual implementation of steps 1112 and 1114 are dependent upon the specific goal satisfaction plan. For instance, certain sub-goals may be sent to separate agents in parallel, while transmission of other sub-goals may be postponed until receipt of particular answers. Further, certain requests may
- 30 generate multiple responses that generate additional sub-goals. Once the responses have been received, the facilitator determines whether the original requested goal has been completed in a step 1118. If the original requested goal has not been completed,

the facilitator recursively repeats the operations 1106 through 1116. Once the original requested goal is completed, the facilitator returns the results to the requesting agent 1118 and the operations are done at 1120.

- A further preferred embodiment of the present invention incorporates *transparent delegation*, which means that a requesting agent can generate a request, and a facilitator can manage the satisfaction of that request, without the requester needing to have any knowledge of the identities or locations of the satisfying agents. In some cases, such as when the request is a data query, the requesting agent may also be oblivious to the *number* of agents involved in satisfying a request. Transparent
- 10 delegation is possible because agents' capabilities (solvables) are treated as an abstract description of a service, rather than as an entry point into a library or body of code.

A further preferred embodiment of the present invention incorporates facilitator handling of compound goals, preferably involving three types of processing: delegation, optimization and interpretation.

15 Delegation processing preferably supports facilitator determination of which specific agents will execute a compound goal and how such a compound goal's subgoals will be combined and the sub-goal results routed. Delegation involves selective application of global and local constraint and advice parameters onto the specific subgoals. Delegation results in a goal that is unambiguous as to its meaning and as to the agents that will participate in satisfying it.

Optimization processing of the completed goal preferably includes the facilitator using sub-goal parallelization where appropriate. *Optimization* results in a goal whose interpretation will require as few exchanges as possible, between the facilitator and the satisfying agents, and can exploit parallel efforts of the satisfying agents, wherever this does not affect the goal's meaning.

Interpretation processing of the optimized goal. Completing the addressing of a goal involves the selection of one or more agents to handle each of its sub-goals (that is, each sub-goal for which this selection has not been specified by the requester). In doing this, the facilitator uses its knowledge of the capabilities of its

30 client agents (and possibly of other facilitators, in a multi-facilitator system). It may also use strategies or advice specified by the requester, as explained below. The

interpretation of a goal involves the coordination of requests to the satisfying agents, and assembling their responses into a coherent whole, for return to the requester.

A further preferred embodiment of present invention extends facilitation so the facilitator can employ strategies and advice given by the requesting agent, resulting in a variety of interaction patterns that may be instantiated in the satisfaction of a request.

A further preferred embodiment of present invention handles the distribution of both data update requests and requests for installation of triggers, preferably using some of the same strategies that are employed in the delegation of service requests.

10 Note that the reliance on facilitation is not absolute; that is, there is no hard requirement that requests and services be matched up by the facilitator, or that interagent communications go through the facilitator. There is preferably support in the agent library for explicit addressing of requests. However, a preferred embodiment of the present invention encourages employment the paradigm of agent 15 communities, minimizing their development effort, by taking advantage of the facilitator's provision of transparent delegation and handling of compound goals.

A facilitator is preferably viewed as a *coordinator*, not a controller, of cooperative task completion. A facilitator preferably never initiates an activity. A facilitator preferably responds to requests to manage the satisfaction of some goal, the update of some data repository, or the installation of a trigger by the appropriate agent or agents. All agents can preferably take advantage of the facilitator's expertise in delegation, and its up-to-date knowledge about the current membership of a dynamic community. The facilitator's coordination services often allows the developer to lessen the complexity of individual agents, resulting in a more manageable software development process, and enabling the creation of lightweight agents.

Maintaining Data Repositories

The agent library supports the creation, maintenance, and use of databases, in the form of data solvables. Creation of a data solvable requires only that it be declared. Querying a data solvable, as with access to any solvable, is done using *oaa_Solve*.

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A data solvable is conceptually similar to a relation in a relational database. The facts associated with each solvable are maintained by the agent library, which also handles incoming messages containing queries of data solvables. The default behavior of an agent library in managing these facts may preferably be refined, using

- 5 parameters specified with the solvable's declaration. For example, the parameter single_value preferably indicates that the solvable should only contain a single fact at any given point in time. The parameter unique_values preferably indicates that no duplicate values should be stored.
- Other parameters preferably allow data solvables use of the concepts of ownership and persistence. For implementing shared repositories, it is often preferable to maintain a record of which agent created each fact of a data solvable with the creating agent being preferably considered the fact's owner. In many applications, it is preferable to remove an agent's facts when that agent goes offline (for instance, when the agent is no longer participating in the agent community, whether by deliberate termination or by malfunction). When a data solvable is declared to be non-persistent, its facts are automatically maintained in this way, whereas a persistent data solvable preferably retains its facts until they are explicitly removed.
- A further preferred embodiment of present invention supports an agent library through procedures by which agents can update (add, remove, and replace) facts belonging to data solvables, either locally or on other agents, given that they have preferably the required permissions. These procedures may preferably be refined using many of the same parameters that apply to service requests. For example, the *address* parameter preferably specifies one or more particular agents to which the update request applies. In its absence, just as with service requests, the update request preferably goes to *all* agents providing the relevant data solvable. This default behavior can be used to maintain coordinated "mirror" copies of a data set within

Similarly, the *feedback* parameters, described in connection with *oaa_Solve*, are preferably available for use with data maintenance requests.

multiple agents, and can be useful in support of distributed, collaborative activities.

A further preferred embodiment of present invention supports ability to provide data solvables not just to client agents, but also to facilitator agents. Data solvables can preferably created, maintained and used by a facilitator. The facilitator preferably can, at the request of a client of the facilitator, create, maintain and share

5 the use of data solvables with all the facilitator's clients. This can be useful with relatively stable collections of agents, where the facilitator's workload is predictable.

Using a Blackboard Style of Communication

- In a further preferred embodiment of present invention, when a data solvable is publicly readable and writable, it acts essentially as a global data repository and can be used cooperatively by a group of agents. In combination with the use of triggers, this allows the agents to organize their efforts around a "blackboard" style of communication.
- As an example, the "DCG-NL" agent (one of several existing natural language processing agents), provides natural language processing services for a variety of its peer agents, expects those other agents to record, on the facilitator, the vocabulary to which they are prepared to respond, with an indication of each word's part of speech, and of the logical form (*ICL* sub-goal) that should result from the use of that word. In a further preferred embodiment of present invention, the NL agent, preferably when it comes online, preferably installs a data solvable for each basic part of speech on its facilitator. For instance, one such solvable would be:

solvable(noun(Meaning, Syntax), [], [])

Note that the empty lists for the solvable's permissions and parameters are acceptable here, since the default permissions and parameters provide appropriate functionality.

A further preferred embodiment of present invention incorporating an Office Assistant system as discussed herein or similar to the discussion here supports several agents making use of these or similar services. For instance, the database agent uses the following call, to library procedure *oaa_AddData*, to post the noun `boss', and to indicate that the "meaning" of boss is the concept `manager':

30 oaa_AddData(noun(manager, atom(boss)), [address(parent)])

Autonomous Monitoring with Triggers

A further preferred embodiment of present invention includes support for triggers, providing a general mechanism for requesting some action be taken when a set of conditions is met. Each agent can preferably install triggers either locally, for itself, or remotely, on its facilitator or peer agents. There are preferably at least four types of triggers: communication, data, task, and time. In addition to a type, each trigger preferably specifies at least a condition and an action, both preferably expressed in *ICL*. The condition indicates under what circumstances the trigger should fire, and the action indicates what should happen when it fires. In addition, each

trigger can be set to fire either an unlimited number of times, or a specified number of times, which can be any positive integer.

Triggers can be used in a variety of ways within preferred embodiments of the present invention. For example, triggers can be used for monitoring external sensors in the execution environment, tracking the progress of complex tasks, or coordinating communications between agents that are essential for the synchronization of related tasks. The installation of a trigger within an agent can be thought of as a representation of that agent's *commitment* to carry out the specified action, whenever the specified condition holds true.

Communication triggers preferably allow any incoming or outgoing event
 (message) to be monitored. For instance, a simple communication trigger may say something like: "Whenever a solution to a goal is returned from the facilitator, send the result to the presentation manager to be displayed to the user."

Data triggers preferably monitor the state of a data repository (which can be maintained on a facilitator or a client agent). Data triggers' conditions may be tested upon the addition, removal, or replacement of a fact belonging to a data solvable. An example data trigger is: "When 15 users are simultaneously logged on to a machine, send an alert message to the system administrator."

Task triggers preferably contain conditions that are tested after the processing of each incoming event and whenever a timeout occurs in the event polling. These
conditions may specify any goal executable by the local *ICL* interpreter, and most often are used to test when some solvable becomes satisfiable. Task triggers are

useful in checking for task-specific internal conditions. Although in many cases such conditions are captured by solvables, in other cases they may not be. For example, a mail agent might watch for new incoming mail, or an airline database agent may monitor which flights will arrive later than scheduled. An example task trigger is: "When mail arrives for me about security, notify me immediately."

Time triggers preferably monitor time conditions. For instance, an alarm trigger can be set to fire at a single fixed point in time (e.g., "On December 23rd at 3pm"), or on a recurring basis (e.g., "Every three minutes from now until noon").

Triggers are preferably implemented as data solvables, declared implicitly for every agent. When requesting that a trigger be installed, an agent may use many of the same parameters that apply to service and data maintenance requests.

A further preferred embodiment of present invention incorporates semantic support, in contrast with most programming methodologies, of the agent on which the trigger is installed only having to know how to evaluate the conditional part of the 15 trigger, not the consequence. When the trigger fires, the action is delegated to the facilitator for execution. Whereas many commercial mail programs allow rules of the form "When mail arrives about XXX, [forward it, delete it, archive it]", the possible actions are hard-coded and the user must select from a fixed set.

A further preferred embodiment of present invention, the consequence of a trigger may be any compound goal executable by the dynamic community of agents. Since new agents preferably define both functionality and vocabulary, when an unanticipated agent (for example, a fax agent) joins the community, no modifications to existing code is required for a user to make use of it - "When mail arrives, fax it to Bill Smith."

25

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The Agent Library

In a preferred embodiment of present invention, the agent library provides the infrastructure for constructing an agent-based system. The essential elements of protocol (involving the details of the messages that encapsulate a service request and

its response) are preferably made transparent to simplify the programmingapplications. This enables the developer to focus functionality, rather than message

construction details and communication details. For example, to request a service of another agent, an agent preferably calls the library procedure *oaa_Solve*. This call results in a message to a facilitator, which will exchange messages with one or more service providers, and then send a message containing the desired results to the

requesting agent. These results are returned via one of the arguments of *oaa_Solve*.
 None of the messages involved in this scenario is explicitly constructed by the agent developer. Note that this describes the *synchronous* use of *oaa_Solve*.

In another preferred embodiment of present invention, an agent library provides both *intra*agent and *inter*agent infrastructure; that is, mechanisms supporting the internal structure of individual agents, on the one hand, and mechanisms of cooperative interoperation between agents, on the other. Note that most of the infrastructure cuts across this boundary with many of the same mechanisms supporting both agent internals and agent interactions in an integrated fashion. For example, services provided by an agent preferably can be accessed by that agent through the same procedure (*oaa_Solve*) that it would employ to request a service of another agent (the only difference being in the *address* parameter accompanying the request). This helps the developer to reuse code and avoid redundant entry points into the same functionality.

Both of the preferred characteristics described above (transparent construction of messages and integration of *intra*agent with *inter*agent mechanisms) apply to most other library functionality as well, including but not limited to data management and temporal control mechanisms.

Source Code Appendix

Source code for version 2.0 of the*OAA* software product is included as an appendix hereto, and is incorporated herein by reference. The code includes an agent library, which provides infrastructure for constructing an agent-based system. The library's several families of procedures provide the functionalities discussed above, as well as others that have not been discussed here but that will be sufficiently clear to the interested practitioner. For example, declarations of an agent's solvables, and their

30 registration with a facilitator, are managed using procedures such as oaa_Declare, oaa_Undeclare, and oaa_Redeclare. Updates to data solvables can be accomplished with a family of procedures including oaa_AddData, oaa_RemoveData, and *oaa_ReplaceData*. Similarly, triggers are maintained using procedures such as *oaa_AddTrigger*, *oaa_RemoveTrigger*, and *oaa_ReplaceTrigger*. The provided source code also includes source code for an OAA Facilitator Agent.

The source code appendix is offered solely as a means of further helping practitioners to construct a preferred embodiment of the invention. By no means is the source code intended to limit the scope of the present invention.

Illustrative Applications

To further illustrate the technology of the preferred embodiment, we will next present and discuss two sample applications of the present inventions.

10 Unified Messaging

A further preferred embodiment of present invention incorporates a Unified Messaging application extending the Automated Office application presented previously herein with an emphasis on ubiquitous access and dynamic presentation of the information and services supported by the agent community. The agents used in this application are depicted in Figure 12.

A hypothetical example of realistic dialog using a preferred embodiment of the present invention can provide insight into how systems may preferably be built using the present invention. In this scenario, the user, with only a telephone as an interface, is planning a trip to Boston where he will soon give a presentation.

20 Capitalized sentences are phrases spoken by the user into the telephone and processed by a phone agent 452.

Responses, unless otherwise indicated, are spoken by the system using text-tospeech generation agent 454.

25 1.1 Welcome to SRI International. Please enter your user ID and password. <User enters touchtone ID and password> Good to see you again Adam Cheyer. I am listening to you.

30 Every user interface agent 408, including the telephone agent 452, should know the identify of its user. This information is used in resolving anaphoric

references such as "me" and "I", and allows multiple user interfaces operated by the same user to work together.

1.2 WHAT IS TODAY'S SCHEDULE? Here is today's schedule for Adam Chever: 5 At 10am for 1 hour, meeting with Dave. At 3pm for 1 hour, presentation about software agents.

End of schedule.

If the user is operating both a graphical user interface and a telephone, as described in conjunction with the Automated Office application, the result of this 10 spoken request is to display a calendar window containing the current schedule. In this case, with no graphical display available, the GEN_NL agent 1202 is tasked to produce a spoken response that can be played over the phone. GEN_NL shares the same dynamic vocabulary and phrasal rules as the natural language parser DCG_NL 426, and contains strategies for producing responses to queries using either simple or 15

list based multimedia utterances

| | nst-Da | ised multimedia utterances. |
|----|-------------------------|---|
| | | FIND FRIDAY'S WEATHER IN BOSTON. The weather in Boston for Friday is as follows: Sunny in the morning. Partly cloudy in the |
| 20 | afte | rnoon with a 20 |
| | • | percent chance of thunderstorms late. Highs in the |
| | mid | 70s. |
| | | In addition to data accessible from legacy applications, content may be |
| | retriev | ved by web-reading agents which provide wrappers around useful websites. |
| 25 | 1.4 | FIND ALL NEW MAIL MESSAGES. There are 2 messages available. Message 1, from Mark Tierny, entitled "OAA meeting." |
| | 1.5 | NEXT MESSAGE Message 2, from Jennifer Schwefler, entitled |
| 30 | "Presentation Summary." | |
| | | PLAY IT. |
| | | This message is a multipart MIME-encoded message. |
| | Ther | e are two parts. |
| | | Part 1. (Voicemail message, not text-to speech): |
| 35 | | Thanks for taking part as a speaker in our |
| | conf | erence. |
| | | The schedule will be posted soon on our homepage. |
| | 1.7 | NEXT PART |
| | | Part 2. (read using text-to-speech): |
| 40 | | The presentation home page is http://www |
| | 1.8 | PRINT MESSAGE |
| | | Command executed. |

Mail messages are no longer just simple text documents, but often consist of multiple subparts containing audio files, pictures, webpages, attachments and so forth. When a user asks to play a complex email message over the telephone, many different agents may be implicated in the translation process, which would be quite different

5 given the request "print it." The challenge is to develop a system which will enable agents to cooperate in an extensible, flexible manner that alleviates explicit coding of agent interactions for every possible input/output combination.

In a preferred embodiment of the present invention, each agent concentrates only on what it can do and on what it knows, and leaves other work to be delegated to the agent community. For instance, a printer agent 1204, defining the solvable print(Object,Parameters), can be defined by the following pseudo-code, which basically says, "If someone can get me a document, in either POSTSCRIPT or text form, I can print it.".

| 15 | <pre>print(Object, Parameters) { ' If Object is reference to "it", find an appropriate</pre> | | | |
|----|--|--|--|--|
| | document | | | |
| | if (Object = "ref(it)") | | | |
| | | | | |
| | oaa_Solve(resolve_reference(the, document, Params, | | | |
| 20 | Object),[]); | | | |
| | ' Given a reference to some document, ask for the | | | |
| | document in POSTSCRIPT | | | |
| | if (Object = "id(Pointer)") | | | |
| | <pre>oaa_Solve(resolve_id_as(id(Pointer), postscript,</pre> | | | |
| 25 | [], Object),[]); | | | |
| | ' If Object is of type text or POSTSCRIPT, we can | | | |
| | print it. | | | |
| | if ((Object is of type Text) or (Object is of type | | | |
| | Postscript)) | | | |
| 30 | do_print(Object); | | | |
| | } | | | |

In the above example, since an email message is the salient document, the mail agent 442 will receive a request to produce the message as POSTSCRIPT. Whereas the mail agent 442 may know how to save a text message as POSTSCRIPT,

35 it will not know what to do with a webpage or voicemail message. For these parts of the message, it will simply send oaa_Solve requests to see if another agent knows how to accomplish the task. Until now, the user has been using only a telephone as user interface. Now, he moves to his desktop, starts a web browser 436, and accesses the URL referenced by the mail message.

 1.9 RECORD MESSAGE
 Recording voice message. Start speaking now.
 1.10 THIS IS THE UPDATED WEB PAGE CONTAINING THE PRESENTATION SCHEDULE. Message one recorded.
 1.11 IF THIS WEB PAGE CHANGES, GET IT TO ME WITH NOTE
 ONE. Trigger added as requested.

In this example, a local agent 436 which interfaces with the web browser can return the current page as a solution to the request "oaa_Solve(resolve_reference(this, web_page, [], Ref),[])", sent by the NL agent 426. A trigger is installed on a web agent 436 to monitor changes to the page, and when the page is updated, the notify agent 446 can find the user and transmit the webpage and voicemail message using the most appropriate media transfer mechanism.

This example based on the Unified Messaging application is intended to show how concepts in accordance with the present invention can be used to produce a simple yet extensible solution to a multi-agent problem that would be difficult to implement using a more rigid framework. The application supports adaptable presentation for queries across dynamically changing, complex information; shared context and reference resolution among applications; and flexible translation of multimedia data. In the next section, we will present an application which highlights the use of parallel competition and cooperation among agents during multi-modal fusion.

Multimodal Map

A further preferred embodiment of present invention incorporates the Multimodal Map application. This application demonstrates natural ways of communicating with a community of agents, providing an interactive interface on which the user may draw, write or speak. In a travel-planning domain illustrated by Figure 13, available information includes hotel, restaurant, and tourist-site data retrieved by distributed software agents from commercial Internet sites. Some preferred types of user interactions and multimodal issues handled by the application

are illustrated by a brief scenario featuring working examples taken from the current system.

Sara is planning a business trip to San Francisco, but would like to schedule some activities for the weekend while she is there. She turns on her laptop PC, executes a map application, and selects San Francisco. 5 [Speaking] Where is downtown? 2.1 Map scrolls to appropriate area. 2.2 [Speaking and drawing region] Show me all hotels near here. Icons representing hotels appear. 10 [Writes on a hotel] Info? 2.3 A textual description (price, attributes, etc.) appears. [Speaking] I only want hotels with a pool. 2.4 Some hotels disappear. 15 [Draws a crossout on a hotel that is too close to a 2.5 highway] Hotel disappears [Speaking and circling] Show me a photo of this 2.6 hotel. 20 Photo appears. [Points to another hotel] 2.7 Photo appears. 2.8 [Speaking] Price of the other hotel? Price appears for previous hotel. 25

- 2.9 [Speaking and drawing an arrow] Scroll down. Display adjusted.
- 2.10 [Speaking and drawing an arrow toward a hotel] What is the distance from this hotel to Fisherman's
- 30 Wharf?
 - Distance displayed.

2.11 [Pointing to another place and speaking] And the distance to here?

Distance displayed.

35 Sara decides she could use some human advice. She picks up the phone, calls Bob, her travel agent, and writes Start collaboration to synchronize his display with hers. At this point, both are presented with identical maps, and the input and actions of one will be remotely seen by the other.

40 3.1 [Sara speaks and circles two hotels] Bob, I'm trying to choose between these two hotels. Any opinions?
3.2 [Bob draws an arrow, speaks, and points] Well, this area is really nice to visit. You can
45 walk there from this hotel. Map scrolls to indicated area. Hotel selected. 3.3 [Sara speaks] Do you think I should visit Alcatraz? 3.4 [Bob speaks] Map, show video of Alcatraz. Video appears.

- 5
- 3.5 [Bob speaks] Yes, Alcatraz is a lot of fun.

A further preferred embodiment of present invention generates the most appropriate interpretation for the incoming streams of multimodal input. Besides providing a user interface *to* a dynamic set of distributed agents, the application is preferably built *using* an agent framework. The present invention also contemplates aiding the coordinate competition and cooperation among information sources, which in turn works in parallel to resolve the ambiguities arising at every level of the interpretation process: *low-level processing of the data stream, anaphora resolution, cross-modality influences* and *addressee*.

15 *Low-level processing of the data stream*: Pen input may be preferably 15 interpreted as a gesture (e.g., 2.5: cross-out) by one algorithm, or as handwriting by a separate recognition process (e.g., 2.3: "info?"). Multiple hypotheses may preferably be returned by a modality recognition component.

Anaphora resolution: When resolving anaphoric references, separate 20 information sources may contribute to resolving the reference: context by object type, deictic, visual context, database queries, discourse analysis. An example of information provided through context by object type is found in interpreting an utterance such as "show photo of the hotel", where the natural language component can return a list of the last hotels talked about. Deictic information in combination

- with a spoken utterance like "show photo of this hotel" may preferably include pointing, circling, or arrow gestures which might indicate the desired object (e.g., 2.7). Deictic references may preferably occur before, during, or after an accompanying verbal command. Information provided in a visual context, given for the request "display photo of the hotel" may preferably include the user interface
- 30 agent might determine that only one hotel is currently visible on the map, and therefore this might be the desired reference object. Database queries preferably involving information from a database agent combined with results from other resolution strategies. Examples are "show me a photo of the hotel in Menlo Park" and

2.2. Discourse analysis preferably provides a source of information for phrases such as "No, the other one" (or 2.8).

The above list of preferred anaphora resolution mechanisms is not exhaustive. Examples of other preferred resolution methods include but are not limited to spatial reasoning ("the hotel between Fisherman's Wharf and Lombard Street") and user preferences ("near my favorite restaurant").

Cross-modality influences: When multiple modalities are used together, one modality may preferably reinforce or remove or diminish ambiguity from the interpretation of another. For instance, the interpretation of an arrow gesture may vary when accompanied by different verbal commands (e.g., "scroll left" vs. "show info about this hotel"). In the latter example, the system must take into account how accurately and unambiguously an arrow selects a single hotel.

Addressee: With the addition of collaboration technology, humans and automated agents all share the same workspace. A pen doodle or a spoken utterance
15 may be meant for either another human, the system (3.1), or both (3.2).

The implementation of the Multimodal Map application illustrates and exploits several preferred features of the present invention: reference resolution and task delegation by parallel parameters of oaa_Solve, basic multi-user collaboration handled through built-in data management services, additional functionality readily achieved by adding new agents to the community, domain-specific code cleanly separated from other agents.

A further preferred embodiment of present invention provides reference resolution and task delegation handled in a distributed fashion by the parallel parameters of oaa_Solve, with meta-agents encoding rules to help the facilitator make context- or user-specific decisions about priorities among knowledge sources.

A further preferred embodiment of present invention provides basic multi-user collaboration handled through at least one built-in data management service. The map user interface preferably publishes data solvables for elements such as icons, screen position, and viewers, and preferably defines these elements to have the attribute "shareable". For every update to this public data, the changes are preferably

Attornev Docket No: SRI1P016(3477)/BRC/EWJ Page 44 of 778

Page 42 of 59

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automatically replicated to all members of the collaborative session, with associated callbacks producing the visible effect of the data change (e.g., adding or removing an icon).

Functionality for recording and playback of a session is preferably
5 implemented by adding agents as members of the collaborative community. These agents either record the data changes to disk, or read a log file and replicate the changes in the shared environment.

The domain-specific code for interpreting travel planning dialog is preferably separated from the speech, natural language, pen recognition, database and map user interface agents. These components were preferably reused without modification to add multimodal map capabilities to other applications for activities such as crisis management, multi-robot control, and the MVIEWS tools for the video analyst. Improved Scalability and Fault Tolerance

Implementations of a preferred embodiment of present invention which rely upon simple, single facilitator architectures may face certain limitations with respect to scalability, because the single facilitator may become a communications bottleneck and may also represent a single, critical point for system failure.

Multiple facilitator systems as disclosed in the preferred embodiments to this point can be used to construct peer-to-peer agent networks as illustrated in Figure 14. While such embodiments are scalable, they do possess the potential for communication bottlenecks as discussed in the previous paragraph and they further possess the potential for reliability problems as central, critical points of vulnerability to systems failure.

A further embodiment of present invention supports a facilitator implemented as an agent like any other, whereby multiple facilitator network topologies can be readily constructed. One example configuration (but not the only possibility) is a hierarchical topology as depicted in Figure 15, where a top level Facilitator manages collections of both client agents 1508 and other Facilitators, 1504 and 1506. Facilitator agents could be installed for individual users, for a group of users, or as

30 appropriate for the task.

Note further, that network work topologies of facilitators can be seen as graphs where each node corresponds to an instance of a facilitator and each edge connecting two or more nodes corresponds to a transmission path across one or more physical transport mechanisms. Some nodes may represent facilitators and some

5 nodes may represent clients. Each node can be further annotated with attributes corresponding to include triggers, data, capabilities but not limited to these attributes.

A further embodiment of present invention provides enhanced scalability and robustness by separating the planning and execution components of the facilitator. In contrast with the centralized facilitation schemes described above, the facilitator

10 system 1600 of Figure 16 separates the registry/planning component from the execution component. As a result, no single facilitator agent must carry all communications nor does the failure of a single facilitator agent shut down the entire system.

Turning directly to Figure 16, the facilitator system 1600 includes a registry/planner 1602 and a plurality of client agents 1612-1616. The registry/planner 1604 is typically replicated in one or more locations accessible by the client agents. Thus if the registry/planner 1604 becomes unavailable, the client agents can access the replicated registry/planner(s).

- This system operates, for example, as follows. An agent transmits a goal 1610 to the registry planner 1602. The registry/planner 1604 translates the goal into an unambiguous execution plan detailing how to accomplish any sub-goals developed from the compound goal, as well as specifying the agents selected for performing the sub-goals. This execution plan is provided to the requesting agent which in turn initiates peer-to-peer interactions 1618 in order to implement the detailed execution
- 25 plan, routing and combining information as specified within the execution plan. Communication is distributed thus decreasing sensitivity of the system to bandwidth limitations of a single facilitator agent. Execution state is likewise distributed thus enabling system operation even when a facilitator agent fails.

Further embodiments of present invention incorporate into the facilitator

30 functionality such as load-balancing, resource management, and dynamic configuration of agent locations and numbers, using (for example) any of the topologies discussed. Other embodiments incorporate into a facilitator the ability to aid agents in establishing peer-to-peer communications. That is, for tasks requiring a

Attornev Docket No: SRI1P016(3477)/BRC/EWJ Page 46 of 778 sequence of exchanges between two agents, the facilitator assist the agents in finding one another and establishing communication, stepping out of the way while the agents communicate peer-to-peer over a direct, perhaps dedicated channel.

Further preferred embodiments of the present invention incorporate
mechanisms for basic transaction management, such as periodically saving the state of agents (both facilitator and client) and rolling back to the latest saved state in the event of the failure of an agent.

IN THE CLAIMS:

| 1 | 1. A computer-implemented method for communication and cooperative task |
|----|---|
| 2 | completion among a plurality of distributed electronic agents, comprising the |
| 3 | acts of: |
| 4 | registering a description of each active client agent's functional capabilities, using an |
| 5 | expandable, platform-independent, inter-agent language; |
| 6 | receiving a request for service as a base goal in the inter-agent language, in the form |
| 7 | of an arbitrarily complex goal expression; and |
| 8 | dynamically interpreting the goal expression, said act of interpreting further |
| 9 | comprising: |
| 10 | generating one or more sub-goals using the inter-agent language; and |
| 11 | dispatching each of the sub-goals to a selected client agent for performance, |
| 12 | based on a match between the sub-goal being dispatched and the |
| 13 | registered functional capabilities of the selected client agent. |
| 1 | 2. A computer-implemented method as recited in claim 1, further including the |
| 2 | following acts of: |
| 3 | receiving a new request for service as a base goal using the inter-agent language, in |
| 4 | the form of another arbitrarily complex goal expression, from at least one of |
| 5 | the selected client agents in response to the sub-goal dispatched to said agent; |
| 6 | and |
| 7 | recursively applying the last step of claim 1 in order to perform the new request for |
| 8 | service. |
| 1 | 3. A computer implemented method as recited in claim 2 wherein the act |
| 2 | of registering a specific agent further includes: |
| 3 | invoking the specific agent in order to activate the specific agent; |
| 4 | instantiating an instance of the specific agent; and |
| 5 | transmitting the new agent profile from the specific agent to the facilitator |
| 6 | agent in response to the instantiation of the specific agent. |
| 1 | 4. A computer implemented method as recited in claim 1 further |
| 2 | including the act of deactivating a specific client agent no longer available to provide |
| 3 | services by deleting the registration of the specific client agent. |
| 1 | 5. A computer implemented method as recited in claim 1 further |
| 2 | comprising the act of providing an agent registry data structure. |
| | |

Attornev Docket No: SRI1P016(3477)/BRC/EWJ Page 48 of 778

Page 46 of 59

1 6. A computer implemented method as recited in claim 5 wherein the 2 agent registry data structure includes at least one symbolic name for each active agent.

1 7. A computer implemented method as recited in claim 5 wherein the 2 agent registry data structure includes at least one data declaration for each active 3 agent.

1 8. A computer implemented method as recited in claim 5 wherein the 2 agent registry data structure includes at least one trigger declaration for one active 3 agent.

9. A computer implemented method as recited in claim 5 wherein the agent registry data structure includes at least one task declaration, and process characteristics for each active agent.

1 10. A computer implemented method as recited in claim 5 wherein the 2 agent registry data structure includes at least one process characteristic for each active 3 agent.

1 11. A computer implemented method as recited in claim 1 further 2 comprising the act of establishing communication between the plurality of distributed 3 agents.

1 12. A computer implemented method as recited in claim 1 further 2 comprising the acts of:

receiving a request for service in a second language differing from the interagent language;

selecting a registered agent capable of converting the second language into the
inter-agent language; and

forwarding the request for service in a second language to the registered agent
capable of converting the second language into the inter-agent language, implicitly
requesting that such a conversion be performed and the results returned.

1 13. A computer implemented method as recited in claim 12 wherein the 2 request includes a natural language query, and the registered agent capable of 3 converting the second language into the inter-agent language service is a natural 4 language agent.

1 14. A computer implemented method as recited in claim 13 wherein the 2 natural language query was generated by a user interface agent. 1 15. A computer implemented method as recited in claim 1, wherein the
 base goal requires setting a trigger having conditional functionality and consequential
 functionality.

1 16. A computer implemented method as recited in claim 15 wherein the 2 trigger is an outgoing communications trigger, the computer implemented method 3 further including the acts of:

4 monitoring all outgoing communication events in order to determine whether a
5 specific outgoing communication event has occurred; and

in response to the occurrence of the specific outgoing communication event,
performing the particular action defined by the trigger.

1 17. A computer implemented method as recited in claim 15 wherein the 2 trigger is an incoming communications trigger, the computer implemented method 3 further including the acts of:

4 monitoring all incoming communication events in order to determine whether
5 a specific incoming communication event has occurred; and

6 in response to the occurrence of a specific incoming communication event 7 satisfying the trigger conditional functionality, performing the particular 8 consequential functionality defined by the trigger.

1 18. A computer implemented method as recited in claim 15 wherein the 2 trigger is a data trigger, the computer implemented method further including the acts 3 of:

monitoring a state of a data repository; and

in response to a particular state event satisfying the trigger conditional
functionality, performing the particular consequential functionality defined by the
trigger.

1 19. A computer implemented method as recited in claim 15 wherein the 2 trigger is a time trigger, the computer implemented method further including the acts 3 of:

monitoring for the occurrence of a particular time condition; and

5 in response to the occurrence of a particular time condition satisfying the 6 trigger conditional functionality, performing the particular consequential functionality 7 defined by the trigger.

1 20. A computer implemented method as recited in claim 15 wherein the 2 trigger is installed and executed within the facilitator agent.

4

1 21. A computer implemented method as recited in claim 15 wherein the 2 trigger is installed and executed within a first service-providing agent.

1 22. A computer implemented method as recited in claim 15 wherein the 2 conditional functionality of the trigger is installed on a facilitator agent.

1 23. A computer implemented method as recited in claim 22 wherein the 2 consequential functionality is installed on a specific service-providing agent other 3 than a facilitator agent.

1 24. A computer implemented method as recited in claim 15 wherein the 2 conditional functionality of the trigger is installed on a specific service-providing 3 agent other than a facilitator agent.

1 25. A computer implemented method as recited in claim 15 wherein the 2 consequential functionality of the trigger is installed on a facilitator agent.

1 26. A computer implemented method as recited in claim 1 wherein the 2 base goal is a compound goal having sub-goals separated by operators.

1 27. A computer implemented method as recited in claim 26 wherein the 2 type of available operators includes a conjunction operator, a disjunction operator, 3 and a conditional execution operator. 1 28. A computer implemented method as recited in claim 27 wherein the type 2 of available operators further includes a parallel disjunction operator that indicates that 3 disjunct goals are to be performed by different agents.

Attorney Docket No: SRI1P016(3477)/BRC/EWJ

1 29. A computer program stored on a computer readable medium, the 2 computer program executable to facilitate cooperative task completion within a 3 distributed computing environment, the distributed computing environment including 4 a plurality of autonomous electronic agents, the distributed computing environment 5 supporting an Interagent Communication Language, the computer program 6 comprising computer executable instructions for:

providing an agent registry that declares capabilities of service-providing
electronic agents currently active within the distributed computing environment;

9 interpreting a service request in order to determine a base goal that may be a
10 compound, arbitrarily complex base goal, the service request adhering to an
11 Interagent Communication Language (ICL), the act of interpreting including the sub12 acts of:

determining any task completion advice provided by the base goal, and determining any task completion constraints provided by the base goal;

constructing a base goal satisfaction plan including the sub-acts of:

determining whether the requested service is available,

determining sub-goals required in completing the base goal,

selecting service-providing electronic agents from the agent registry
suitable for performing the determined sub-goals, and

20 ordering a delegation of sub-goal requests to best complete the 21 requested service; and

implementing the base goal satisfaction plan.

1 30. A computer program as recited in claim 29 wherein the computer 2 executable instruction for providing an agent registry includes the following computer 3 executable instructions for registering a specific service-providing electronic agent 4 into the agent registry:

establishing a bi-directional communications link between the specific agent
and a facilitator agent controlling the agent registry;

providing a new agent profile to the facilitator agent, the new agent profile
defining publicly available capabilities of the specific agent; and

9 registering the specific agent together with the new agent profile within the
10 agent registry, thereby making available to the facilitator agent the capabilities of the
11 specific agent.

13

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A computer program as recited in claim 30 wherein the computer
 executable instruction for registering a specific agent further includes:

invoking the specific agent in order to activate the specific agent;

4 instantiating an instance of the specific agent; and

5 transmitting the new agent profile from the specific agent to the facilitator 6 agent in response to the instantiation of the specific agent.

1 32. A computer program as recited in claim 29 wherein the computer 2 executable instruction for providing an agent registry includes a computer executable 3 instruction for removing a specific service-providing electronic agent from the 4 registry upon determining that the specific agent is no longer available to provide 5 services.

1 33. A computer program as recited in claim 29 wherein the provided agent 2 registry includes a symbolic name, a unique address, data declarations, trigger 3 declarations, task declarations, and process characteristics for each active agent.

1 34. A computer program as recited in claim 29 further including computer 2 executable instructions for receiving the service request via a communications link 3 established with a client.

1 35. A computer program as recited in claim 29 wherein the computer 2 executable instruction for providing a service request includes instructions for:

receiving a non-ICL format service request;

selecting an active agent capable of converting the non-ICL formal service
request into an ICL format service request;

forwarding the non-ICL format service request to the active agent capable of
converting the non-ICL format service request, together with a request that such
conversion be performed; and

9 receiving an ICL format service request corresponding to the non-ICL format
 10 service request.

1 36. A computer program as recited in claim 35 wherein the non-ICL 2 format service request includes a natural language query, and the active agent capable 3 of converting the non-ICL formal service request into an ICL format service request is 4 a natural language agent.

37. A computer program as recited in claim 36 wherein the natural
 language query is generated by a user interface agent.

3

1 38. A computer program as recited in claim 29, the computer program 2 further including computer executable instructions for implementing a base goal that 3 requires setting a trigger having conditional and consequential functionality.

1 39. A computer program as recited in claim 38 wherein the trigger is an 2 outgoing communications trigger, the computer program further including computer 3 executable instructions for:

4 monitoring all outgoing communication events in order to determine whether a
5 specific outgoing communication event has occurred; and

in response to the occurrence of the specific outgoing communication event,
performing the particular action defined by the trigger.

1 40. A computer program as recited in claim 38 wherein the trigger is an 2 incoming communications trigger, the computer program further including computer 3 executable instructions for:

monitoring all incoming communication events in order to determine whether a specific incoming communication event has occurred; and

in response to the occurrence of the specific incoming communication event,
performing the particular action defined by the trigger.

41. A computer program as recited in claim 38 wherein the trigger is a data trigger, the computer program further including computer executable instructions for:

monitoring a state of a data repository; and

4 in response to a particular state event, performing the particular action defined5 by the trigger.

1 42. A computer program as recited in claim 38 wherein the trigger is a 2 time trigger, the computer program further including computer executable instructions 3 for:

4 monitoring for the occurrence of a particular time condition; and

in response to the occurrence of the particular time condition, performing the
particular action defined by the trigger.

43. A computer program as recited in claim 38 further including computer
 executable instructions for installing and executing the trigger within the facilitator
 agent.

1 44. A computer program as recited in claim 38 further including computer 2 executable instructions for installing and executing the trigger within a first service-3 providing agent.

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45. A computer program as recited in claim 29 further including computer
 executable instructions for interpreting compound goals having sub-goals separated
 by operators.

1 46. A computer program as recited in claim 45 wherein the type of 2 available operators includes a conjunction operator, a disjunction operator, and a 3 conditional execution operator.

1 47. A computer program as recited in claim 46 wherein the type of 2 available operators further includes a parallel disjunction operator that indicates that 3 disjunct goals are to be performed by different agents.

48. An Interagent Communication Language (ICL) providing a basis for 1 facilitated cooperative task completion within a distributed computing environment 2 having a facilitator agent and a plurality of autonomous service-providing electronic 3 4 agents, the ICL enabling agents to perform queries of other agents, exchange information with other agents, set triggers within other agents, an ICL syntax 5 supporting compound goal expressions such that goals within a single request 6 7 provided according to the ICL syntax may be coupled by a conjunctive operator, a disjunctive operator, a conditional execution operator, and a parallel disjunctive 8 9 operator parallel disjunctive operator that indicates that disjunct goals are to be performed by different agents. 10

49. An ICL as recited in claim 48, wherein the ICL is computer platform
 independent.

1 50. An ICL as recited in claim 48 wherein the ICL is independent of 2 computer programming languages which the plurality of agents are programmed in.

51. An ICL as recited in claim 48 wherein the ICL syntax supports explicit
 task completion constraints within goal expressions.

1 52. An ICL as recited in claim 51 wherein possible types of task 2 completion constraints include use of specific agent constraints and response time 3 constraints.

53. An ICL as recited in claim 51 wherein the ICL syntax supports explicit
 task completion advisory suggestions within goal expressions.

54. An ICL as recited in claim 48 wherein the ICL syntax supports explicit
 task completion advisory suggestions within goal expressions.

1 55. An ICL as recited in claim 48 wherein each autonomous service-2 providing electronic agent defines and publishes a set of capability declarations or 3 solvables, expressed in ICL, that describes services provided by such electronic agent.

56. An ICL as recited in claim 55 wherein an electronic agent's solvables
 define an interface for the electronic agent.

1 57. An ICL as recited in claim 56 wherein the facilitator agent maintains 2 an agent registry making available a plurality of electronic agent interfaces.

1 58. An ICL as recited in claim 57 wherein the possible types of solvables 2 includes procedure solvables, a procedure solvable operable to implement a procedure 3 such as a test or an action.

1 59. An ICL as recited in claim 58 wherein the possible types of solvables 2 further includes data solvables, a data solvable operable to provide access to a 3 collection of data.

1 60. An ICL as recited in claim 58 wherein the possible types of solvables 2 includes data solvables, a data solvable operable to provide access to a collection of 3 data.

1 61. A facilitator agent arranged to coordinate cooperative task completion 2 within a distributed computing environment having a plurality of autonomous service-3 providing electronic agents, the facilitator agent comprising:

an agent registry that declares capabilities of service-providing electronic
 agents currently active within the distributed computing environment; and

a facilitating engine operable to parse a service request in order to interpret a
compound goal set forth therein, the compound goal including both local and global
constraints and control parameters, the service request formed according to an
Interagent Communication Language (ICL), the facilitating engine further operable to
construct a goal satisfaction plan specifying the coordination of a suitable delegation
of sub-goal requests to complete the requested service satisfying both the local and
global constraints and control parameters.

1 62. A facilitator agent as recited in claim 61, wherein the facilitating 2 engine is capable of modifying the goal satisfaction plan during execution, the 3 modifying initiated by events such as new agent declarations within the agent registry, 4 decisions made by remote agents, and information provided to the facilitating engine 5 by remote agents.

Attornev Docket No: SRI1P016(3477)/BRC/EWJ Page 57 of 778 1 63. A facilitator agent as recited in claim 61 wherein the agent registry 2 includes a symbolic name, a unique address, data declarations, trigger declarations, 3 task declarations, and process characteristics for each active agent.

1 64. A facilitator agent as recited in claim 61 wherein the facilitating engine 2 is operable to install a trigger mechanism requesting that a certain action be taken 3 when a certain set of conditions are met.

1 65. A facilitator agent as recited in claim 64 wherein the trigger 2 mechanism is a communication trigger that monitors communication events and 3 performs the certain action when a certain communication event occurs.

1 66. A facilitator agent as recited in claim 64 wherein the trigger 2 mechanism is a data trigger that monitors a state of a data repository and performs the 3 certain action when a certain data state is obtained.

67. A facilitator agent as recited in claim 66 wherein the data repository is
 local to the facilitator agent.

68. A facilitator agent as recited in claim 66 wherein the data repository is
 remote from the facilitator agent.

69. A facilitator agent as recited in claim 64 wherein the trigger
 mechanism is a task trigger having a set of conditions.

1 70. A facilitator agent as recited in claim 61, the facilitator agent further 2 including a global database accessible to at least one of the service-providing 3 electronic agents.

1 71. A software-based, flexible computer architecture for communication 2 and cooperation among distributed electronic agents, the architecture contemplating a 3 distributed computing system comprising:

a plurality of service-providing electronic agents; and

5 a facilitator agent in bi-directional communications with the plurality of 6 service-providing electronic agents, the facilitator agent including:

an agent registry that declares capabilities of service-providing
electronic agents currently active within the distributed computing
environment;

10a facilitating engine operable to parse a service request in order11to interpret an arbitrarily complex goal set forth therein, the facilitating12engine further operable to construct a goal satisfaction plan including

the coordination of a suitable delegation of sub-goal requests to best complete the requested service.

72. A computer architecture as recited in claim 71, wherein the basis for 1 2 the computer architect is an Interagent Communication Language (ICL) enabling agents to perform queries of other agents, exchange information with other agents, 3 4 and set triggers within other agents, the ICL further defined by an ICL syntax supporting compound goal expressions such that goals within a single request 5 provided according to the ICL syntax may be coupled by a conjunctive operator, a 6 7 disjunctive operator, a conditional execution operator, and a parallel disjunctive 8 operator parallel disjunctive operator that indicates that disjunct goals are to be 9 performed by different agents.

73. A computer architecture as recited in claim 72, wherein the ICL is
 computer platform independent.

1 74. A computer architecture as recited in claim 73 wherein the ICL is 2 independent of computer programming languages in which the plurality of agents are 3 programmed.

75. A computer architecture as recited in claim 73 wherein the ICL syntax
 supports explicit task completion constraints within goal expressions.

1 76. A computer architecture as recited in claim 75 wherein possible types 2 of task completion constraints include use of specific agent constraints and response 3 time constraints.

77. A computer architecture as recited in claim 75 wherein the ICL syntax
 supports explicit task completion advisory suggestions within goal expressions.

78. A computer architecture as recited in claim 73 wherein the ICL syntax
 supports explicit task completion advisory suggestions within goal expressions.

1 79. A computer architecture as recited in claim 73 wherein each 2 autonomous service-providing electronic agent defines and publishes a set of 3 capability declarations or solvables, expressed in ICL, that describes services 4 provided by such electronic agent.

1 80. A computer architecture as recited in claim 79 wherein an electronic 2 agent's solvables define an interface for the electronic agent.

1 81. A computer architecture as recited in claim 80 wherein the possible 2 types of solvables includes procedure solvables, a procedure solvable operable to 3 implement a procedure such as a test or an action.

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82. A computer architecture as recited in claim 81 wherein the possible
 types of solvables further includes data solvables, a data solvable operable to provide
 access to a collection of data.

83. A computer architecture as recited in claim 82 wherein the possible 1 types of solvables includes a data solvable operable to provide access 2 3 to modify a collection of data. 84. • A computer architecture as recited in claim 71 wherein the planning 1 component of the facilitating engine are distributed across at least two 2 computer processes. 3 85. A computer architecture as recited in claim 71 wherein the execution 1 component of the facilitating engine is distributed across at least two 2 computer processes. 3 86. A data wave carrier providing a transport mechanism for information 1 2 communication in a distributed computing environment having at least one facilitator agent and at least one active client agent, the data wave carrier comprising a signal 3 representation of an inter-agent language description of an active client agent's 4 functional capabilities. 5 87. A data wave carrier as recited in claim 85, the data wave carrier further 1 comprising a signal representation of a request for service in the inter-agent language 2 3 from a first agent to a second agent. 88. A data wave carrier as recited in claim 85, the data wave carrier further 1 comprising a signal representation of a goal dispatched to an agent for performance 2 from a facilitator agent. 3

1 89. A data wave carrier as recited in claim 88 wherein a later state of the 2 data wave carrier comprises a signal representation of a response to the dispatched 3 goal including results and/or a status report from the agent for performance to the 4 facilitator agent.

Software-Based Architecture for Communication and Cooperation Among Distributed Electronic Agents

ABSTRACT

A highly flexible, software-based architecture is disclosed for constructing distributed systems. The architecture supports cooperative task completion by flexible, dynamic configurations of autonomous electronic agents. Communication and cooperation between agents are brokered by one or more facilitators, which are responsible for matching requests, from users and agents, with descriptions of the
capabilities of other agents. It is not generally required that a user or agent know the identities, locations, or number of other agents involved in satisfying a request, and relatively minimal effort is involved in incorporating new agents and "wrapping" legacy applications. Extreme flexibility is achieved through an architecture organized around the declaration of capabilities by service-providing agents, the construction of

- 15 arbitrarily complex goals by users and service-requesting agents, and the role of facilitators in delegating and coordinating the satisfaction of these goals, subject to advice and constraints that may accompany them. Additional mechanisms and features include facilities for creating and maintaining shared repositories of data; the use of triggers to instantiate commitments within and between agents; agent-based
- 20 provision of multi-modal user interfaces, including natural language; and built-in support for including the user as a privileged member of the agent community. Specialized embodiments providing enhanced scalability are also described.

Page 59 of 59

Page 61 of 778



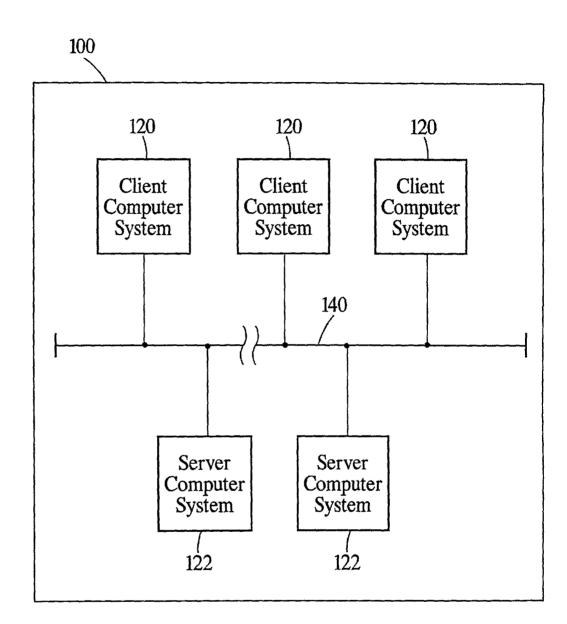


Fig. 1 (Prior Art)

Page 62 of 778

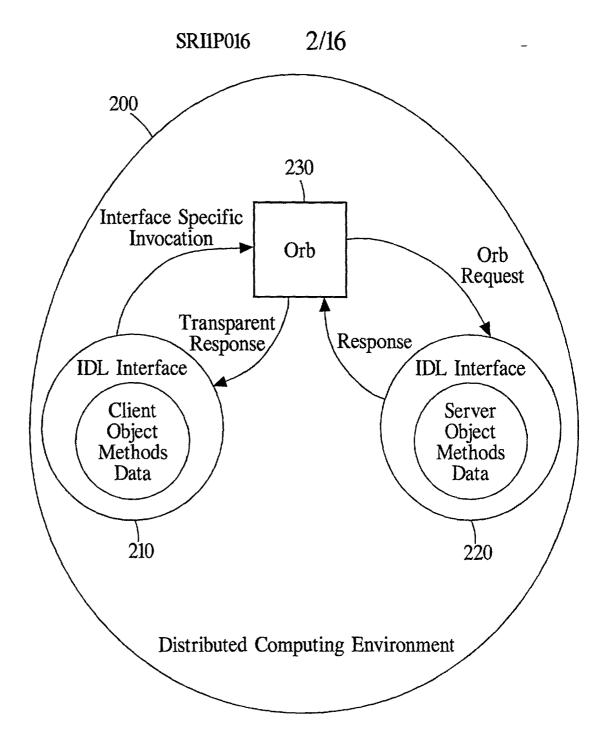


Fig. 2 (Prior Art)

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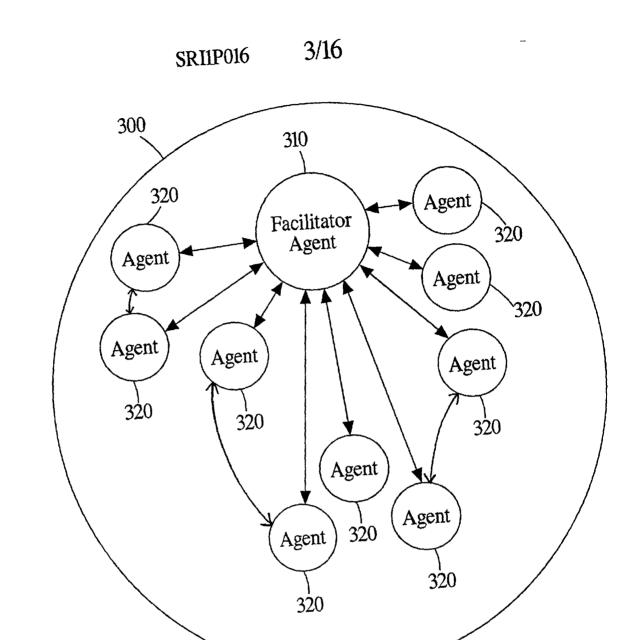


Fig. 3

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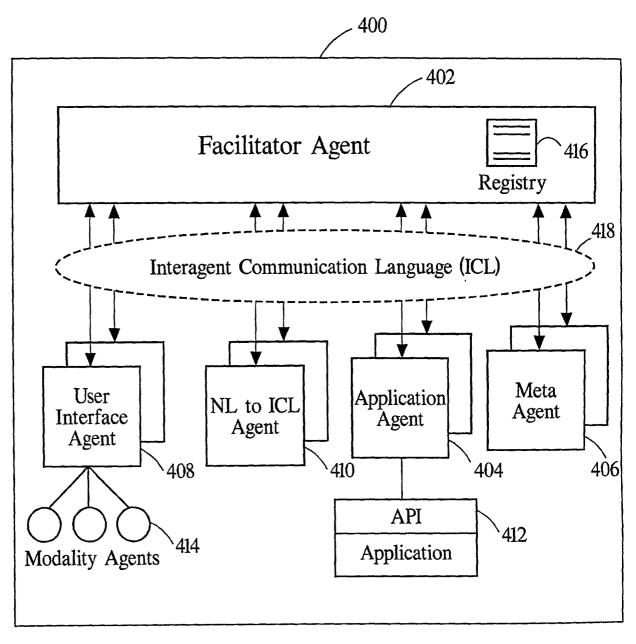
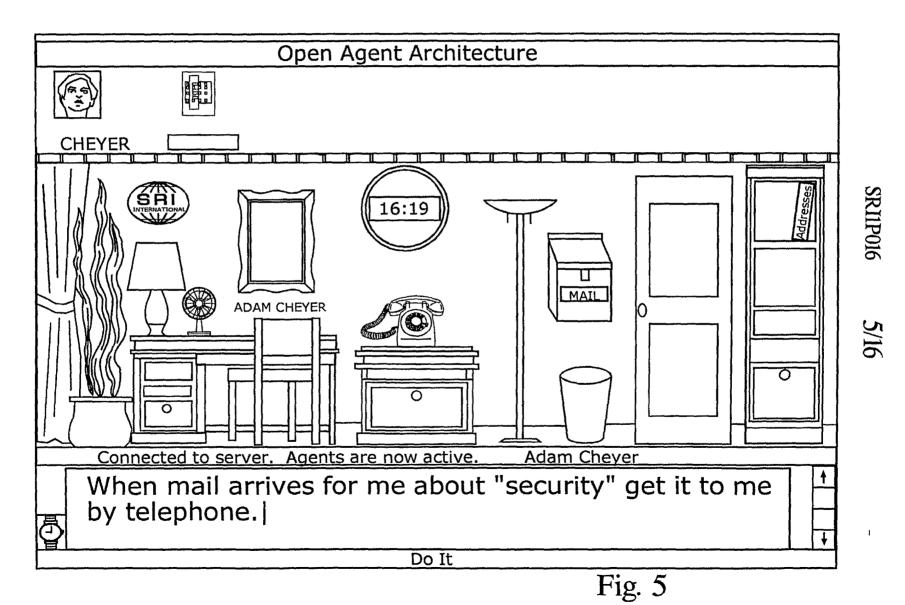
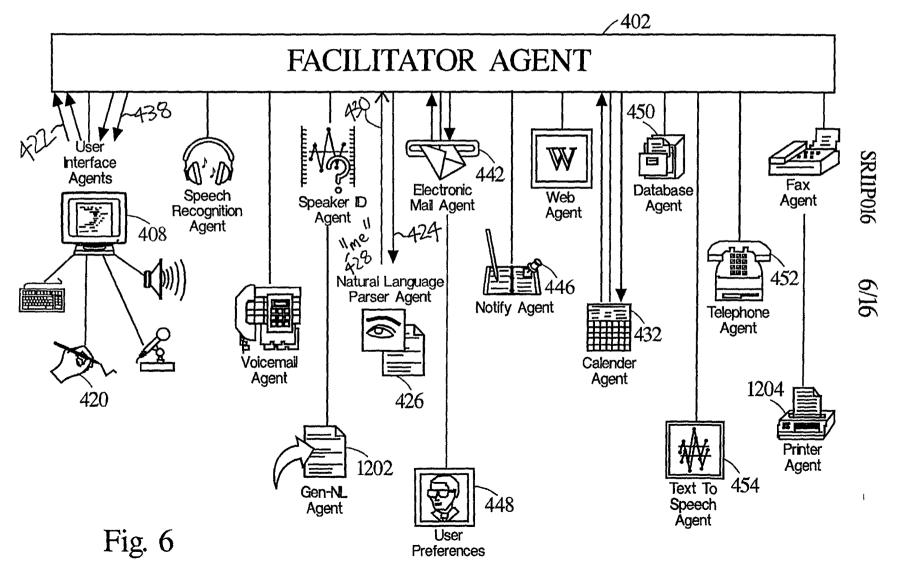


Fig. 4

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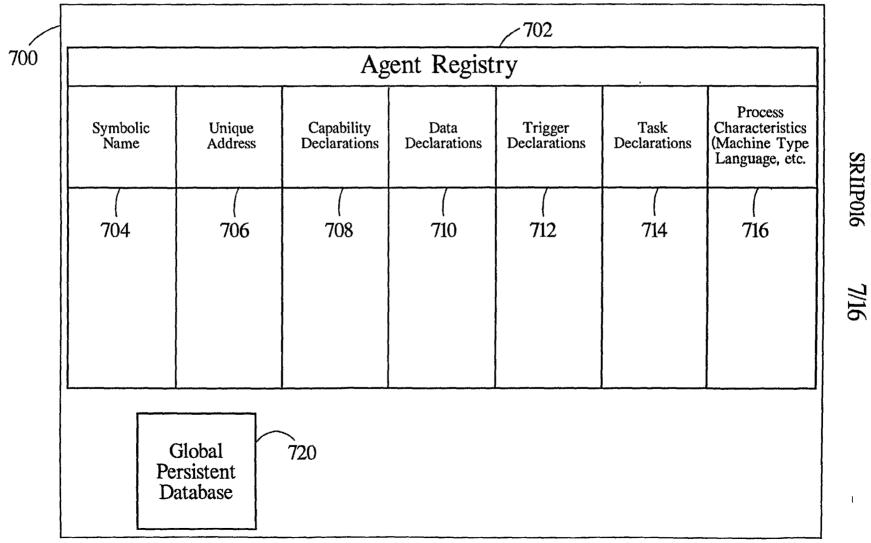


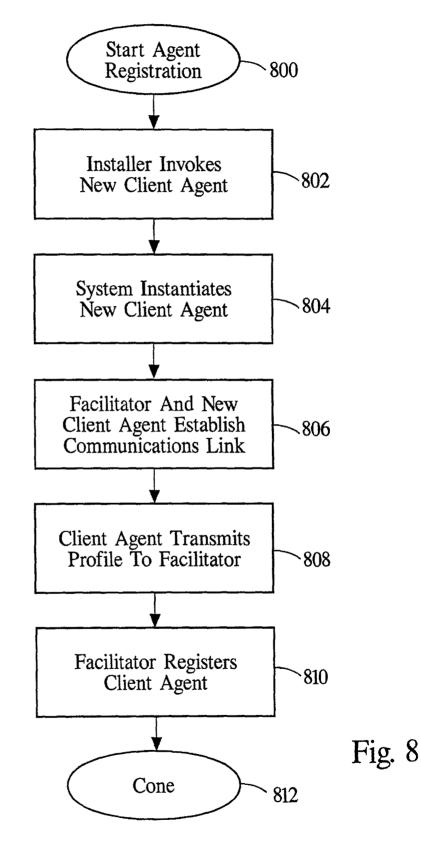
Page 67 of 778

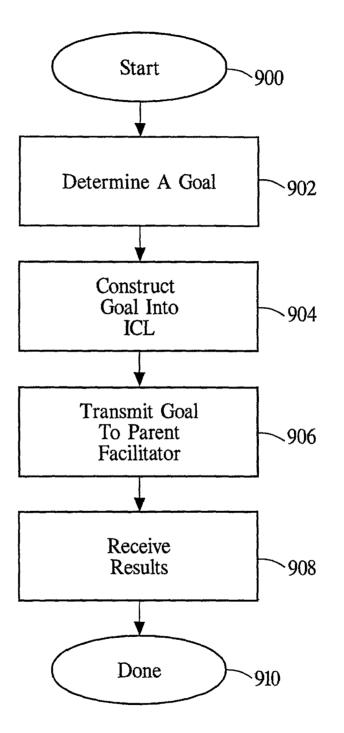
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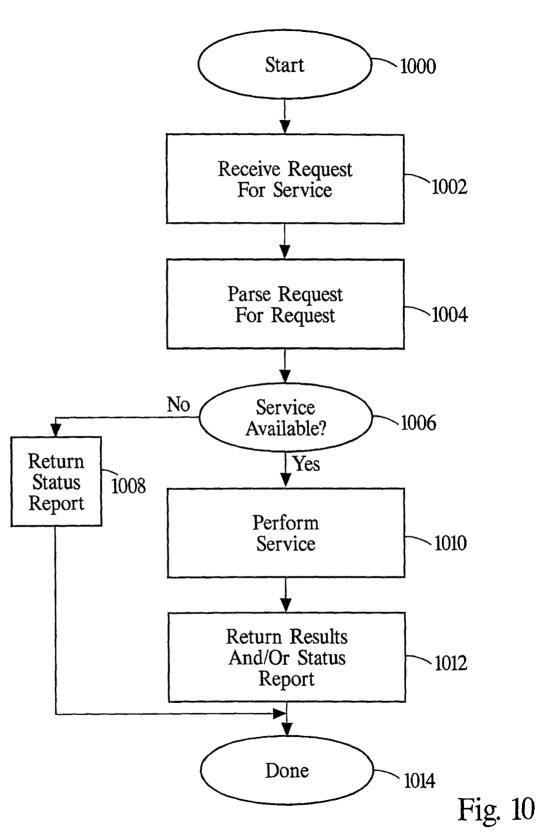






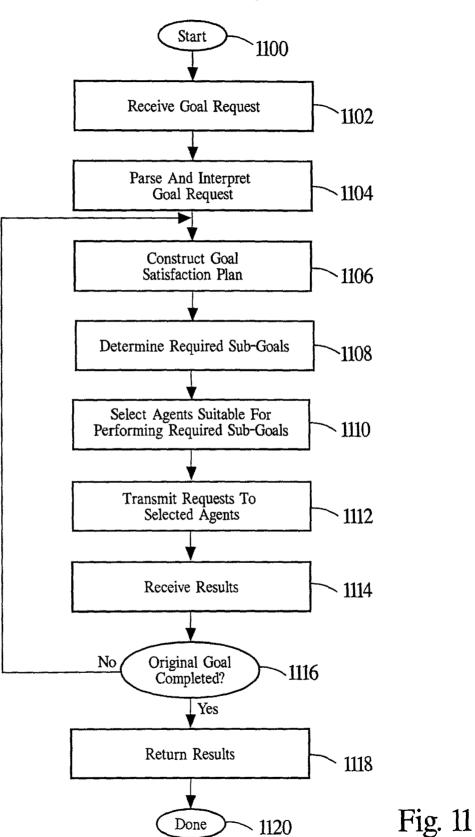


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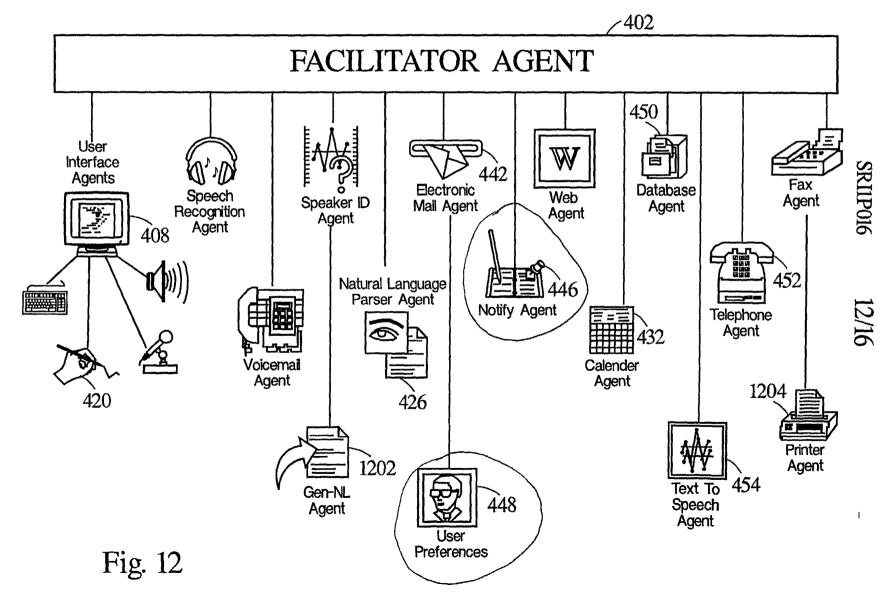




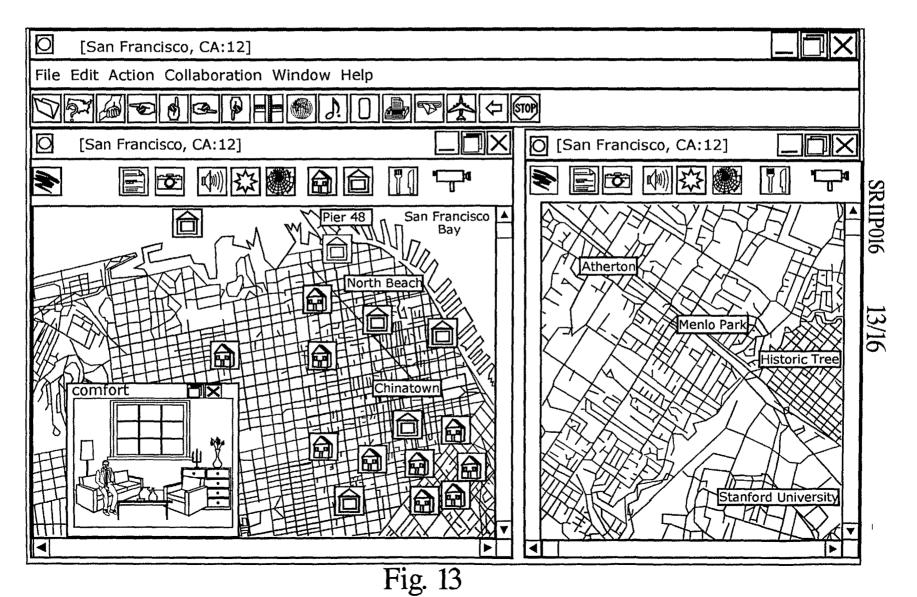
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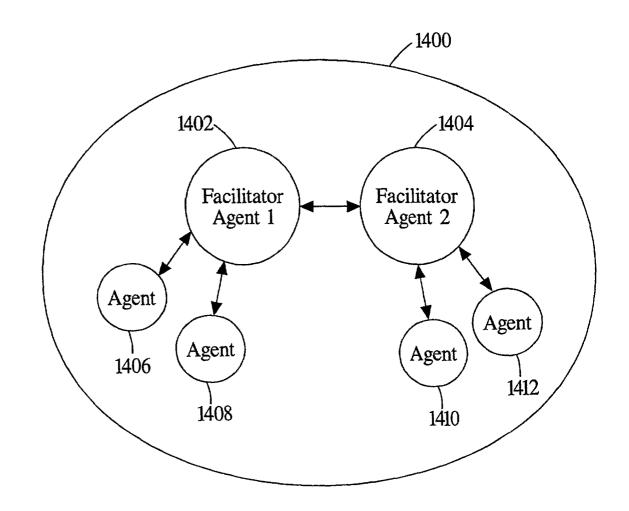
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Page 73 of 778



Page 74 of 778



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Page 75 of 778

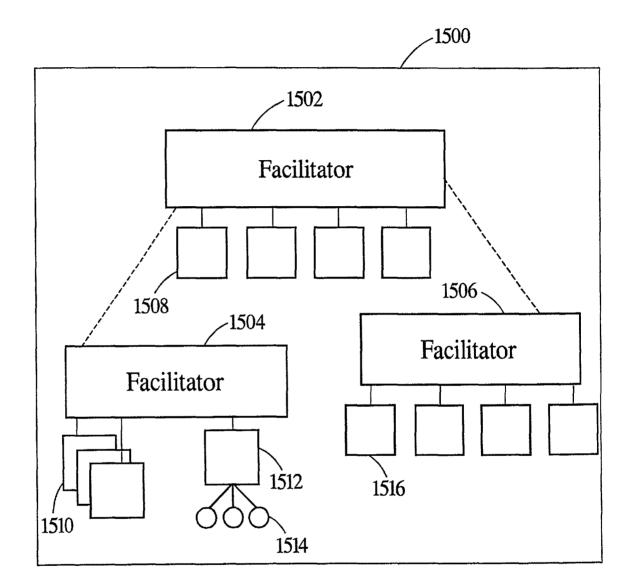


Fig. 15

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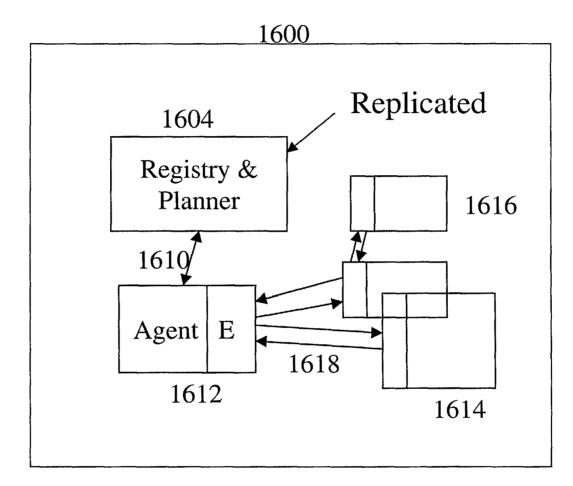


Figure 16

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Page 77 of 778



DECLARATION AND POWER OF ATTORNEY FOR ORIGINAL U.S. PATENT APPLICATION

Attorney's Docket No. _ SRI1P016

As a below-named inventor, I hereby declare that:

My residence, post office address and citizenship are as stated below next to my name.

I believe that I am the original, first and sole inventor (if only one name is listed below) or an original, first and joint inventor (if plural names are listed below) of the subject matter which is claimed and for which a patent is sought on the invention entitled: SOFTWARE-BASED ARCHITECTURE FOR COMMUNICATION AND COOPERATION AMONG DISTRIBUTED ELECTRONIC AGENTS, the specification of which is attached hereto.

I hereby state that I have reviewed and understand the contents of the above-identified specification, including the claims, as amended by any amendment referred to above.

I acknowledge the duty to disclose information which is material to the examination of this application in accordance with Title 37, CFR § 1.56.

| JC PYM Stephens & | Coleman | LLP, |
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And I hereby appoint the law firm of Hickman & Marting, including Paul L. Hickman (Reg. No. 28, 516); L. Keith Stephens (Reg. No. 32,632); Brian R. Coleman (Reg. No. 39,145); Dawn L. Palmer (Reg. No. 41,238); Jerray Wei (Reg. No. 43,247); and Ian L. Cartier (Reg. No. 38,406) as my principal attorneys to prosecute this application and to transact all business in the Patent and Trademark Office connected therewith:

Send Correspondence To:

Brian R. Coleman HICKMAN STEPHENS & COLEMAN, LLP P.O. BOX 52037 Palo Alto, California 94303-0746

Direct Telephone Calls To:

Brian R. Coleman at telephone number (650) 470-7430

I hereby declare that all statements made herein of my own knowledge are true and that all statements made on information and belief are believed to be true; and further that these statements were made with the knowledge that willful false statements and the like so made are punishable by fine or imprisonment, or both, under section 1001 of Title 18 of the United States Code, and that such willful false statements may jeopardize the validity of the application or any patent issuing thereon.

| Typewritten Full Name of | | () C A |
|--------------------------|----------------------|---------------------------|
| Sole or First Inventor: | Adam J. Cheyer | Citizenship: $(1>H)$ |
| Inventor's signature: | alem A Cheyn | Date of Signature: 1/5/99 |
| Residence: (City) | Palo Alto | (State/Country) <u>CA</u> |
| Post Office Address: | 757 Cereza Drive Pal | 0 AHO CA 94306 |
| | | |
| Typewritten Full Name of | | $L \subset \Lambda$ |
| Second Inventor: | David L. Martin | Citizenship: $U > H$ |
| Inventor's signature: | David 4. Martin | Date of Signature: 1/5/99 |
| Residence: (City) | Santa Clara | (State/Country)CA |
| Post Office Address: | 167 CRONIN DR. | Santa Clara, CA 95051 |

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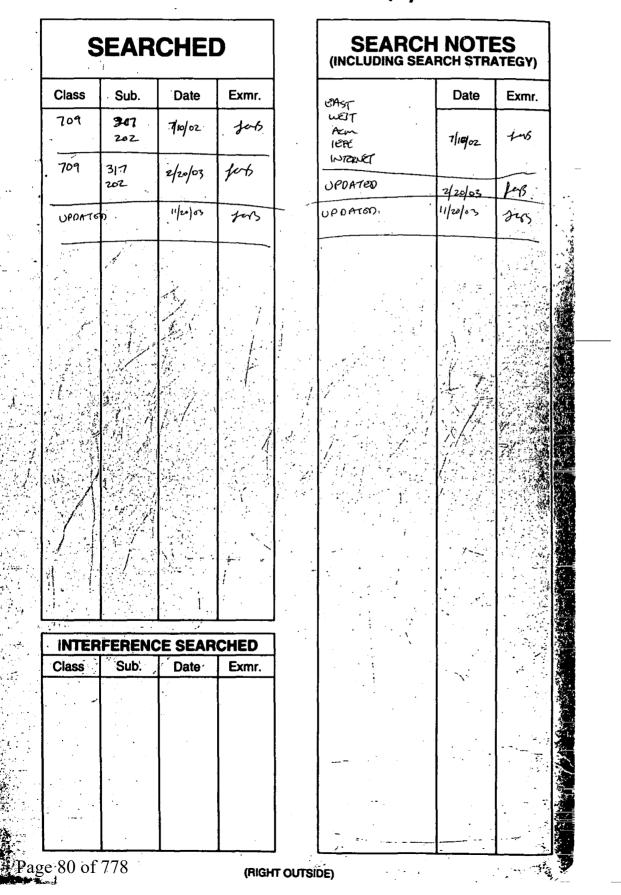
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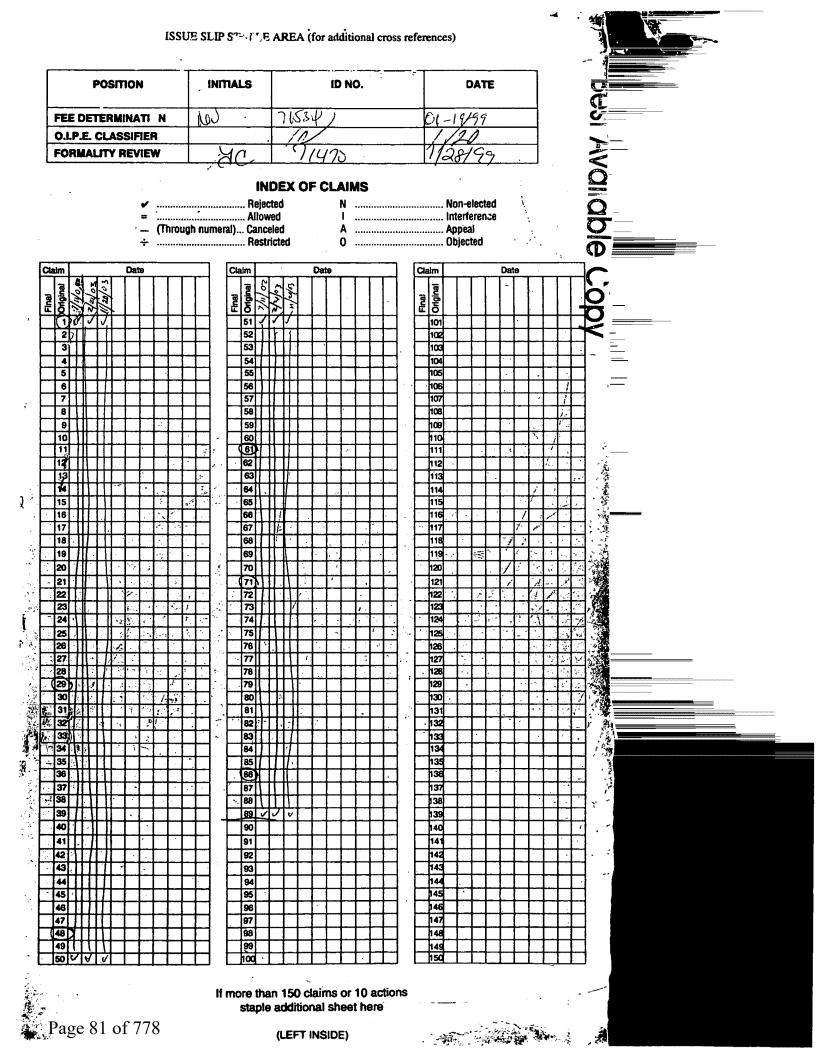
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Page 79 of 778



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IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

CERTIFICATE OF EXPRESS MAILING Attorney Docket No.: SRI1P016 I hereby certify that this paper and the documents and/or fees referred to as 57 attached therein are being deposited with the United States Postal Service First Named Inventor: on January 05, 1999 in an envelope as "Express Mail Post Office to Addressee" service under 37 CFR §1.10, Mailing Label Number EL221766053US, addressed to the Assistant Commissioner for Patents, CHEYER, Adam J. Washington, DQ 20221 21 PTO Michael L. Gough UTILITY PATENT APPLICATION TRANSMITTAL (37 CFR § 1.53(b)) Assistant Commissioner for Patents Duplicate for Box Patent Application fee processing Washington, DC 20231 Sir: This is a request for filing a patent application under 37 CFR § 1.53(b) in the name of inventors: Adam J. Cheyer and David L. Martin SOFTWARE-BASED ARCHITECTURE FOR COMMUNICATION AND COOPERATION AMONG For: DISTRIBUTED ELECTRONIC AGENTS **Application Elements:** N Ų ÷ 59 Pages of Specification, Claims and Abstract 16 Sheets of Drawings 01 Pages Combined Declaration and Power of Attorney Accompanying Application Parts: Assignment and Assignment Recordation Cover Sheet (recording fee not enclosed) **Return Receipt Postcard** Fee Calculation (37 CFR § 1.16) (Col. 1) (Col. 2) SMALL ENTITY OR LARGE ENTITY NO. FILED NO. EXTRA <u>RATE</u> FEE RATE FEE **BASIC FEE** \$395 \$ OR \$760 \$ 760.00 -20 = TOTAL CLAIMS 89 69 x11 =\$ OR $x_{18} = 1242.00 INDEP CLAIMS -03 = \$ x78 =\$234.00 06 03 x41 = OR * If the difference in Col. 1 is less Total S OR Total \$2236.00 than zero, enter "0" in Col. 2. Including filing fees and the assignment recordation fee of \$40.00, the Commissioner is authorized to charge all required fees to Deposit Account No. 50-0384 (Order No. SRI1P016). X The Commissioner is authorized to charge any fees beyond the amount enclosed which may be

(Revised 12/97, Pat App Trans 53(b) Reg

required, or to credit any overpayment, to Deposit Account No. 50-0384 (Order No. SRI1P016).

Page 82 of 778

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ũ ũ General Authorization for Petition Extension of Time (37 CFR §1.136)

Applicants hereby make and generally authorize any Petitions for Extensions of Time as may be needed for any subsequent filings. The Commissioner is also authorized to charge any extension fees under 37 CFR §1.17 as may be needed to Deposit Account No. 50-0384.

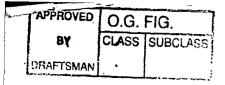
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Brian R. Coleman HICKMAN STEPHENS & COLEMAN, LLP P.O. Box 52037 Palo Alto, CA 94303-0746

> Tel (650) 470-7430 Fax (650) 470-7440

(15/99 Date:

Brian R. Coleman Registration No. 39,145







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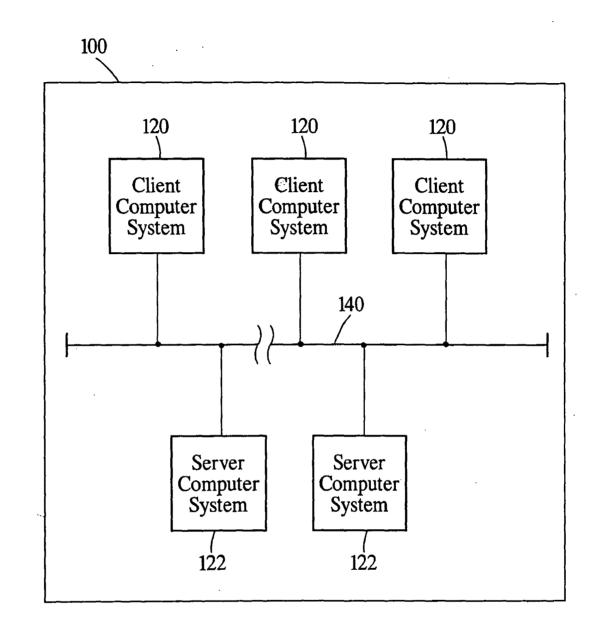


Fig. 1 (Prior Art)

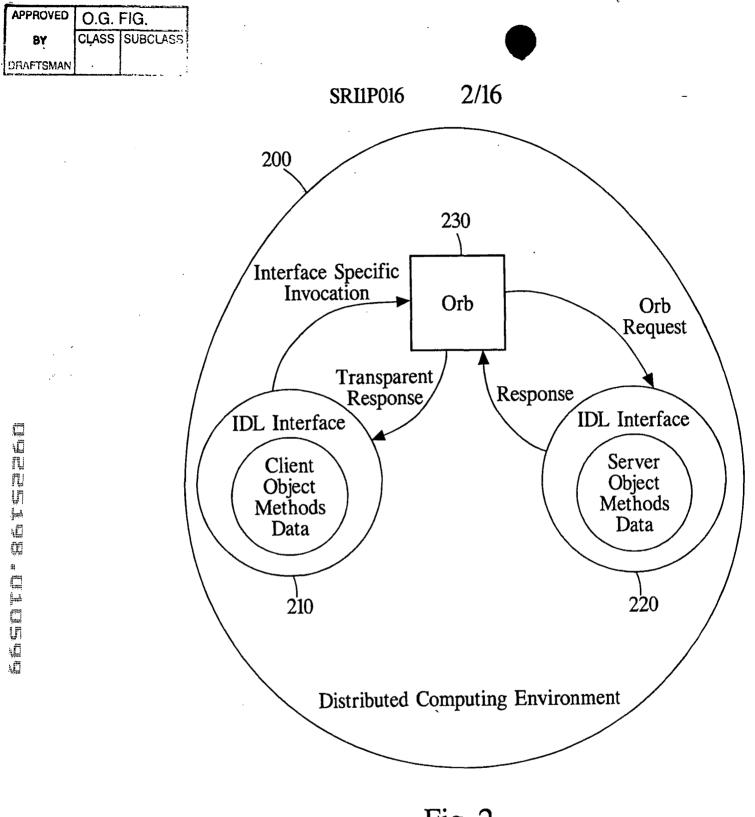


Fig. 2 (Prior Art)

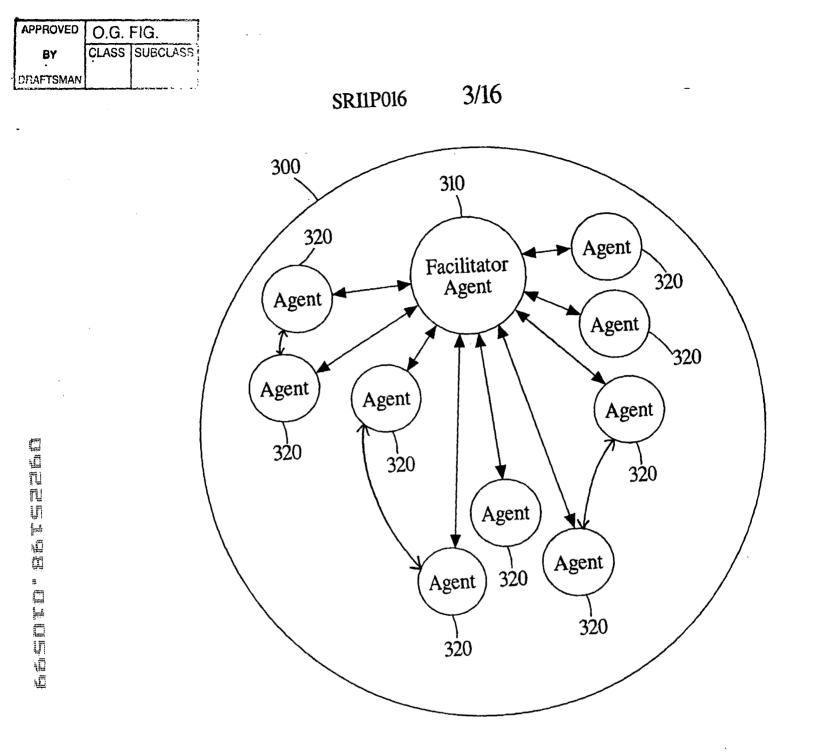


Fig. 3

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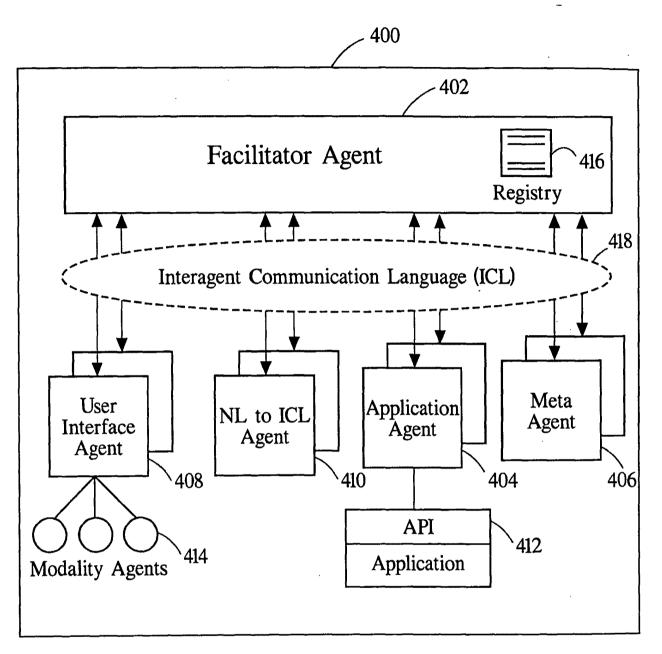
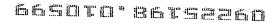
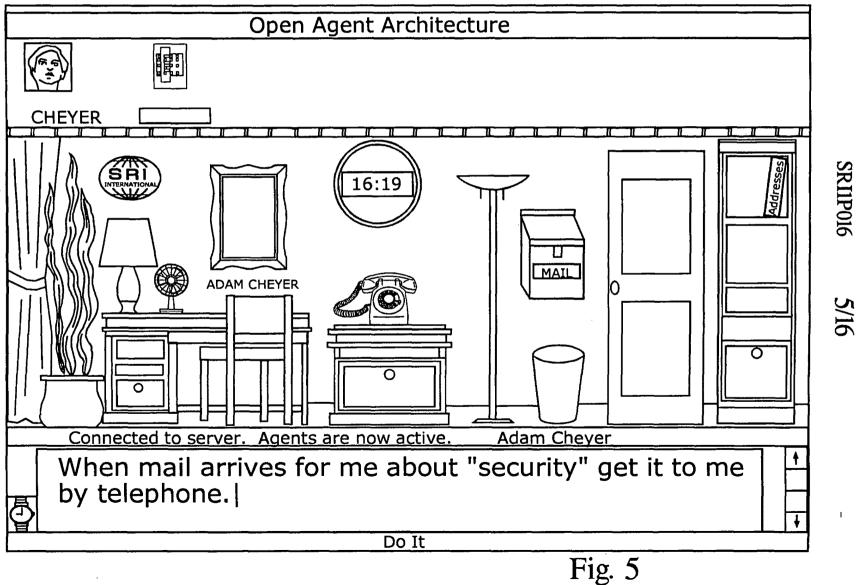


Fig. 4

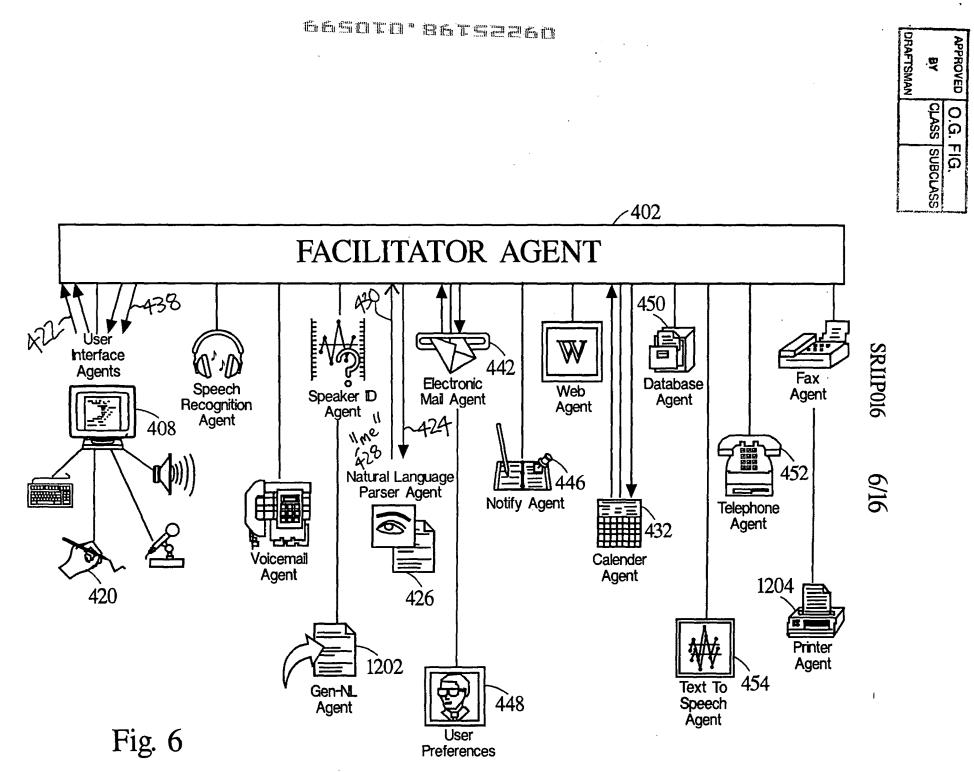




APPROVED O.G. FIG. BY CLASS SUBCLASS DRAFTSMAN

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Page 88 of 778



Page 89 of 778

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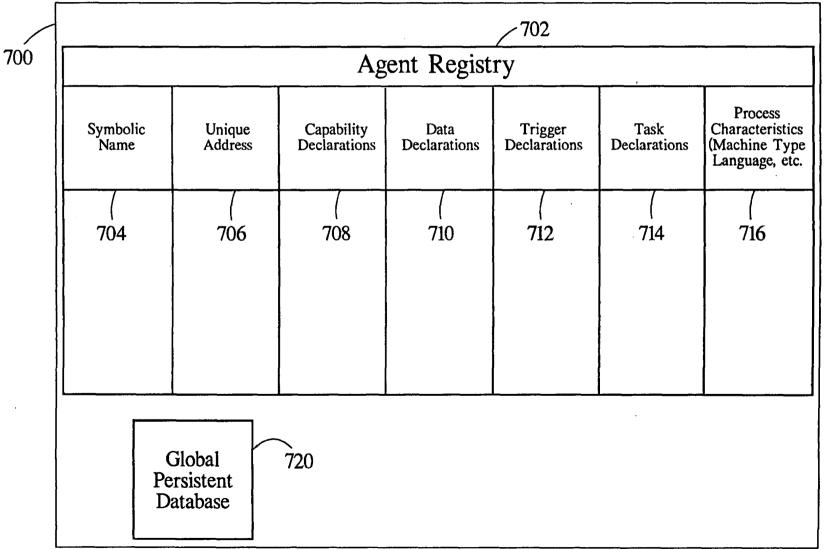
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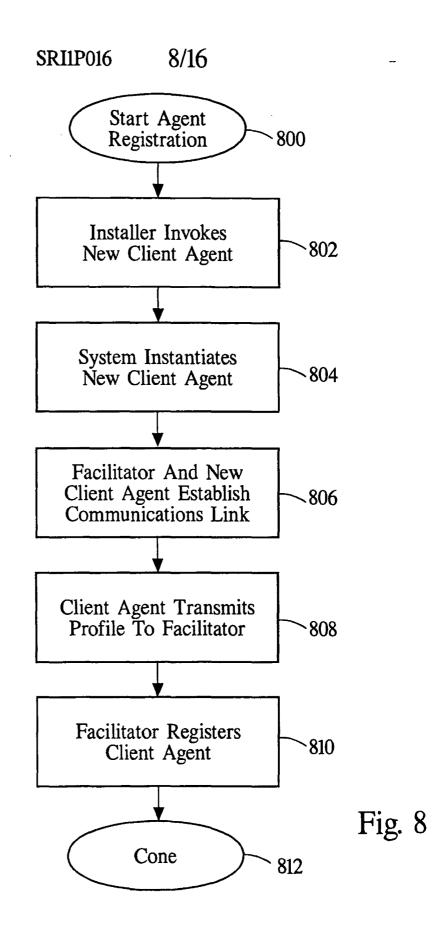
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Page 90 of 778

| APPROVED | 0.G. | FIG. |
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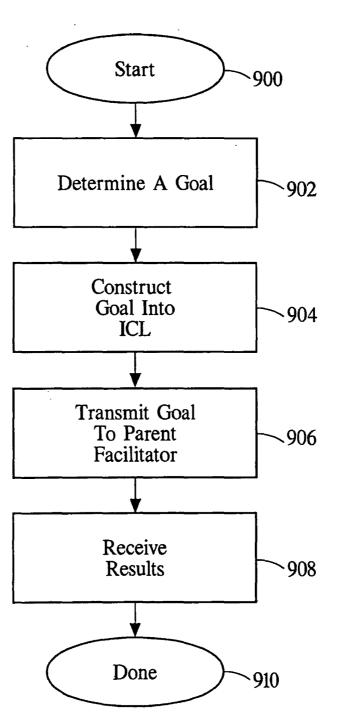
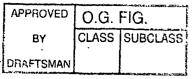
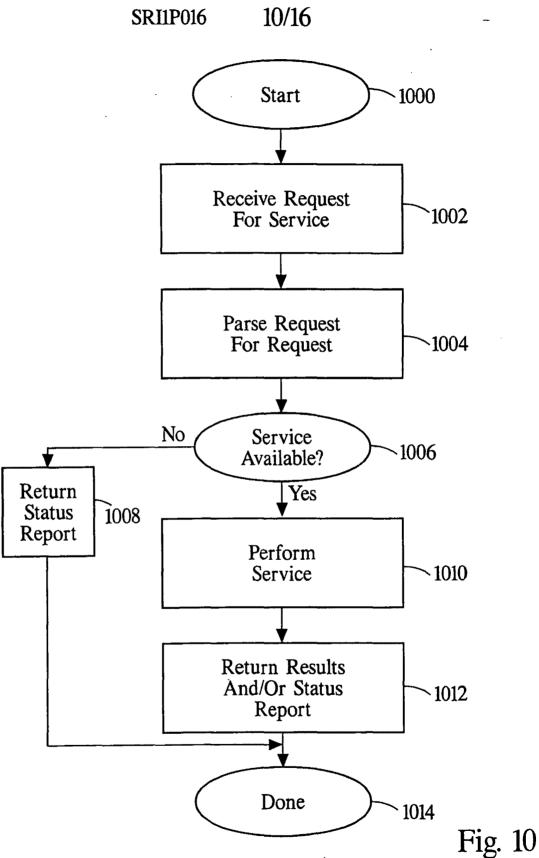
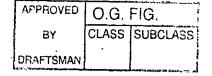


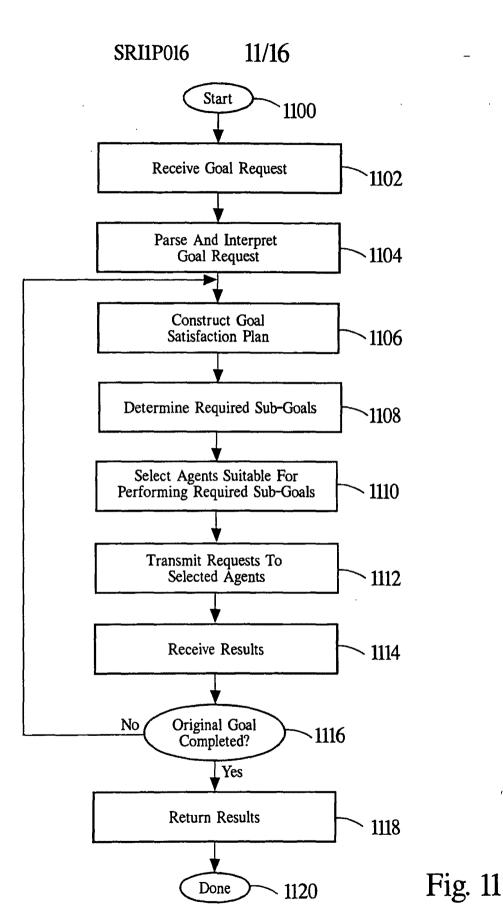
Fig. 9

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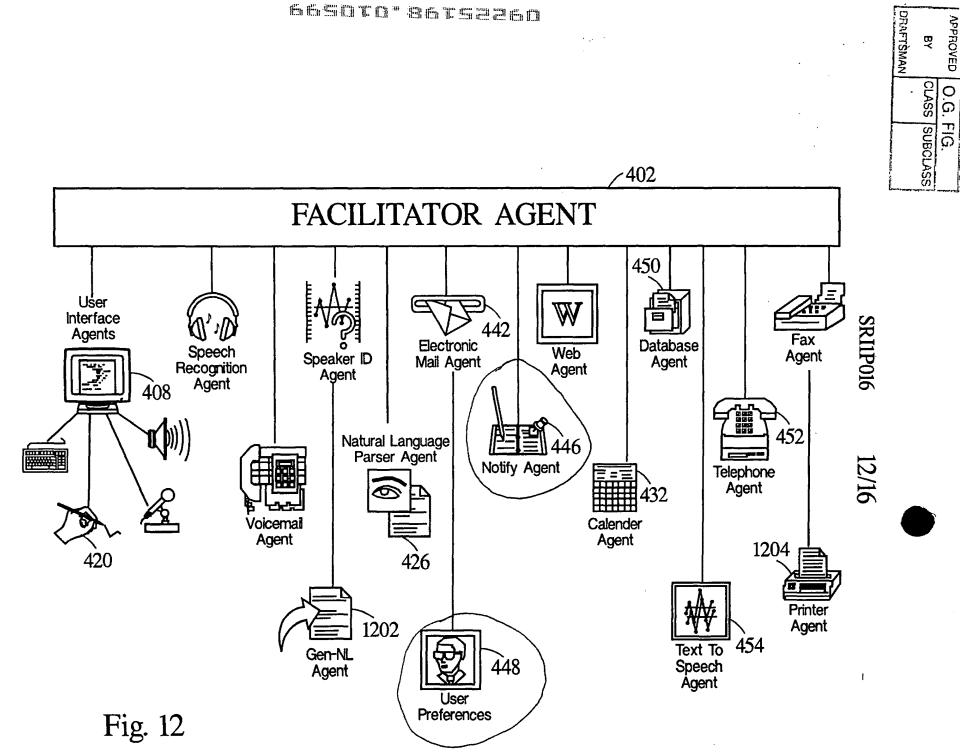




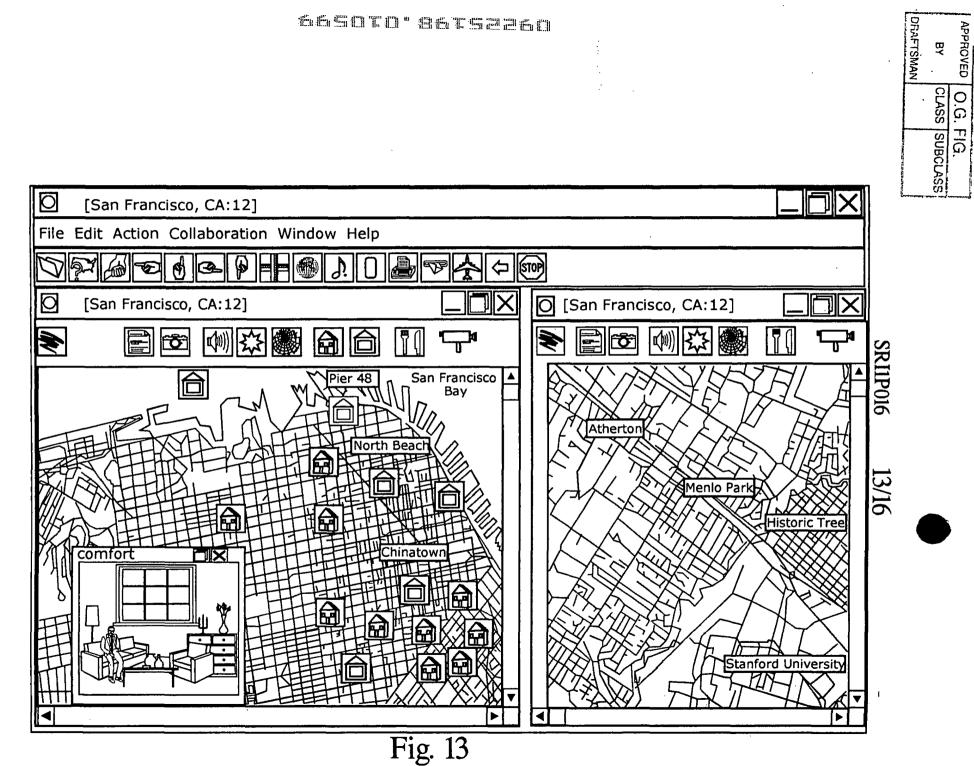


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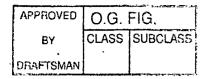
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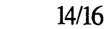
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Page 96 of 778



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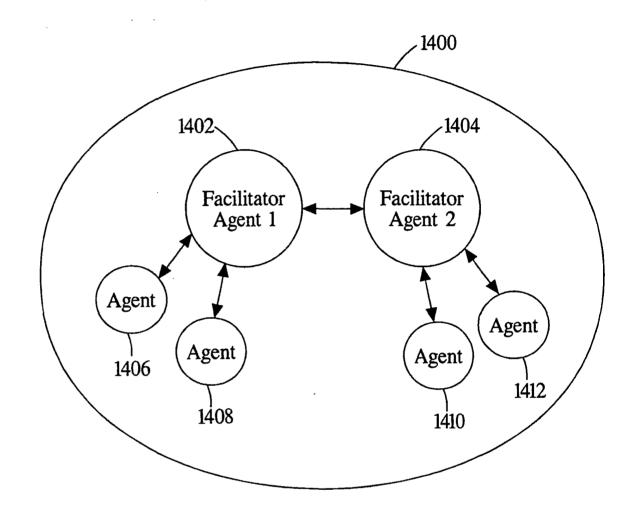


Fig. 14

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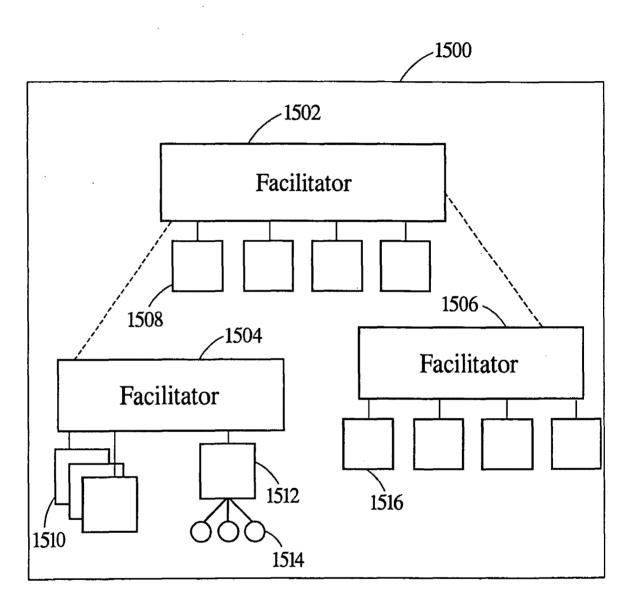
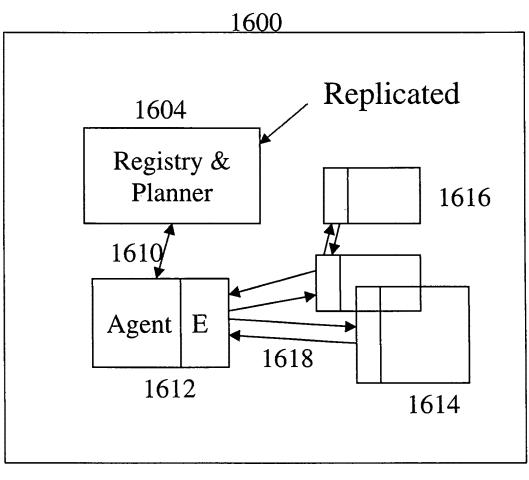


Fig. 15

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Software-Based Architecture for Communication and Cooperation Among Distributed Electronic Agents

By:

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BACKGROUND OF THE INVENTION

10 Field of the Invention

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The present invention is related to distributed computing environments and the completion of tasks within such environments. In particular, the present invention teaches a variety of software-based architectures for communication and cooperation among distributed electronic agents. Certain embodiments teach interagent communication languages enabling client agents to make requests in the form of arbitrarily complex goal expressions that are solved through facilitation by a facilitator agent.

Context and Motivation for Distributed Software Systems

- 20 The evolution of models for the design and construction of distributed software systems is being driven forward by several closely interrelated trends: the adoption of a *networked computing model*, rapidly rising expectations for *smarter*, *longer-lived*, *more autonomous software applications* and an ever increasing demand for *more accessible and intuitive user interfaces*.
 - Prior Art Figure 1 illustrates a *networked computing model* 100 having a plurality of client and server computer systems 120 and 122 coupled together over a physical transport mechanism 140. The adoption of the *networked computing model* 100 has lead to a greatly increased reliance on distributed sites for both data and processing resources. Systems such as the networked computing model 100 are based
- 30 upon at least one physical transport mechanism 140 coupling the multiple computer systems 120 and 122 to support the transfer of information between these computers. Some of these computers basically support using the network and are known as *client*

computers (clients). Some of these computers provide resources of the computers and are known as server computers (servers). The servers 122 can vary greatly in the resources they possess, access they provide and services made available to other computers across a network. Servers may service other servers as well as clients.

The Internet is a computing system based upon this network computing model. The Internet is continually growing, stimulating a paradigm shift for computing away from requiring all relevant data and programs to reside on the user's desktop machine. The data now routinely accessed from computers spread around the world has become increasingly rich in format, comprising multimedia documents, and audio and video streams. With the popularization of programming languages such as JAVA, data transported between local and remote machines may also include programs that can be downloaded and executed on the local machine. There is an ever increasing reliance on networked computing, necessitating software design approaches that allow for flexible composition of distributed processing elements in a dynamically changing and relatively unstable environment.

In an increasing variety of domains, application designers and users are coming to expect the deployment of *smarter, longer-lived, more autonomous, software applications*. Push technology, persistent monitoring of information sources, and the maintenance of user models, allowing for personalized responses and sharing of preferences, are examples of the simplest manifestations of this trend. Commercial enterprises are introducing significantly more advanced approaches, in many cases employing recent research results from artificial intelligence, data mining, machine learning, and other fields.

More than ever before, the increasing complexity of systems, the development of new technologies, and the availability of multimedia material and environments are creating a demand for *more accessible and intuitive user interfaces*. Autonomous, distributed, multi-component systems providing sophisticated services will no longer lend themselves to the familiar "direct manipulation" model of interaction, in which an individual user masters a fixed selection of commands provided by a single

30 application. Ubiquitous computing, in networked environments, has brought about a situation in which the typical user of many software services is likely to be a non-

expert, who may access a given service infrequently or only a few times.

Page 101 of Automev Docket No: SRI1P016(3477)/BRC/EWJ

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Accommodating such usage patterns calls for new approaches a ortunately, input modalities now becoming widely available, such as speech recognition and pen-based handwriting/gesture recognition, and the ability to manage the presentation of systems' responses by using multiple media provide an opportunity to fashion a style of human-computer interaction that draws much more heavily on our experience with human-human interactions.

PRIOR RELATED ART

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Existing approaches and technologies for distributed computing include 10 distributed objects, mobile objects, blackboard-style architectures, and agent-based software engineering.

The Distributed Object Approach

Object-oriented languages, such as C++ or JAVA, provide significant advances over standard procedural languages with respect to the reusability and modularity of code: encapsulation, inheritance and polymorhpism. Encapsulation 15 encourages the creation of library interfaces that minimize dependencies on underlying algorithms or data structures. Changes to programming internals can be made at a later date with requiring modifications to the code that uses the library. Inheritance permits the extension and modification of a library of routines and data 20 without requiring source code to the original library. Polymorphism allows one body of code to work on an arbitrary number of data types. For the sake of simplicity traditional objects may be seen to contain both methods and data. Methods provide the mechanisms by which the internal state of an object may be modified or by which communication may occur with another object or by which the instantiation or 25 removal of objects may be directed.

With reference to Figure 2, a distributed object technology based around an Object Request Broker will now be described. Whereas "standard" object-oriented programming (OOP) languages can be used to build monolithic programs out of many object building blocks, distributed object technologies (DOOP) allow the creation of

30 programs whose components may be spread across multiple machines. As shown in Figure 2, an object system 200 includes client objects 210 and server objects 220. To implement a client-server relationship between objects, the distributed object system 200 uses a registry mechanism (CORBA's registry is called an enject Request Broker, or ORB) 230 to store the interface descriptions of available objects. Through the services of the ORB 230, a client can transparently invoke a method on a remote server object. The ORB 230 is then responsible for finding the object 220 that can implement the request, passing it the parameters, invoking its method, and returning the results. In the most sophisticated systems, the client 210 does not have to be aware of where the object is located, its programming language, its operating system, or any

Although distributed objects offer a powerful paradigm for creating networked
applications, certain aspects of the approach are not perfectly tailored to the constantly changing environment of the Internet. A major restriction of the DOOP approach is that the interactions among objects are fixed through explicitly coded instructions by the application developer. It is often difficult to reuse an object in a new application without bringing along all its inherent dependencies on other objects
(embedded interface definitions and explicit method calls). Another restriction of the DOOP approach is the result of its reliance on a remote procedure call (RPC) style of communication. Although easy to debug, this single thread of execution model does not facilitate programming to exploit the potential for parallel computation that one would expect in a distributed environment. In addition, RPC uses a blocking

20 (synchronous) scheme that does not scale well for high-volume transactions.

other system aspects that are not part of the server object's interface.

Mobile Objects

Mobile objects, sometimes called mobile agents, are bits of code that can move to another execution site (presumably on a different machine) under their own programmatic control, where they can then interact with the local environment. For

- 25 certain types of problems, the mobile object paradigm offers advantages over more traditional distributed object approaches. These advantages include network bandwidth and parallelism. Network bandwidth advantages exist for some database queries or electronic commerce applications, where it is more efficient to perform tests on data by bringing the tests to the data than by bringing large amounts of data to
- 30 the testing program. Parallelism advantages include situations in which mobile agents can be spawned in parallel to accomplish many tasks at once.

Some of the disadvantages and inconveniences of the incolle agent approach include the programmatic specificity of the agent interactions, lack of coordination support between participant agents and execution environment irregularities regarding specific programming languages supported by host processors upon which agents

- 5 reside. In a fashion similar to that of DOOP programming, an agent developer must programmatically specify where to go and how to interact with the target environment. There is generally little coordination support to encourage interactions among multiple (mobile) participants. Agents must be written in the programming language supported by the execution environment, whereas many other distributed 10 technologies support heterogeneous communities of components, written in diverse
- programming languages.

Blackboard Architectures

Blackboard architectures typically allow multiple processes to communicate by reading and writing tuples from a global data store. Each process can watch for
items of interest, perform computations based on the state of the blackboard, and then add partial results or queries that other processes can consider. Blackboard architectures provide a flexible framework for problem solving by a dynamic community of distributed processes. A blackboard architecture provides one solution to eliminating the tightly bound interaction links that some of the other distributed
technologies require during interprocess communication. This advantage can also be a disadvantage: although a programmer does not need to refer to a specific process during computation, the framework does not provide programmatic control for doing

Agent-based Software Engineering

so in cases where this would be practical.

- 25 Several research communities have approached distributed computing by casting it as a problem of modeling communication and cooperation among autonomous entities, or agents. Effective communication among independent agents requires four components: (1) a transport mechanism carrying messages in an asynchronous fashion, (2) an interaction protocol defining various types of
- 30 communication interchange and their social implications (for instance, a response is expected of a question), (3) a content language permitting the expression and interpretation of utterances, and (4) an agreed-upon set of shared vocabulary and

Page 104 of 778 mey Docket No: SRI1P016(3477)/BRC/EWJ

meaning for concepts (often called an *ontology*). Such mechanisms permit a much richer style of interaction among participants than can be expressed using a distributed object's RPC model or a blackboard architecture's centralized exchange approach.

Agent-based systems have shown much promise for flexible, fault-tolerant, distributed problem solving. Several agent-based projects have helped to evolve the notion of facilitation. However, existing agent-based technologies and architectures are typically very limited in the extent to which agents can specify complex goals or influence the strategies used by the facilitator. Further, such prior systems are not sufficiently attuned to the importance of integrating human agents (i.e., users) through natural language and other human-oriented user interface technologies.

The initial version of SRI International's Open Agent ArchitectureTM ("*OAA*[@]") technology provided only a very limited mechanism for dealing with compound goals. Fixed formats were available for specifying a flat list of either conjoined (AND) sub-goals or disjoined (OR) sub-goals; in both cases, parallel goal solving was hard-wired in, and only a single set of parameters for the entire list could be specified. More complex goal expressions involving (for example) combinations of different boolean connectors, nested expressions, or conditionally interdependent ("IF .. THEN") goals were not supported. Further, system scalability was not adequately addressed in this prior work.

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SUMMARY OF INVENTION

A first embodiment of the present invention discloses a highly flexible, software-based architecture for constructing distributed systems. The architecture supports cooperative task completion by flexible, dynamic configurations of autonomous electronic agents. Communication and cooperation between agents are brokered by one or more facilitators, which are responsible for matching requests, from users and agents, with descriptions of the capabilities of other agents. It is not generally required that a user or agent know the identities, locations, or number of

30 other agents involved in satisfying a request, and relatively minimal effort is involved in incorporating new agents and "wrapping" legacy applications. Extreme flexibility is achieved through an architecture organized around the declaration of capabilities by service-providing agents, the construction of arbitrarily complex goals by users and service-requesting agents, and the role of facilitators in delegating and coordinating the satisfaction of these goals, subject to advice and constraints that may accompany them. Additional mechanisms and features include facilities for creating and

5 maintaining shared repositories of data; the use of triggers to instantiate commitments within and between agents; agent-based provision of multi-modal user interfaces, including natural language; and built-in support for including the user as a privileged member of the agent community. Specific embodiments providing enhanced scalability are also described.

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BRIEF DESCRIPTION OF THE DRAWINGS

Prior Art

Prior Art FIGURE 1 depicts a networked computing model;

Prior Art FIGURE 2 depicts a distributed object technology based around an Object Resource Broker;

Examples of the Invention

FIGURE 3 depicts a distributed agent system based around a facilitator agent;

FIGURE 4 presents a structure typical of one small system of the present 20 invention;

FIGURE 5 depicts an Automated Office system implemented in accordance with an example embodiment of the present invention supporting a mobile user with a laptop computer and a telephone;

FIGURE 6 schematically depicts an Automated Office system implemented as
 a network of agents in accordance with a preferred embodiment of the present invention;

FIGURE 7 schematically shows data structures internal to a facilitator in accordance with a preferred embodiment of the present invention;

FIGURE 8 depicts operations involved in instantiating a client agent with its parent facilitator in accordance with a preferred embodiment of the present invention; FIGURE 9 depicts operations involved in a client agent mutiating a service request and receiving the response to that service request in accordance with a certain preferred embodiment of the present invention;

FIGURE 10 depicts operations involved in a client agent responding to a
service request in accordance with another preferable embodiment of the present invention;

FIGURE 11 depicts operations involved in a facilitator agent response to a service request in accordance with a preferred embodiment of the present invention;

FIGURE 12 depicts an Open Agent Architecture[™] based system of agents
implementing a unified messaging application in accordance with a preferred embodiment of the present invention;

FIGURE 13 depicts a map oriented graphical user interface display as might be displayed by a multi-modal map application in accordance with a preferred embodiment of the present invention;

FIGURE 14 depicts a peer to peer multiple facilitator based agent system supporting distributed agents in accordance with a preferred embodiment of the present invention;

FIGURE 15 depicts a multiple facilitator agent system supporting at least a limited form of a hierarchy of facilitators in accordance with a preferred embodiment of the present invention; and

FIGURE 16 depicts a replicated facilitator architecture in accordance with one embodiment of the present invention.

BRIEF DESCRIPTION OF THE APPENDICES

25 The Appendices provide source code for an embodiment of the present invention written in the PROLOG programming language.

APPENDIX A: Source code file named compound.pl.

APPENDIX B: Source code file named fac.pl.

APPENDIX C: Source code file named libcom_tcp.pl.

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APPENDIX D: Source code file named liboaa.pr.

APPENDIX E: Source code file named translations.pl.

DETAILED DESCRIPTION OF THE INVENTION

Figure 3 illustrates a distributed agent system 300 in accordance with one embodiment of the present invention. The agent system 300 includes a facilitator agent 310 and a plurality of agents 320. The illustration of Figure 3 provides a high level view of one simple system structure contemplated by the present invention. The facilitator agent 310 is in essence the "parent" facilitator for its "children" agents 320. The agents 320 forward service requests to the facilitator agent 310. The facilitator agent 310 interprets these requests, organizing a set of goals which are then delegated to appropriate agents for task completion.

The system 300 of Figure 3 can be expanded upon and modified in a variety of ways consistent with the present invention. For example, the agent system 300 can be distributed across a computer network such as that illustrated in Figure 1. The facilitator agent 310 may itself have its functionality distributed across several different computing platforms. The agents 320 may engage in interagent communication (also called peer to peer communications). Several different systems 300 may be coupled together for enhanced performance. These and a variety of other structural configurations are described below in greater detail.

Figure 4 presents the structure typical of a small system 400 in one
embodiment of the present invention, showing user interface agents 408, several
application agents 404 and meta-agents 406, the system 400 organized as a
community of peers by their common relationship to a facilitator agent 402. As will
be appreciated, Figure 4 places more structure upon the system 400 than shown in
Figure 3, but both are valid representations of structures of the present invention. The
facilitator 402 is a specialized server agent that is responsible for coordinating agent
communications and cooperative problem-solving. The facilitator 402 may also
provide a global data store for its client agents, allowing them to adopt a blackboard
style of interaction. Note that certain advantages are found in utilizing two or more

facilitator agents within the system 400. For example, larger systems can be assembled from multiple facilitator/client groups, each having the sort of structure

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shown in Figure 4. An agents that are not facilitators are referred to herein generically as *client* agents -- so called because each acts (in some respects) as a client of some facilitator, which provides communication and other essential services for the client.

5 The variety of possible client agents is essentially unlimited. Some typical categories of client agents would include application agents 404, meta-agents 406, and user interface agents 408, as depicted in Figure 4. Application agents 404 denote specialists that provide a collection of services of a particular sort. These services could be domain-independent technologies (such as speech recognition, natural 10 language processing 410, email, and some forms of data retrieval and data mining) or user-specific or domain-specific (such as a travel planning and reservations agent). Application agents may be based on legacy applications or libraries, in which case the agent may be little more than a wrapper that calls a pre-existing API 412, for example. Meta-agents 406 are agents whose role is to assist the facilitator agent 402 in coordinating the activities of other agents. While the facilitator 402 possesses 15 domain-independent coordination strategies, meta-agents 406 can augment these by using domain- and application-specific knowledge or reasoning (including but not limited to rules, learning algorithms and planning).

With further reference to Figure 4, user interface agents 408 can play an
extremely important and interesting role in certain embodiments of the present invention. By way of explanation, in some systems, a user interface agent can be implemented as a collection of "micro-agents", each monitoring a different input modality (point-and-click, handwriting, pen gestures, speech), and collaborating to produce the best interpretation of the current inputs. These micro-agents are depicted in Figure 4, for example, as Modality Agents 414. While describing such subcategories of client agents is useful for purposes of illustration and understanding, they need not be formally distinguished within the system in preferred implementations of the present invention.

The operation of one preferred embodiment of the present invention will be discussed in greater detail below, but may be briefly outlined as follows. When invoked, a client agent makes a connection to a facilitator, which is known as its *parent facilitator*. These connections are depicted as a double headed arrow between

Page 109 of Zu&nev Docket No: SRI1P016(3477)/BRC/EWJ

the client agent and the racilitator agent in Figure 3 and 4, for example. Upon connection, an agent registers with its parent facilitator a specification of the capabilities and services it can provide. For example, a natural language agent may register the characteristics of its available natural language vocabulary. (For more

- 5 details regarding client agent connections, see the discussion of Figure 8 below.) Later during task completion, when a facilitator determines that the registered services 416 of one of its client agents will help satisfy a goal, the facilitator sends that client a request expressed in the Interagent Communication Language (*ICL*) 418. (See Figure 11 below for a more detailed discussion of the facilitator operations involved.) The
- agent parses this request, processes it, and returns answers or status reports to the facilitator. In processing a request, the client agent can make use of a variety of infrastructure capabilities provided in the preferred embodiment. For example, the client agent can use *ICL* 418 to request services of other agents, set triggers, and read or write shared data on the facilitator or other client agents that maintain shared data.
 (See the discussion of Figures 9-11 below for a more detailed discussion of request
- processing.)

The functionality of each client agent are made available to the agent community through registration of the client agent's capabilities with a facilitator 402. A software "wrapper" essentially surrounds the underlying application program performing the services offered by each client. The common infrastructure for constructing agents is preferably supplied by an *agent library*. The agent library is preferably accessible in the runtime environment of several different programming languages. The agent library preferably minimizes the effort required to construct a new system and maximizes the ease with which legacy systems can be "wrapped" and made compatible with the agent-based architecture of the present invention.

By way of further illustration, a representative application is now briefly presented with reference to Figures 5 and 6. In the Automated Office system depicted in Figure 5, a mobile user with a telephone and a laptop computer can access and task commercial applications such as calendars, databases, and email systems running back at the office. A user interface (UI) agent 408, shown in Figure 6, runs on the

30 back at the office. A user interface (UI) agent 408, shown in Figure 6, runs on the user's local laptop and is responsible for accepting user input, sending requests to the facilitator 402 for delegation to appropriate agents, and displaying the results of the distributed computation. The user may interact directly with a specific remote application by clicking on active areas in the interface, calling up a form or window for that application, and making queries with standard interface dialog mechanisms. Conversely, a user may express a task to be executed by using typed, handwritten, or spoken (over the telephone) English sentences, without explicitly specifying which agent or agents should perform the task.

For instance, if the question "What is my schedule?" is written 420 in the user interface 408, this request will be sent 422 by the UI 408 to the facilitator 402, which in turn will ask 424 a natural language (NL) agent 426 to translate the query into *ICL*10 18. To accomplish this task, the NL agent 426 may itself need to make requests of the agent community to resolve unknown words such as "me" 428 (the UI agent 408 can respond 430 with the name of the current user) or "schedule" 432 (the calendar agent 434 defines this word 436). The resulting *ICL* expression is then routed by the facilitator 402 to appropriate agents (in this case, the calendar agent 434) to execute the request. Results are sent back 438 to the UI agent 408 for display.

The spoken request "When mail arrives for me about security, notify me immediately." produces a slightly more complex example involving communication among all agents in the system. After translation into ICL as described above, the facilitator installs a trigger 440 on the mail agent 442 to look for new messages about 20 security. When one such message does arrive in its mail spool, the trigger fires, and the facilitator matches the action part of the trigger to capabilities published by the notification agent 446. The notification agent 446 is a meta-agent, as it makes use of rules concerning the optimal use of different output modalities (email, fax, speech generation over the telephone) plus information about an individual user's preferences 448 to determine the best way of relaying a message through available media transfer 25 application agents. After some competitive parallelism to locate the user (the calendar agent 434 and database agent 450 may have different guesses as to where to find the user) and some cooperative parallelism to produce required information (telephone number of location, user password, and an audio file containing a text-to-

30 speech representation of the email message), a telephone agent 452 calls the user, verifying its identity through touchtones, and then play the message.

The above example illustrates a number of inventive features. As new agents connect to the facilitator, registering capability specifications and natural language vocabulary, what the user can say and do dynamically changes; in other words, the ICL is dynamically *expandable*. For example, adding a calendar agent to the system

- 5 in the previous example and registering its capabilities enables users to ask natural language questions about their "schedule" without any need to revise code for the facilitator, the natural language agents, or any other client agents. In addition, the interpretation and execution of a task is a distributed process, with no single agent defining the set of possible inputs to the system. Further, a single request can produce
- 10 cooperation and flexible communication among many agents, written in different programming languages and spread across multiple machines.

Design Philosophy and Considerations

One preferred embodiment provides an integration mechanism for heterogeneous applications in a distributed infrastructure, incorporating some of the dynamism and extensibility of blackboard approaches, the efficiency associated with mobile objects, plus the rich and complex interactions of communicating agents. Design goals for preferred embodiments of the present invention may be categorized under the general headings of *interoperation and cooperation, user interfaces*, and *software engineering*. These design goals are not absolute requirements, nor will they necessarily be satisfied by all embodiments of the present invention, but rather simply reflect the inventor's currently preferred design philosophy.

Versatile mechanisms of interoperation and cooperation

- Interoperation refers to the ability of distributed software components agents - to communicate meaningfully. While every system-building framework must provide mechanisms of interoperation at some level of granularity, agent-based frameworks face important new challenges in this area. This is true primarily because autonomy, the hallmark of *individual* agents, necessitates greater flexibility in interactions within *communities* of agents. *Coordination* refers to the mechanisms by
- 30 which a community of agents is able to work together productively on some task. In these areas, the goals for our framework are to *provide flexibility in assembling*

communities of autonomous service providers, provide flexibility in structuring cooperative interactions, impose the right amount of structure, as well as include legacy and "owned-elsewhere" applications.

Provide flexibility in assembling communities of autonomous service providers
-- both at development time and at runtime. Agents that conform to the linguistic and ontological requirements for effective communication should be able to participate in an agent community, in various combinations, with minimal or near minimal prerequisite knowledge of the characteristics of the other players. Agents with duplicate and overlapping capabilities should be able to coexist within the same
community, with the system making optimal or near optimal use of the redundancy.

Provide flexibility in structuring cooperative interactions among the members of a community of agents. A framework preferably provides an economical mechanism for setting up a variety of interaction patterns among agents, without requiring an inordinate amount of complexity or infrastructure within the individual agents. The provision of a service should be independent or minimally dependent upon a particular configuration of agents.

Impose the right amount of structure on individual agents. Different
approaches to the construction of multi-agent systems impose different requirements
on the individual agents. For example, because KQML is neutral as to the content of
messages, it imposes minimal structural requirements on individual agents. On the
other hand, the BDI paradigm tends to impose much more demanding requirements,
by making assumptions about the nature of the programming elements that are
meaningful to individual agents. Preferred embodiments of the present invention
should fall somewhere between the two, providing a rich set of interoperation and
coordination capabilities, without precluding any of the software engineering goals
defined below.

Include legacy and "owned-elsewhere" applications. Whereas legacy usually implies reuse of an established system fully controlled by the agent-based system developer, owned-elsewhere refers to applications to which the developer has partial access, but no control. Examples of owned-elsewhere applications include data

sources and services available on the World Wide Web, via simple form-based

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interfaces, and applications used cooperatively within a virtual enterprise, which remain the properties of separate corporate entities. Both classes of application must preferably be able to interoperate, more or less as full-fledged members of the agent community, without requiring an overwhelming integration effort.

5 Human-oriented user interfaces

Systems composed of multiple distributed components, and possibly dynamic configurations of components, require the crafting of intuitive user interfaces to provide conceptually natural interaction mechanisms, treat users as privileged members of the agent community and support collaboration.

10 Provide conceptually natural interaction mechanisms with multiple distributed components. When there are numerous disparate agents, and/or complex tasks implemented by the system, the user should be able to express requests without having detailed knowledge of the individual agents. With speech recognition, handwriting recognition, and natural language technologies becoming more mature, 15 agent architectures should preferably support these forms of input playing increased roles in the tasking of agent communities.

Preferably treat *users as privileged members* of the agent community by providing an appropriate level of task specification within *software* agents, and reusable translation mechanisms between this level and the level of *human* requests, supporting constructs that seamlessly incorporate interactions between both humaninterface and software types of agents.

Preferably support *collaboration* (simultaneous work over shared data and processing resources) between users and agents.

Realistic software engineering requirements

- 25 System-building frameworks should preferably address the practical concerns of real-world applications by the specification of requirements which preferably include: *Minimize the effort* required to create new agents, and to wrap existing applications. *Encourage reuse*, both of domain-independent and domain-specific components. The concept of *agent orientation*, like that of object orientation, provides
- 30 a natural conceptual framework for reuse, so long as mechanisms for encapsulation

and interaction are structured appropriately. Support lightweight, mobile platforms. Such platforms should be able to serve as hosts for agents, without requiring the installation of a massive environment. It should also be possible to construct individual agents that are relatively small and modest in their processing

5 requirements. *Minimize platform and language barriers*. Creation of new agents, as well as wrapping of existing applications, should not require the adoption of a new language or environment.

Mechanisms of Cooperation

Cooperation among agents in accordance with the present invention is preferably achieved via messages expressed in a common language, *ICL*. Cooperation among agent is further preferably structured around a three-part approach: providers of services register capabilities specifications with a facilitator, requesters of services construct goals and relay them to a facilitator, and facilitators coordinate the efforts of the appropriate service providers in satisfying these goals.

15 The Interagent Communication Language (ICL)

Interagent Communication Language ("ICL") 418 refers to an interface, communication, and task coordination language preferably shared by all agents, regardless of what platform they run on or what computer language they are programmed in. ICL may be used by an agent to task itself or some subset of the agent community. Preferably, ICL allows agents to specify explicit control parameters while simultaneously supporting expression of goals in an underspecified, loosely constrained manner. In a further preferred embodiment, agents employ ICL to perform queries, execute actions, exchange information, set triggers, and manipulate data in the agent community.

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In a further preferred embodiment, a program element expressed in *ICL* is the *event*. The activities of every agent, as well as communications between agents, are preferably structured around the transmission and handling of events. In communications, events preferably serve as messages between agents; in regulating the activities of individual agents, they may preferably be thought of as goals to be

30 satisfied. Each event preferably has a type, a set of parameters, and content. For example, the agent library procedure *oaa_Solve* can be used by an agent to request

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Page 115 of Attomey Docket No: SRI1P016(3477)/BRC/EWJ

services of other agents. A call to oaa_Solve, within the code or agent A, results in an event having the form

ev_post_solve(Goal, Params)

going from A to the facilitator, where ev_post_solve is the type, Goal is the content, and *Params* is a list of parameters. The allowable content and parameters preferably vary according to the type of the event.

The *ICL* preferably includes a layer of conversational protocol and a content layer. The conversational layer of ICL is defined by the event types, together with the parameter lists associated with certain of these event types. The content layer consists of the specific goals, triggers, and data elements that may be embedded within various events.

The *ICL* conversational protocol is preferably specified using an orthogonal, parameterized approach, where the conversational aspects of each element of an interagent conversation are represented by a selection of an event type and a selection of values from at least one orthogonal set of parameters. This approach offers greater 15 expressiveness than an approach based solely on a fixed selection of *speech acts*, such as embodied in KQML. For example, in KQML, a request to satisfy a query can employ either of the performatives ask_all or ask_one. In ICL, on the other hand, this type of request preferably is expressed by the event type ev_post_solve, together with the solution_limit(N) parameter - where N can be any positive integer. (A request for 20 all solutions is indicated by the omission of the *solution_limit* parameter.) The request can also be accompanied by other parameters, which combine to further refine its semantics. In KQML, then, this example forces one to choose between two possible conversational options, neither of which may be precisely what is desired. In either

25 case, the performative chosen is a single value that must capture the entire conversational characterization of the communication. This requirement raises a difficult challenge for the language designer, to select a set of performatives that provides the desired functionality without becoming unmanageably large. Consequently, the debate over the right set of performatives has consumed much discussion within the KQML community.

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The content layer of the *ICL* preferably supports unification and other features found in logic programming language environments such as PROLOG. In some

Page 116 of Atto hey Docket No: SR11P016(3477)/BRC/EWJ

Page 17 of 59

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embodiments, the content layer of the ICL is simply an extension of at least one programming language. For example, the Applicants have found that PROLOG is suitable for implementing and extending into the content layer of the ICL. The agent libraries preferably provide support for constructing, parsing, and manipulating ICL expressions. It is possible to embed content expressed in other languages within an *ICL* event. However, expressing content in *ICL* simplifies the facilitator's access to the content, as well as the conversational layer, in delegating requests. This gives the facilitator more information about the nature of a request and helps the facilitator decompose compound requests and delegate the sub-requests.

10 Further, ICL expressions preferably include, in addition to events, at least one of the following: capabilities declarations, requests for services, responses to requests, trigger specifications, and shared data elements. A further preferred embodiment of the present invention incorporates ICL expressions including at least all of the following: events, capabilities declarations, requests for services, responses to requests, trigger specifications, and shared data elements.

Providing Services: Specifying "Solvables"

In a preferred embodiment of the present invention, every participating agent defines and publishes a set of capability declarations, expressed in ICL, describing the services that it provides. These declarations establish a high-level interface to the agent. This interface is used by a facilitator in communicating with the agent, and, 20 most important, in delegating service requests (or parts of requests) to the agent. Partly due to the use of PROLOG as a preferred basis for ICL, these capability declarations are referred as *solvables*. The agent library preferably provides a set of procedures allowing an agent to add, remove, and modify its solvables, which it may preferably do at any time after connecting to its facilitator. 25

There are preferably at least two major types of solvables: *procedure* solvables and *data* solvables. Intuitively, a procedure solvable performs a test or action, whereas a data solvable provides access to a collection of data. For example, in creating an agent for a mail system, procedure solvables might be defined for sending

a message to a person, testing whether a message about a particular subject has 30 arrived in the mail queue, or displaying a particular message onscreen. For a database

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wrapper agent, one might define a distinct data solvable corresponding to each of the relations present in the database. Often, a data solvable is used to provide a *shared* data store, which may be not only queried, but also updated, by various agents having the required permissions.

There are several primary technical differences between these two types of solvables. First, each procedure solvable must have a handler declared and defined for it, whereas this is preferably not necessary for a data solvable. The handling of requests for a data solvable is preferably provided transparently by the agent library. Second, data solvables are preferably associated with a dynamic collection of facts (or clauses), which may be further preferably modified at runtime, both by the agent providing the solvable, and by other agents (provided they have the required permissions). Third, special features, available for use with data solvables, preferably facilitate maintaining the associated facts. In spite of these differences, it should be noted that the mechanism of *use* by which an agent requests a service is the same for the two types of solvables.

In one embodiment, a request for one of an agent's services normally arrives in the form of an event from the agent's facilitator. The appropriate handler then deals with this event. The handler may be coded in whatever fashion is most appropriate, depending on the nature of the task, and the availability of task-specific libraries or legacy code, if any. The only hard requirement is that the handler return an appropriate response to the request, expressed in *ICL*. Depending on the nature of the request, this response could be an indication of success or failure, or a list of solutions (when the request is a data query).

A solvable preferably has three parts: a *goal*, a list of *parameters*, and a list of *permissions*, which are declared using the format:

solvable(Goal, Parameters, Permissions)

The goal of a solvable, which syntactically takes the preferable form of an *ICL* structure, is a logical representation of the service provided by the solvable. (An *ICL* structure consists of a *functor* with 0 or more arguments. For example, in the structure

30 a(b,c), `a' is the functor, and `b' and `c' the arguments.) As with a PROLOG structure, the goal's arguments themselves may preferably be structures.

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Various options can be included in the parameter list, to refine the semantics associated with the solvable. The *type* parameter is preferably used to say whether the solvable is *data* or *procedure*. When the type is *procedure*, another parameter may be used to indicate the handler to be associated with the solvable. Some of the

5 parameters appropriate for a *data* solvable are mentioned elsewhere in this application. In either case (procedure or data solvable), the *private* parameter may be preferably used to restrict the use of a solvable to the declaring agent when the agent intends the solvable to be solely for its internal use but wishes to take advantage of the mechanisms in accordance with the present invention to access it, or when the agent

10 wants the solvable to be available to outside agents only at selected times. In support of the latter case, it is preferable for the agent to change the status of a solvable from private to non-private at any time.

The permissions of a solvable provide mechanisms by which an agent may preferably control access to its services allowing the agent to restrict calling and writing of a solvable to itself and/or other selected agents. (*Calling* means requesting the service encapsulated by a solvable, whereas *writing* means modifying the collection of facts associated with a data solvable.) The default permission for every solvable in a further preferred embodiment of the present invention is to be callable by anyone, and for data solvables to be writable by anyone. A solvable's permissions can preferably be changed at any time, by the agent providing the solvable.

For example, the solvables of a simple email agent might include:

| | | <pre>solvable(send_message(email, +ToPerson, +Params),</pre> |
|----|-------|--|
| | | <pre>[type(procedure), callback(send_mail)],</pre> |
| | | |
| 25 | | <pre>solvable(last_message(email, -MessageId),</pre> |
| | | <pre>[type(data), single_value(true)],</pre> |
| | | [write(true)]), |
| | | <pre>solvable(get_message(email, +MessageId, -</pre> |
| | Msg), | |
| 20 | Mag/, | <pre>[type(procedure), callback(get_mail)],</pre> |
| 30 | | [type(procedure), callback(get_mail)], |
| | | []) |

The symbols `+' and `-', indicating input and output arguments, are at present used only for purposes of documentation. Most parameters and permissions have default values, and specifications of default values may be omitted from the

35 parameters and permissions lists.

Defining an agent's capabilities in terms of solvable declarations effectively creates a vocabulary with which other agents can communicate with the new agent. Ensuring that agents will speak the same language and share a common, unambiguous semantics of the vocabulary involves *ontology*. Agent development tools and services (automatic translations of solvables by the facilitator) help address this issue; additionally, a preferred embodiment of the present invention will typically rely on vocabulary from either formally engineered ontologies for specific domains or from ontologies constructed during the incremental development of a body of agents for several applications or from both specific domain ontologies and incrementally developed ontologies. Several example tools and services are described in Cheyer et al.'s paper entitled "Development Tools for the Open Agent Architecture," as presented at the Practical Application of Intelligent Agents and Multi-Agent Technology (PAAM 96), London, April 1996.

Although the present invention imposes no hard restrictions on the form of solvable declarations, two common usage conventions illustrate some of the utility associated with solvables.

Classes of services are often preferably tagged by a particular type. For instance, in the example above, the "last_message" and "get_message" solvables are specialized for email, not by modifying the *names* of the services, but rather by the use of the `email' parameter, which serves during the execution of an *ICL* request to select (or not) a specific type of message.

Actions are generally written using an imperative verb as the functor of the solvable in a preferred embodiment of the present invention, the direct object (or item class) as the first argument of the predicate, required arguments following, and then an extensible parameter list as the last argument. The parameter list can hold optional information usable by the function. The *ICL* expression generated by a natural language parser often makes use of this parameter list to store prepositional phrases and adjectives.

As an illustration of the above two points, "Send mail to Bob about lunch" will be translated into an *ICL* request send_message(email, `Bob Jones', [subject(lunch)]), whereas "Remind Bob about lunch" would leave the transport unspecified

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(send message(KIND, Bob Jones', [subject(lunch)])), enabling an available message transfer agents (e.g., fax, phone, mail, pager) to compete for the opportunity to carry out the request.

Requesting Services

5 An agent preferably requests services of the community of agent by delegating tasks or goals to its facilitator. Each request preferably contains calls to one or more agent solvables, and optionally specifies parameters containing advice to help the facilitator determine how to execute the task. Calling a solvable preferably does not require that the agent specify (or even know of) a particular agent or agents to handle

- the call. While it is possible to specify one or more agents using an address parameter 10 (and there are situations in which this is desirable), in general it is advantageous to leave this delegation to the facilitator. This greatly reduces the hard-coded component dependencies often found in other distributed frameworks. The agent libraries of a preferred embodiment of the present invention provide an agent with a
- single, unified point of entry for requesting services of other agents: the library 15 procedure *oaa* Solve. In the style of logic programming, *oaa_Solve* may preferably be used both to retrieve data and to initiate actions, so that calling a *data* solvable looks the same as calling a *procedure* solvable.

Complex Goal Expressions

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A powerful feature provided by preferred embodiments of the present invention is the ability of a client agent (or a user) to submit compound goals of an arbitrarily complex nature to a facilitator. A compound goal is a single goal expression that specifies multiple sub-goals to be performed. In speaking of a "complex goal expression" we mean that a single goal expression that expresses multiple sub-goals can potentially include more than one type of logical connector 25 (e.g., AND, OR, NOT), and/or more than one level of logical nesting (e.g., use of parentheses), or the substantive equivalent. By way of further clarification, we note that when speaking of an "arbitrarily complex goal expression" we mean that goals are expressed in a language or syntax that allows expression of such complex goals

when appropriate or when desired, not that every goal is itself necessarily complex. 30

It is contemplated that this ability is provided through an interagent communication language having the necessary syntax and semantics. In one example, the goals may take the form of compound goal expressions composed using operators similar to those employed by PROLOG, that is, the comma for conjunction, the

semicolon for disjunction, the arrow for conditional execution, etc. The present invention also contemplates significant extensions to PROLOG syntax and semantics. For example, one embodiment incorporates a "parallel disjunction" operator indicating that the disjuncts are to be executed by different agents concurrently. A further embodiment supports the specification of whether a given sub-goal is to be executed breadth-first or depth-first.

A further embodiment supports each sub-goal of a compound goal optionally having an address and/or a set of parameters attached to it. Thus, each sub-goal takes the form

Address:Goal::Parameters

15 where both *Address* and *Parameters* are optional.

An address, if present, preferably specifies one or more agents to handle the given goal, and may employ several different types of referring expression: unique names, symbolic names, and shorthand names. Every agent has preferably a unique name, assigned by its facilitator, which relies upon network addressing schemes to ensure its global uniqueness. Preferably, agents also have self-selected symbolic names (for example, "mail"), which are not guaranteed to be unique. When an address includes a symbolic name, the facilitator preferably takes this to mean that all agents having that name should be called upon. Shorthand names include `self' and `parent' (which refers to the agent's facilitator). The address associated with a goal or sub-goal is preferably always optional. When an address is not present, it is the facilitator's job to supply an appropriate address.

The distributed execution of compound goals becomes particularly powerful when used in conjunction with natural language or speech-enabled interfaces, as the query itself may specify how functionality from distinct agents will be combined. As

30 a simple example, the spoken utterance "Fax it to Bill Smith's manager." can be translated into the following compound *ICL* request:

oaa_Solve((manager('Bill Smith', M), fax(it,M,[])), [strategy(action)])

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Page 122 of Augmev Docket No: SRI1P016(3477)/BRC/EWJ

Note that in this ICL request there are two sub-goals, "manager('Bill Smith',M)" and "fax(it,M,[])," and a single global parameter "strategy(action)." According to the present invention, the facilitator is capable of mapping global parameters in order to apply the constraints or advice across the separate sub-goals in a meaningful way. In this instance, the global parameter strategy(action) implies a parallel constraint upon the first sub-goal; i.e., when there are multiple agents that can respond to the manager sub-goal, each agent should receive a request for service. In contrast, for the second sub-goal, parallelism should not be inferred from the global parameter strategy(action) because such an inference would possibly result in the transmission of duplicate facsimiles.

Refining Service Requests

In a preferred embodiment of the present invention, parameters associated with a goal (or sub-goal) can draw on useful features to refine the request's meaning. For example, it is frequently preferred to be able to specify whether or not solutions are to be returned synchronously; this is done using the *reply* parameter, which can take any of the values *synchronous, asynchronous*, or *none*. As another example, when the goal is a non-compound query of a data solvable, the *cache* parameter may preferably be used to request local caching of the facts associated with that solvable. Many of the remaining parameters fall into two categories: feedback and advice.

20 *Feedback parameters* allow a service requester to receive information from the facilitator about how a goal was handled. This feedback can include such things as the identities of the agents involved in satisfying the goal, and the amount of time expended in the satisfaction of the goal.

- Advice parameters preferably give constraints or guidance to the facilitator in completing and interpreting the goal. For example, a *solution_limit* parameter preferably allows the requester to say how many solutions it is interested in; the facilitator and/or service providers are free to use this information in optimizing their efforts. Similarly, a *time_limit* is preferably used to say how long the requester is willing to wait for solutions to its request, and, in a multiple facilitator system, a
- 30 *level_limit* may preferably be used to say how remote the facilitators may be that are consulted in the search for solutions. A *priority* parameter is preferably used to

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indicate that a request is more urgent than previous requests that have not yet been satisfied. Other preferred advice parameters include but are not limited to parameters used to tell the facilitator whether parallel satisfaction of the parts of a goal is appropriate, how to combine and filter results arriving from multiple solver agents, and whether the requester itself may be considered a candidate solver of the sub-goals of a request.

Advice parameters preferably provide an extensible set of low-level, orthogonal parameters capable of combining with the *ICL* goal language to fully express how information should flow among participants. In certain preferred embodiments of the present invention, multiple parameters can be grouped together and given a group name. The resulting *high-level advice parameters* can preferably be used to express concepts analogous to KQML's performatives, as well as define classifications of problem types. For instance, KQML's "ask_all" and "ask_one" performatives would be represented as combinations of values given to the parameters

15 reply, parallel_ok, and solution_limit. As an example of a higher-level problem type, the strategy "math_problem" might preferably send the query to all appropriate math solvers in parallel, collect their responses, and signal a conflict if different answers are returned. The strategy "essay_question" might preferably send the request to all appropriate participants, and signal a problem (i.e., cheating) if any of the returned 20 answers are identical.

Facilitation

In a preferred embodiment of the present invention, when a facilitator receives a compound goal, its job is to construct a goal satisfaction plan and oversee its satisfaction in an optimal or near optimal manner that is consistent with the specified advice. The facilitator of the present invention maintains a knowledge base that records the capabilities of a collection of agents, and uses that knowledge to assist requesters and providers of services in making contact.

Figure 7 schematically shows data structures 700 internal to a facilitator in accordance with one embodiment of the present invention. Consider the function of a

30 Agent Registry 702 in the present invention. Each registered agent may be seen as associated with a collection of fields found within its parent facilitator such as shown in the figure. Each registered agent may optionally possess a Symbolic Name which

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would be entered into neld 704. As mentioned elsewhere, Symoolic Names need not be unique to each instance of an agent. Note that an agent may in certain preferred embodiments of the present invention possess more than one Symbolic Name. Such Symbolic Names would each be found through their associations in the Agent

5 Registry entries. Each agent, when registered, must possess a Unique Address, which is entered into the Unique Address field 706.

With further reference to Figure 7, each registered agent may be optionally associated with one or more capabilities, which have associated Capability Declaration fields 708 in the parent facilitator Agent Registry 702. These capabilities may define not just functionality, but may further provide a utility parameter 10 indicating, in some manner (e.g., speed, accuracy, etc), how effective the agent is at providing the declared capability. Each registered agent may be optionally associated with one or more data components, which have associated Data Declaration fields 710 in the parent facilitator Agent Registry 702. Each registered agent may be optionally associated with one or more triggers, which preferably could be referenced through 15 their associated Trigger Declaration fields 712 in the parent facilitator Agent Registry 702. Each registered agent may be optionally associated with one or more tasks, which preferably could be referenced through their associated Task Declaration fields 714 in the parent facilitator Agent Registry 702. Each registered agent may be optionally associated with one or more Process Characteristics, which preferably 20 could be referenced through their associated Process Characteristics Declaration fields 716 in the parent facilitator Agent Registry 702. Note that these characteristics in certain preferred embodiments of the present invention may include one or more of the following: Machine Type (specifying what type of computer may run the agent),

25 Language (both computer and human interface).

A facilitator agent in certain preferred embodiments of the present invention further includes a Global Persistent Database 720. The database 720 is composed of data elements which do not rely upon the invocation or instantiation of client agents for those data elements to persist. Examples of data elements which might be present in such a database include but are not limited to the network address of the facilitator agent's server, facilitator agent's server accessible network port list, firewalls, user

lists, and security operans regarding the access of server resources accessible to the facilitator agent.

A simplified walk through of operations involved in creating a client agent, a client agent initiating a service request, a client agent responding to a service request and a facilitator agent responding to a service request are including hereafter by way of illustrating the use of such a system. These figures and their accompanying discussion are provided by way of illustration of one preferred embodiment of the present invention and are not intended to limit the scope of the present invention.

Figure 8 depicts operations involved in instantiating a client agent with its parent facilitator in accordance with a preferred embodiment of the present invention. The operations begin with starting the Agent Registration in a step 800. In a next step 802, the Installer, such as a client or facilitator agent, invokes a new client agent. It will be appreciated that any computer entity is capable of invoking a new agent. The system then instantiates the new client agent in a step 804. This operation may

involve resource allocations somewhere in the network on a local computer system for the client agent, which will often include memory as well as placement of references to the newly instantiated client agent in internal system lists of agents within that local computing system. Once instantiated, the new client and its parent facilitator establish a communications link in a step 806. In certain preferred
embodiments, this communications link involves selection of one or more physical transport mechanisms for this communication. Once established, the client agent transmits it profile to the parent facilitator in a step 808. When received, the parent facilitator registers the client agent in a step 810. Then, at a step 812, a client agent has been instantiated in accordance with one preferred embodiment of the present

Figure 9 depicts operations involved in a client agent initiating a service request and receiving the response to that service request in accordance with a preferred embodiment of the present invention. The method of Figure 9 begins in a step 900, wherein any initialization or other such procedures may be performed.

30 Then, in a step 902, the client agent determines a goal to be achieved (or solved). This goal is then translated in a step 904 into *ICL*, if it is not already formulated in it. The goal, now stated in *ICL*, is then transmitted to the client agent's parent facilitator in a step 906. The parent facilitator responds to this service request and at a later time, the client agent receives the results of the request in a step 908, operations of Figure 9 being complete in a done step 910.

FIGURE 10 depicts operations involved in a client agent responding to a service request in accordance with a preferred embodiment of the present invention. 5 Once started in a step 1000, the client agent receives the service request in a step 1002. In a next step 1004, the client agent parses the received request from ICL. The client agent then determines if the service is available in a step 1006. If it is not, the client agent returns a status report to that effect in a step 1008. If the service is available, control is passed to a step 1010 where the client performs the requested 10 service. Note that in completing step 1010 the client may form complex goal expressions, requesting results for these solvables from the facilitator agent. For example, a fax agent might fax a document to a certain person only after requesting and receiving a fax number for that person. Subsequently, the client agent either returns the results of the service and/or a status report in a step 1012. The operations 15 of Figure 10 are complete in a done step 1014.

FIGURE 11 depicts operations involved in a facilitator agent response to a service request in accordance with a preferred embodiment of the present invention. The start of such operations in step 1100 leads to the reception of a goal request in a
step 1102 by the facilitator. This request is then parsed and interpreted by the facilitator in a step 1104. The facilitator then proceeds to construct a goal satisfaction plan in a next step 1106. In steps 1108 and 1110, respectively, the facilitator determines the required sub-goals and then selects agents suitable for performing the required sub-goals. The facilitator then transmits the sub-goal requests to the selected agents in a step 1112 and receives the results of these transmitted requests in a step 1114. It should be noted that the actual implementation of steps 1112 and 1114 are dependent upon the specific goal satisfaction plan. For instance, certain sub-goals may be sent to separate agents in parallel, while transmission of other sub-goals may be postponed until receipt of particular answers. Further, certain requests may

30 generate multiple responses that generate additional sub-goals. Once the responses have been received, the facilitator determines whether the original requested goal has been completed in a step 1118. If the original requested goal has not been completed,

Page 127 of Attomey Docket No: SRI1P016(3477)/BRC/EWJ

the facilitator recursively repeats the operations 1106 through 116. Once the original requested goal is completed, the facilitator returns the results to the requesting agent 1118 and the operations are done at 1120.

- A further preferred embodiment of the present invention incorporates *transparent delegation*, which means that a requesting agent can generate a request, and a facilitator can manage the satisfaction of that request, without the requester needing to have any knowledge of the identities or locations of the satisfying agents. In some cases, such as when the request is a data query, the requesting agent may also be oblivious to the *number* of agents involved in satisfying a request. Transparent
- 10 delegation is possible because agents' capabilities (solvables) are treated as an abstract description of a service, rather than as an entry point into a library or body of code.

A further preferred embodiment of the present invention incorporates facilitator handling of compound goals, preferably involving three types of processing: delegation, optimization and interpretation.

15 Delegation processing preferably supports facilitator determination of which specific agents will execute a compound goal and how such a compound goal's subgoals will be combined and the sub-goal results routed. Delegation involves selective application of global and local constraint and advice parameters onto the specific subgoals. Delegation results in a goal that is unambiguous as to its meaning and as to the agents that will participate in satisfying it.

Optimization processing of the completed goal preferably includes the facilitator using sub-goal parallelization where appropriate. *Optimization* results in a goal whose interpretation will require as few exchanges as possible, between the facilitator and the satisfying agents, and can exploit parallel efforts of the satisfying agents, wherever this does not affect the goal's meaning.

Interpretation processing of the optimized goal. Completing the addressing of a goal involves the selection of one or more agents to handle each of its sub-goals (that is, each sub-goal for which this selection has not been specified by the requester). In doing this, the facilitator uses its knowledge of the capabilities of its

30 client agents (and possibly of other facilitators, in a multi-facilitator system). It may also use strategies or advice specified by the requester, as explained below. The

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Page 128 of 778 Docket No: SRI1P016(3477)/BRC/EWJ

interpretation of a goar involves the coordination of requests is the satisfying agents, and assembling their responses into a coherent whole, for return to the requester.

A further preferred embodiment of present invention extends facilitation so the facilitator can employ strategies and advice given by the requesting agent, resulting in a variety of interaction patterns that may be instantiated in the satisfaction of a request.

A further preferred embodiment of present invention handles the distribution of both data update requests and requests for installation of triggers, preferably using some of the same strategies that are employed in the delegation of service requests.

Note that the reliance on facilitation is not absolute; that is, there is no hard requirement that requests and services be matched up by the facilitator, or that interagent communications go through the facilitator. There is preferably support in the agent library for explicit addressing of requests. However, a preferred embodiment of the present invention encourages employment the paradigm of agent communities, minimizing their development effort, by taking advantage of the facilitator's provision of transparent delegation and handling of compound goals.

A facilitator is preferably viewed as a *coordinator*, not a controller, of cooperative task completion. A facilitator preferably never initiates an activity. A facilitator preferably responds to requests to manage the satisfaction of some goal, the update of some data repository, or the installation of a trigger by the appropriate agent or agents. All agents can preferably take advantage of the facilitator's expertise in delegation, and its up-to-date knowledge about the current membership of a dynamic community. The facilitator's coordination services often allows the developer to lessen the complexity of individual agents, resulting in a more manageable software

development process, and enabling the creation of lightweight agents.

Maintaining Data Repositories

The agent library supports the creation, maintenance, and use of databases, in the form of data solvables. Creation of a data solvable requires only that it be declared. Querying a data solvable, as with access to any solvable, is done using

30 oaa_Solve.

A data solvable is conceptually similar to a relation in a relational database. The facts associated with each solvable are maintained by the agent library, which also handles incoming messages containing queries of data solvables. The default behavior of an agent library in managing these facts may preferably be refined, using parameters specified with the solvable's declaration. For example, the parameter *single_value* preferably indicates that the solvable should only contain a single fact at any given point in time. The parameter *unique_values* preferably indicates that no duplicate values should be stored.

Other parameters preferably allow data solvables use of the concepts of ownership and persistence. For implementing shared repositories, it is often preferable to maintain a record of which agent created each fact of a data solvable with the creating agent being preferably considered the fact's owner. In many applications, it is preferable to remove an agent's facts when that agent goes offline (for instance, when the agent is no longer participating in the agent community, whether by deliberate termination or by malfunction). When a data solvable is declared to be non-persistent, its facts are automatically maintained in this way, whereas a persistent data solvable preferably retains its facts until they are explicitly removed.

A further preferred embodiment of present invention supports an agent library through procedures by which agents can update (add, remove, and replace) facts belonging to data solvables, either locally or on other agents, given that they have preferably the required permissions. These procedures may preferably be refined using many of the same parameters that apply to service requests. For example, the *address* parameter preferably specifies one or more particular agents to which the update request applies. In its absence, just as with service requests, the update request preferably goes to *all* agents providing the relevant data solvable. This default behavior can be used to maintain coordinated "mirror" copies of a data set within multiple agents, and can be useful in support of distributed, collaborative activities.

Similarly, the *feedback* parameters, described in connection with *oaa_Solve*, are preferably available for use with data maintenance requests.

Page 130 of Atlaney Docket No: SRI1P016(3477)/BRC/EWJ

A further preferred embodiment of present invention supports ability to provide data solvables not just to client agents, but also to facilitator agents. Data solvables can preferably created, maintained and used by a facilitator. The facilitator preferably can, at the request of a client of the facilitator, create, maintain and share

5 the use of data solvables with all the facilitator's clients. This can be useful with relatively stable collections of agents, where the facilitator's workload is predictable.

Using a Blackboard Style of Communication

In a further preferred embodiment of present invention, when a data solvable is publicly readable and writable, it acts essentially as a global data repository and can be used cooperatively by a group of agents. In combination with the use of triggers, this allows the agents to organize their efforts around a "blackboard" style of communication.

As an example, the "DCG-NL" agent (one of several existing natural language processing agents), provides natural language processing services for a variety of its peer agents, expects those other agents to record, on the facilitator, the vocabulary to which they are prepared to respond, with an indication of each word's part of speech, and of the logical form (*ICL* sub-goal) that should result from the use of that word. In a further preferred embodiment of present invention, the NL agent, preferably when it comes online, preferably installs a data solvable for each basic part of speech on its facilitator. For instance, one such solvable would be:

solvable(noun(Meaning, Syntax), [], [])

Note that the empty lists for the solvable's permissions and parameters are acceptable here, since the default permissions and parameters provide appropriate functionality.

A further preferred embodiment of present invention incorporating an Office Assistant system as discussed herein or similar to the discussion here supports several agents making use of these or similar services. For instance, the database agent uses the following call, to library procedure *oaa_AddData*, to post the noun `boss', and to indicate that the "meaning" of boss is the concept `manager':

30 oaa_AddData(noun(manager, atom(boss)), [address(parent)])

Autonomous Monitoring with Triggers

A further preferred embodiment of present invention includes support for triggers, providing a general mechanism for requesting some action be taken when a set of conditions is met. Each agent can preferably install triggers either locally, for itself, or remotely, on its facilitator or peer agents. There are preferably at least four types of triggers: communication, data, task, and time. In addition to a type, each trigger preferably specifies at least a condition and an action, both preferably expressed in ICL. The condition indicates under what circumstances the trigger should fire, and the action indicates what should happen when it fires. In addition, each trigger can be set to fire either an unlimited number of times, or a specified number of times, which can be any positive integer.

Triggers can be used in a variety of ways within preferred embodiments of the present invention. For example, triggers can be used for monitoring external sensors in the execution environment, tracking the progress of complex tasks, or coordinating communications between agents that are essential for the synchronization of related 15 tasks. The installation of a trigger within an agent can be thought of as a representation of that agent's *commitment* to carry out the specified action, whenever the specified condition holds true.

Communication triggers preferably allow any incoming or outgoing event 20 (message) to be monitored. For instance, a simple communication trigger may say something like: "Whenever a solution to a goal is returned from the facilitator, send the result to the presentation manager to be displayed to the user."

Data triggers preferably monitor the state of a data repository (which can be maintained on a facilitator or a client agent). Data triggers' conditions may be tested 25 upon the addition, removal, or replacement of a fact belonging to a data solvable. An example data trigger is: "When 15 users are simultaneously logged on to a machine, send an alert message to the system administrator."

Task triggers preferably contain conditions that are tested after the processing of each incoming event and whenever a timeout occurs in the event polling. These conditions may specify any goal executable by the local ICL interpreter, and most often are used to test when some solvable becomes satisfiable. Task triggers are

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useful in checking for task-specific internal conditions. Although in many cases such conditions are captured by solvables, in other cases they may not be. For example, a mail agent might watch for new incoming mail, or an airline database agent may monitor which flights will arrive later than scheduled. An example task trigger is: "When mail arrives for me about security, notify me immediately."

Time triggers preferably monitor time conditions. For instance, an alarm trigger can be set to fire at a single fixed point in time (e.g., "On December 23rd at 3pm"), or on a recurring basis (e.g., "Every three minutes from now until noon").

Triggers are preferably implemented as data solvables, declared implicitly for every agent. When requesting that a trigger be installed, an agent may use many of the same parameters that apply to service and data maintenance requests.

A further preferred embodiment of present invention incorporates semantic support, in contrast with most programming methodologies, of the agent on which the trigger is installed only having to know how to evaluate the conditional part of the 15 trigger, not the consequence. When the trigger fires, the action is delegated to the facilitator for execution. Whereas many commercial mail programs allow rules of the form "When mail arrives about XXX, [forward it, delete it, archive it]", the possible actions are hard-coded and the user must select from a fixed set.

A further preferred embodiment of present invention, the consequence of a trigger may be any compound goal executable by the dynamic community of agents. Since new agents preferably define both functionality and vocabulary, when an unanticipated agent (for example, a fax agent) joins the community, no modifications to existing code is required for a user to make use of it - "When mail arrives, fax it to Bill Smith."

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The Agent Library

In a preferred embodiment of present invention, the agent library provides the infrastructure for constructing an agent-based system. The essential elements of protocol (involving the details of the messages that encapsulate a service request and

its response) are preferably made transparent to simplify the programmingapplications. This enables the developer to focus functionality, rather than message

Dyerction af the solution

construction details any communication details. For example, to request a service of another agent, an agent preferably calls the library procedure *oaa_Solve*. This call results in a message to a facilitator, which will exchange messages with one or more service providers, and then send a message containing the desired results to the

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None of the messages involved in this scenario is explicitly constructed by the agent developer. Note that this describes the *synchronous* use of *oaa_Solve*.

requesting agent. These results are returned via one of the arguments of *oaa Solve*.

In another preferred embodiment of present invention, an agent library provides both *intra*agent and *inter*agent infrastructure; that is, mechanisms supporting the internal structure of individual agents, on the one hand, and mechanisms of cooperative interoperation between agents, on the other. Note that most of the infrastructure cuts across this boundary with many of the same mechanisms supporting both agent internals and agent interactions in an integrated fashion. For example, services provided by an agent preferably can be accessed by that agent through the same procedure (*oaa_Solve*) that it would employ to request a service of another agent (the only difference being in the *address* parameter accompanying the request). This helps the developer to reuse code and avoid redundant entry points into the same functionality.

Both of the preferred characteristics described above (transparent construction of messages and integration of *intra*agent with *inter*agent mechanisms) apply to most other library functionality as well, including but not limited to data management and temporal control mechanisms.

Source Code Appendix

Source code for version 2.0 of the OAA software product is included as an appendix hereto, and is incorporated herein by reference. The code includes an agent library, which provides infrastructure for constructing an agent-based system. The library's several families of procedures provide the functionalities discussed above, as well as others that have not been discussed here but that will be sufficiently clear to the interested practitioner. For example, declarations of an agent's solvables, and their

30 registration with a facilitator, are managed using procedures such as oaa_Declare, oaa_Undeclare, and oaa_Redeclare. Updates to data solvables can be accomplished with a family of procedures including oaa_AddData, oaa_RemoveData, and

Page 134 of Alto hev Docket No: SRI1P016(3477)/BRC/EWJ

oaa_ReplaceData. Shamarly, triggers are maintained using procedures such as oaa_AddTrigger, oaa_RemoveTrigger, and oaa_ReplaceTrigger. The provided source code also includes source code for an OAA Facilitator Agent.

The source code appendix is offered solely as a means of further helping practitioners to construct a preferred embodiment of the invention. By no means is the source code intended to limit the scope of the present invention.

Illustrative Applications

To further illustrate the technology of the preferred embodiment, we will next present and discuss two sample applications of the present inventions.

10 Unified Messaging

A further preferred embodiment of present invention incorporates a Unified Messaging application extending the Automated Office application presented previously herein with an emphasis on ubiquitous access and dynamic presentation of the information and services supported by the agent community. The agents used in this application are depicted in Figure 12.

A hypothetical example of realistic dialog using a preferred embodiment of the present invention can provide insight into how systems may preferably be built using the present invention. In this scenario, the user, with only a telephone as an interface, is planning a trip to Boston where he will soon give a presentation.

20 Capitalized sentences are phrases spoken by the user into the telephone and processed by a phone agent 452.

Responses, unless otherwise indicated, are spoken by the system using text-tospeech generation agent 454.

25 1.1 Welcome to SRI International. Please enter your user ID and password. <User enters touchtone ID and password> Good to see you again Adam Cheyer. I am listening to you.

30

Every user interface agent 408, including the telephone agent 452, should know the identify of its user. This information is used in resolving anaphoric

Page 135 of Anonev Docket No: SRI1P016(3477)/BRC/EWJ

references such as "me and "I", and allows multiple user interfaces operated by the same user to work together.

1.2 WHAT IS TODAY'S SCHEDULE? Here is today's schedule for Adam Cheyer: 5 At 10am for 1 hour, meeting with Dave. At 3pm for 1 hour, presentation about software agents.

End of schedule.

If the user is operating both a graphical user interface and a telephone, as described in conjunction with the Automated Office application, the result of this spoken request is to display a calendar window containing the current schedule. In this case, with no graphical display available, the GEN_NL agent 1202 is tasked to produce a spoken response that can be played over the phone. GEN_NL shares the same dynamic vocabulary and phrasal rules as the natural language parser DCG_NL 426, and contains strategies for producing responses to queries using either simple or

list-based multimedia utterances.

| | 1.3 | FIND FRIDAY'S WEATHER IN BOSTON. The weather in Boston for Friday is as follows: |
|----|------------|---|
| | c . | Sunny in the morning. Partly cloudy in the |
| 20 | afte | rnoon with a 20 percent chance of thunderstorms late. Highs in the |
| | mid ' | 70s. |

In addition to data accessible from legacy applications, content may be retrieved by web-reading agents which provide wrappers around useful websites.

| 25 | 1.4 | FIND ALL NEW MAIL MESSAGES. | |
|----|-------------------------|--|--|
| | | There are 2 messages available. | |
| | | Message 1, from Mark Tierny, entitled "OAA meeting." | |
| | 1.5 | NEXT MESSAGE | |
| | | Message 2, from Jennifer Schwefler, entitled | |
| 30 | "Presentation Summary." | | |
| | 1.6 | PLAY IT. | |
| | | This message is a multipart MIME-encoded message. | |
| | There | e are two parts. | |
| | | Part 1. (Voicemail message, not text-to speech): | |
| 35 | | Thanks for taking part as a speaker in our | |
| | conference. | | |
| | | The schedule will be posted soon on our homepage. | |
| | 1.7 | NEXT PART | |
| | | Part 2. (read using text-to-speech): | |
| 40 | | The presentation home page is http://www | |
| | 1.8 | PRINT MESSAGE | |
| | | Command executed. | |

Mail messages are no longer just simple text documents, but often consist of multiple subparts containing audio files, pictures, webpages, attachments and so forth. When a user asks to play a complex email message over the telephone, many different agents may be implicated in the translation process, which would be quite different

5 given the request "print it." The challenge is to develop a system which will enable agents to cooperate in an extensible, flexible manner that alleviates explicit coding of agent interactions for every possible input/output combination.

In a preferred embodiment of the present invention, each agent concentrates only on what it can do and on what it knows, and leaves other work to be delegated to the agent community. For instance, a printer agent 1204, defining the solvable print(Object,Parameters), can be defined by the following pseudo-code, which basically says, "If someone can get me a document, in either POSTSCRIPT or text form, I can print it.".

| 15 | <pre>print(Object, Parameters) { ' If Object is reference to "it", find an appropriate</pre> | |
|---------------------------------|--|--|
| | document | |
| | if (Object = "ref(it)") | |
| | <pre>oaa_Solve(resolve_reference(the, document, Params,</pre> | |
| 20 | Object),[]); | |
| | ' Given a reference to some document, ask for the | |
| | document in POSTSCRIPT | |
| | if (Object = "id(Pointer)") | |
| | <pre>oaa_Solve(resolve_id_as(id(Pointer), postscript,</pre> | |
| 25 | [], Object),[]); | |
| | ' If Object is of type text or POSTSCRIPT, we can | |
| | print it. | |
| | if ((Object is of type Text) or (Object is of type | |
| | Postscript)) | |
| <pre>30 do_print(Object);</pre> | | |
| | } | |

In the above example, since an email message is the salient document, the mail agent 442 will receive a request to produce the message as POSTSCRIPT. Whereas the mail agent 442 may know how to save a text message as POSTSCRIPT,

35 it will not know what to do with a webpage or voicemail message. For these parts of the message, it will simply send oaa_Solve requests to see if another agent knows how to accomplish the task.

Until now, the user has been using only a telephone as user interface. Now, he moves to his desktop, starts a web browser 436, and accesses the URL referenced by the mail message.

1.9 RECORD MESSAGE Recording voice message. Start speaking now.
1.10 THIS IS THE UPDATED WEB PAGE CONTAINING THE PRESENTATION SCHEDULE. Message one recorded.
1.11 IF THIS WEB PAGE CHANGES, GET IT TO ME WITH NOTE ONE.

Trigger added as requested.

In this example, a local agent 436 which interfaces with the web browser can return the current page as a solution to the request "oaa_Solve(resolve_reference(this, web_page, [], Ref),[])", sent by the NL agent 426. A trigger is installed on a web agent 436 to monitor changes to the page, and when the page is updated, the notify agent 446 can find the user and transmit the webpage and voicemail message using the most appropriate media transfer mechanism.

This example based on the Unified Messaging application is intended to show how concepts in accordance with the present invention can be used to produce a simple yet extensible solution to a multi-agent problem that would be difficult to implement using a more rigid framework. The application supports adaptable presentation for queries across dynamically changing, complex information; shared context and reference resolution among applications; and flexible translation of multimedia data. In the next section, we will present an application which highlights

the use of parallel competition and cooperation among agents during multi-modal fusion.

Multimodal Map

A further preferred embodiment of present invention incorporates the Multimodal Map application. This application demonstrates natural ways of communicating with a community of agents, providing an interactive interface on which the user may draw, write or speak. In a travel-planning domain illustrated by Figure 13, available information includes hotel, restaurant, and tourist-site data retrieved by distributed software agents from commercial Internet sites. Some preferred types of user interactions and multimodal issues handled by the application

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are illustrated by a brief scenario featuring working examples taken from the current system.

Sara is planning a business trip to San Francisco, but would like to schedule some activities for the weekend while she is there. She turns on her laptop PC, 5 executes a map application, and selects San Francisco. 2.1 [Speaking] Where is downtown? Map scrolls to appropriate area. 2.2 [Speaking and drawing region] Show me all hotels near here. 10 Icons representing hotels appear. 2.3 [Writes on a hotel] Info? A textual description (price, attributes, etc.) appears. [Speaking] I only want hotels with a pool. 2.4 Some hotels disappear. 15 [Draws a crossout on a hotel that is too close to a 2.5 highway] Hotel disappears 2.6 [Speaking and circling] Show me a photo of this 20 hotel. Photo appears. [Points to another hotel] 2.7 Photo appears. [Speaking] Price of the other hotel? 2.8 25 Price appears for previous hotel. 2.9 [Speaking and drawing an arrow] Scroll down. Display adjusted. [Speaking and drawing an arrow toward a hotel] 2.10 What is the distance from this hotel to Fisherman's Wharf? 30 Distance displayed. 2.11 [Pointing to another place and speaking] And the distance to here? Distance displayed. Sara decides she could use some human advice. She picks up the phone, calls 35 Bob, her travel agent, and writes Start collaboration to synchronize his display with hers. At this point, both are presented with identical maps, and the input and actions

of one will be remotely seen by the other.

40 3.1 [Sara speaks and circles two hotels] Bob, I'm trying to choose between these two hotels. Any opinions?
3.2 [Bob draws an arrow, speaks, and points] Well, this area is really nice to visit. You can
45 walk there from this hot

Map scrolls to indicated area. Hotel selected. [Sara speaks] Do you think I should visit Alcatraz?

3.4 [Bob speaks] Map, show video of Alcatraz.

3.3

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3.5 [Bob speaks] Yes, Alcatraz is a lot of fun.

A further preferred embodiment of present invention generates the most appropriate interpretation for the incoming streams of multimodal input. Besides providing a user interface *to* a dynamic set of distributed agents, the application is preferably built *using* an agent framework. The present invention also contemplates aiding the coordinate competition and cooperation among information sources, which in turn works in parallel to resolve the ambiguities arising at every level of the interpretation process: *low-level processing of the data stream, anaphora resolution, cross-modality influences* and *addressee*.

15 Low-level processing of the data stream: Pen input may be preferably interpreted as a gesture (e.g., 2.5: cross-out) by one algorithm, or as handwriting by a separate recognition process (e.g., 2.3: "info?"). Multiple hypotheses may preferably be returned by a modality recognition component.

Anaphora resolution: When resolving anaphoric references, separate
information sources may contribute to resolving the reference: context by object type, deictic, visual context, database queries, discourse analysis. An example of information provided through context by object type is found in interpreting an utterance such as "show photo of the hotel", where the natural language component can return a list of the last hotels talked about. Deictic information in combination
with a spoken utterance like "show photo of this hotel" may preferably include pointing, circling, or arrow gestures which might indicate the desired object (e.g., 2.7). Deictic references may preferably occur before, during, or after an accompanying verbal command. Information provided in a visual context, given for the request "display photo of the hotel" may preferably include the user interface

30 agent might determine that only one hotel is currently visible on the map, and therefore this might be the desired reference object. Database queries preferably involving information from a database agent combined with results from other resolution strategies. Examples are "show me a photo of the hotel in Menlo Park" and

Geguro. Sersard

Video appears.

2.2. Discourse analysis preferably provides a source of information for phrases such as "No, the other one" (or 2.8).

The above list of preferred anaphora resolution mechanisms is not exhaustive. Examples of other preferred resolution methods include but are not limited to spatial reasoning ("the hotel between Fisherman's Wharf and Lombard Street") and user preferences ("near my favorite restaurant").

Cross-modality influences: When multiple modalities are used together, one modality may preferably reinforce or remove or diminish ambiguity from the interpretation of another. For instance, the interpretation of an arrow gesture may vary when accompanied by different verbal commands (e.g., "scroll left" vs. "show info about this hotel"). In the latter example, the system must take into account how accurately and unambiguously an arrow selects a single hotel.

Addressee: With the addition of collaboration technology, humans and automated agents all share the same workspace. A pen doodle or a spoken utterance
15 may be meant for either another human, the system (3.1), or both (3.2).

The implementation of the Multimodal Map application illustrates and exploits several preferred features of the present invention: reference resolution and task delegation by parallel parameters of oaa_Solve, basic multi-user collaboration handled through built-in data management services, additional functionality readily achieved by adding new agents to the community, domain-specific code cleanly separated from other agents.

A further preferred embodiment of present invention provides reference resolution and task delegation handled in a distributed fashion by the parallel parameters of oaa_Solve, with meta-agents encoding rules to help the facilitator make context- or user-specific decisions about priorities among knowledge sources.

A further preferred embodiment of present invention provides basic multi-user collaboration handled through at least one built-in data management service. The map user interface preferably publishes data solvables for elements such as icons, screen position, and viewers, and preferably defines these elements to have the attribute "shareable". For every update to this public data, the changes are preferably

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automatically replicated to all members of the collaborative session, with associated callbacks producing the visible effect of the data change (e.g., adding or removing an icon).

Functionality for recording and playback of a session is preferably
implemented by adding agents as members of the collaborative community. These agents either record the data changes to disk, or read a log file and replicate the changes in the shared environment.

The domain-specific code for interpreting travel planning dialog is preferably separated from the speech, natural language, pen recognition, database and map user interface agents. These components were preferably reused without modification to add multimodal map capabilities to other applications for activities such as crisis management, multi-robot control, and the MVIEWS tools for the video analyst. **Improved Scalability and Fault Tolerance**

Implementations of a preferred embodiment of present invention which rely upon simple, single facilitator architectures may face certain limitations with respect to scalability, because the single facilitator may become a communications bottleneck and may also represent a single, critical point for system failure.

Multiple facilitator systems as disclosed in the preferred embodiments to this point can be used to construct peer-to-peer agent networks as illustrated in Figure 14. While such embodiments are scalable, they do possess the potential for communication bottlenecks as discussed in the previous paragraph and they further possess the potential for reliability problems as central, critical points of vulnerability to systems failure.

A further embodiment of present invention supports a facilitator implemented as an agent like any other, whereby multiple facilitator network topologies can be readily constructed. One example configuration (but not the only possibility) is a hierarchical topology as depicted in Figure 15, where a top level Facilitator manages collections of both client agents 1508 and other Facilitators, 1504 and 1506. Facilitator agents could be installed for individual users, for a group of users, or as appropriate for the task.

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Note further, that network work topologies of facilitators can be seen as graphs where each node corresponds to an instance of a facilitator and each edge connecting two or more nodes corresponds to a transmission path across one or more physical transport mechanisms. Some nodes may represent facilitators and some nodes may represent clients. Each node can be further annotated with attributes corresponding to include triggers, data, capabilities but not limited to these attributes.

A further embodiment of present invention provides enhanced scalability and robustness by separating the planning and execution components of the facilitator. In contrast with the centralized facilitation schemes described above, the facilitator system 1600 of Figure 16 separates the registry/planning component from the execution component. As a result, no single facilitator agent must carry all communications nor does the failure of a single facilitator agent shut down the entire system.

Turning directly to Figure 16, the facilitator system 1600 includes a registry/planner 1602 and a plurality of client agents 1612-1616. The registry/planner 1604 is typically replicated in one or more locations accessible by the client agents. Thus if the registry/planner 1604 becomes unavailable, the client agents can access the replicated registry/planner(s).

This system operates, for example, as follows. An agent transmits a goal 1610 to the registry planner 1602. The registry/planner 1604 translates the goal into an unambiguous execution plan detailing how to accomplish any sub-goals developed from the compound goal, as well as specifying the agents selected for performing the sub-goals. This execution plan is provided to the requesting agent which in turn initiates peer-to-peer interactions 1618 in order to implement the detailed execution plan, routing and combining information as specified within the execution plan.

Communication is distributed thus decreasing sensitivity of the system to bandwidth limitations of a single facilitator agent. Execution state is likewise distributed thus enabling system operation even when a facilitator agent fails.

Further embodiments of present invention incorporate into the facilitator functionality such as load-balancing, resource management, and dynamic configuration of agent locations and numbers, using (for example) any of the topologies discussed. Other embodiments incorporate into a facilitator the ability to aid agents in establishing peer-to-peer communications. That is, for tasks requiring a

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sequence of exchanges between two agents, the facilitator assistche agents in finding one another and establishing communication, stepping out of the way while the agents communicate peer-to-peer over a direct, perhaps dedicated channel.

Further preferred embodiments of the present invention incorporate
mechanisms for basic transaction management, such as periodically saving the state of agents (both facilitator and client) and rolling back to the latest saved state in the event of the failure of an agent.

APPENDIX A.I

Source code file named compound.pl.



1

```
*
  File : compound.pl
웅
  Primary Authors : David Martin, Adam Cheyer
ક્ષ
  Purpose : Provides handling of compound goals by the facilitator.
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  Unpublished-rights reserved under the copyright laws of the United States.
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  Unpublished Copyright (c) 1998, SRI International.
  "Open Agent Architecture" and "OAA" are Trademarks of SRI International.
*
  _____
$
```


% This is just here so this file can be compiled separately (but its % official declaration is in oaa.pl): :- op(599,yfx,::).

:- dynamic binding_num/1, ks_num/1, multiple_continuation/7

% This file is loaded by facilitator code, and thus no % module imports are needed here.

/*\

These facilitator routines support the use of compound "ICL goals". An ICLGoal is of the form Sources:Goal::Params, where both Sources and Params are optional. Each subgoal of ICLGoal is also of that form.

When an agent calls solve/2, it may specify an ICL goal which is "incomplete"; that is, ambiguous as to which agents are to solve the various subgoals. The facilitator then completes the ICL goal, if necessary, and executes it. Execution involves having all the subgoals solved by the appropriate agents, assembling the solutions, and returning them to the requesting agent.

If a agent wants to construct a complete ICL goal, and is willing to guarantee that it's complete and that all solvers mentioned in it are currently valid, then that agent (usually a "meta-agent") may call execute_goal directly. @@ We haven't yet provided library calls for this.

IMPORTANT NOTE: : has higher precedence than ::. This means that a:b::c will unify with X:Y and X:Y::Z, but NOT with Y::Z.

Wherever a Sources field appears, it may be any of the following: built_in facilitator

Page 146 of 778

parent KS [KS1, KS2, ...]

x

'built_in' isn't normally specified by a requesting agent - although there's no harm in doing so - but is used internally by the facilitator. KS, KS1, KS2, etc. may be either the name or address of an agent (client or facilitator). 'facilitator' or 'parent' may also appear in a list of KS's. If Sources is an empty list or a var, it is handled just as if there were no Sources field, in which case the facilitator determines what sources are relevant.

Note that when an ICL goal includes a Sources field, there should not be Sources fields for any of its subgoals. If there are, they will be ignored. (@@Need to make sure this works ok.) However, Params fields may be usefully nested within goals that have Params fields. Certain nested parameters, such as solution_limit/1, can be used by the solving agent.

If an ICL goal has parameters, some of them are "inherited" by subgoals. If there's a conflicting parameter on a subgoal, however, it overrides an inherited parameter.

PARAMETERS

address(+A) [embedded or global] - Used precisely as if A: prefixes the relevant goal.

get_address(-S) [embedded] - bind S to indicate who provided the solution. Solver identities will be given as numeric ids. Currently only works when attached to non-compound (sub)goals.

get_address(-S) [global] - bind S to indicate all sources that were queried in finding solutions (even if they returned none).

*/

/*\

complete_goal(RequestingKS, Goal, GlobalParams, CompletedGoal).

complete_goal takes in an ICL goal and produces a "complete ICL goal" (sometimes known as a "plan", but I think we'll reserve that term for future developments). The goal and the complete goal have precisely the same variables - but are not necessarily unifiable.

*/

complete_goal(RequestingKS, Goal, GlobalParams, CompletedGoal) : complete_addressing(RequestingKS, Goal, GlobalParams, AddressedGoal),
 complete_concurrency(AddressedGoal, CompletedGoal).

/*\

complete_addressing(+RequestingKS, +ICLGoal, +GlobalParams, -AddressedGoal).

AddressedGoal has more-or-less the same form as ICLGoal, but possibly with some regrouping of subgoals, and the addition of Sources fields to ICLGoal or its subgoals. The idea is that AddressedGoal contains complete information as to where its various subgoals are to be sent, so that no further analysis is needed. Any regrouping of subgoals is done as an optimization. AddressedGoal shares all variables with ICLGoal.

@@What other operators (e.g., negation) might we want to support?

 $\setminus * /$

/*\

complete sources(+RequestingKS, +ICLGoal, +GlobalParams, -AddressedGoal).

Ensures that every subgoal is explicitly covered by one or more sources. Determines the largest subgoals that can be "chunked"; that is, grouped together for submission to a source.

In the process, every goal acquires a Params field (wherever there was no Params field before, the empty list is added). This is done just to make the definition of complete sources more readable.

*/

```
% Here we assume that the goal-writer didn't really mean to put a var,
    % because it's not meaningful to do so:
complete sources(KS, Sources:Goal, GlobalParams, AddressedGoal) :-
    var(Sources),
    1,
   complete sources(KS, Goal, GlobalParams, AddressedGoal).
/*
    ( AddressedGoal = A: ->
      Sources = A
    | otherwise ->
      findall(A, sub_term(A:_, AddressedGoal), SubSources),
      % @@More work needed here:
      Sources = SubSources
   ).
*/
   % Here we assume that the goal-writer didn't really mean to put [],
    % because it's not meaningful to do so:
```

```
complete sources(KS, []:Goal, GlobalParams, AddressedGoal) :-
    1,
    complete sources(KS, Goal, GlobalParams, AddressedGoal).
    % Sources and Params already specified; we're done:
    % @@But let's verify the sources are valid!
complete sources( KS, Sources:Goal::Params, GlobalParams,
             Sources:Goal::Params) :-
    1.
    % Sources already specified; add empty Params list:
complete sources( KS, Sources:Goal, GlobalParams, Sources:Goal::[]) :-
    1.
    % Sure, we'll continue to support an address in Params or GlobalParams:
complete sources(KS, Goal::Params, GlobalParams, AddressedGoal) :-
    % @@ verify_params(...),
    ( memberchk(address(Sources), Params) ;
      memberchk(address(Sources), GlobalParams) ),
    \+ var(Sources),
    1,
    complete sources(KS, Sources:Goal::Params, GlobalParams, AddressedGoal).
    % No Sources or Params specified; add empty Params list before
    % proceeding:
complete sources(KS, Goal, GlobalParams, AddressedGoal) :-
    + (Goal = ::),
    1,
    complete sources(KS, Goal::[], GlobalParams, AddressedGoal).
    % Here we get down to the real work: determining solvers and
    % chunking of subgoals:
complete sources(KS, (\+ Goal1)::Params, GlobalParams, AddressedGoal) :-
    1,
    oaa Name (Facilitator),
    complete sources(KS, Goal1, GlobalParams, AddressedGoal1),
      % If S1 is a SINGLE source, it's OK to send the negation to the source.
      % This case also works if S1 == built in.
    ( (AddressedGoal1 = [S1]:G1::P1,
       S1 = Facilitator,
       S1 \== facilitator) ->
        AddressedGoal = S1: ((\+ G1)::P1)::Params
    | otherwise ->
        AddressedGoal = (\+ AddressedGoal1::Params)
    ).
complete_sources(KS, (Goal1, Goal2, Goal3)::Params, GlobalParams,
             AddressedGoal) :-
    % This clause is needed because we want built in pred's to be grouped
    % with what comes before, not after.
    1,
    complete_sources(KS, Goal1, GlobalParams, AddressedGoal1),
    complete_sources(KS, Goal2, GlobalParams, AddressedGoal2),
    complete sources(KS, Goal3, GlobalParams, AddressedGoal3),
    ( (AddressedGoal1 = S1:G1::P1,
       AddressedGoal2 = S2:G2::P2,
```

.

١,

```
AddressedGoal3 = S3:G3::P3,
       chunkable sources([S1, S2, S3], Sources),
       compatible params([P1, P2, P3])) ->
       AddressedGoal = Sources: (G1::P1, G2::P2, G3::P3)::Params
      (AddressedGoal1 = S1:G1::P1,
       AddressedGoal2 = S2:G2::P2,
       AddressedGoal3 = (S3A:G3A::P3A, Goal3B)::P3,
       % Goal3B may or may not begin with Source:. icl GoalComponents
       % deals with the precedence issues.
       icl_GoalComponents(Goal3B, _, G3B, P3B),
       chunkable sources([S1, S2, S3A], Sources),
       append (P3A, P3, NewP3A),
       append(P3B, P3, NewP3B),
       compatible params([P1, P2, NewP3A])) ->
       AddressedGoal = (Sources: (G1::P1, G2::P2, G3A::NewP3A)::[],
                        G3B::NewP3B)::Params
    (AddressedGoal1 = S1:G1::P1,
       AddressedGoal2 = S2:G2::P2,
       chunkable_sources(S1, S2, Sources),
       compatible_params([P1, P2])) ->
       AddressedGoal = (Sources: (G1::P1, G2::P2)::[], AddressedGoal3)::Params
    (AddressedGoal2 = S2:G2::P2,
       AddressedGoal3 = S3:G3::P3,
       chunkable sources (S2, S3, Sources),
       compatible_params([P2, P3])) ->
       AddressedGoal = (AddressedGoal1, Sources: (G2::P2, G3::P3)::[])::Params
    (AddressedGoal2 = S2:G2::P2,
       AddressedGoal3 = (S3A:G3A::P3A, Goal3B)::P3,
       icl_GoalComponents(Goal3B, _, G3B, P3B),
       chunkable sources([S2, S3A], Sources),
       append(P3A, P3, NewP3A),
       append(P3B, P3, NewP3B),
       compatible params([P2, NewP3A])) ->
       AddressedGoal = (AddressedGoal1, Sources: (G2::P2, G3A::NewP3A)::[],
                        G3B:NewP3B)::Params
    | otherwise ->
       AddressedGoal =
           (AddressedGoal1, AddressedGoal2, AddressedGoal3)::Params
   ).
complete_sources(KS, (Goal1, Goal2)::Params, GlobalParams, AddressedGoal) :-
    1,
   complete_sources(KS, Goal1, GlobalParams, AddressedGoal1),
   complete_sources(KS, Goal2, GlobalParams, AddressedGoal2),
    ( (AddressedGoal1 = S1:G1::P1,
       AddressedGoal2 = S2:G2::P2,
       chunkable sources (S1, S2, Sources),
       compatible params([P1, P2])) ->
       AddressedGoal = Sources: (G1::P1, G2::P2)::Params
    | otherwise ->
      AddressedGoal = (AddressedGoal1, AddressedGoal2)::Params
    ).
    % Note: this clause must precede that for disjunction.
complete sources(KS, (Goal1 -> Goal2 ; Goal3)::Params, GlobalParams,
             AddressedGoal) :-
    1,
   complete_sources(KS, Goal1, GlobalParams, AddressedGoal1),
   complete_sources(KS, Goal2, GlobalParams, AddressedGoal2),
```

```
complete sources(KS, Goal3, GlobalParams, AddressedGoal3),
    ( (AddressedGoal1 = S1:G1::P1,
       AddressedGoal2 = S2:G2::P2,
       AddressedGoal3 = S3:G3::P3,
       chunkable sources([S1, S2, S3], Sources),
       compatible params([P1, P2, P3])) ->
       AddressedGoal = Sources: (G1::P1 -> G2::P2 | G3::P3)::Params
    | otherwise ->
       AddressedGoal =
         (AddressedGoal1 -> AddressedGoal2 | AddressedGoal3)::Params
    ).
complete sources(KS, (Goal1 -> Goal2)::Params, GlobalParams, AddressedGoal) :-
    !,
    complete sources(KS, Goal1, GlobalParams, AddressedGoal1),
    complete sources(KS, Goal2, GlobalParams, AddressedGoal2),
    ( (AddressedGoal1 = S1:G1::P1,
       AddressedGoal2 = S2:G2::P2,
       chunkable sources([S1, S2], Sources),
       compatible params([P1, P2])) ->
       AddressedGoal = Sources: (G1::P1 -> G2::P2)::Params
    | otherwise ->
       AddressedGoal =
         (AddressedGoal1 -> AddressedGoal2)::Params
    ).
complete sources(KS, (Goal1 ; Goal2)::Params, GlobalParams, AddressedGoal) :-
    !,
    complete sources(KS, Goal1, GlobalParams, AddressedGoal1),
    complete sources(KS, Goal2, GlobalParams, AddressedGoal2),
    ( (AddressedGoal1 = S1:G1::P1,
       AddressedGoal2 = S2:G2::P2,
       chunkable sources (S1, S2, Sources),
       compatible params([P1, P2])) ->
       AddressedGoal = Sources: (G1::P1; G2::P2)::Params
    | otherwise ->
       AddressedGoal = (AddressedGoal1; AddressedGoal2)::Params
    ).
    % To be complete, we will allow for this nonstandard goal form:
complete sources(KS, Goal::Params1::Params2, GlobalParams,
             AddressedGoal::Params2) :-
    !,
    complete sources(KS, Goal::Params1, GlobalParams, AddressedGoal).
complete_sources(_KS, Goal::Params, _GlobalParams, built_in:Goal::Params) :-
    icl BuiltIn(Goal),
    % Here, finally, we determine the agents (or parent facilitator) that
    % can solve a non-compound Goal:
complete_sources(KS, Goal, GlobalParams, Sources:Goal) :-
    sources for goal(KS, Goal, GlobalParams, Sources).
remove_empty_params(Addr:Goal::[], Addr:NewGoal) :-
    1.
    remove_empty_params(Goal, NewGoal).
remove empty params (Addr:Goal::Params, Addr:NewGoal::Params) :-
    !,
   remove_empty_params(Goal, NewGoal).
remove_empty_params(Goal::[], NewGoal) :-
    !,
```

```
remove empty params(Goal, NewGoal).
remove empty params(Goal::Params, NewGoal::Params) :-
    1,
    remove empty params (Goal, NewGoal).
remove empty params(Sources:Goal, Sources:NewGoal) :-
    1.
    remove empty params (Goal, NewGoal).
remove empty params((\+ Goal)::[], (\+ NewGoal)) :-
    1.
    remove_empty_params(Goal, NewGoal).
remove_empty_params((Goal1, Goal2), (NewGoal1, NewGoal2)) :-
    !,
    remove empty params (Goal1, NewGoal1),
    remove empty params (Goal2, NewGoal2).
remove empty params((Goal1 ; Goal2), (NewGoal1 ; NewGoal2)) :-
    1,
    remove empty params (Goal1, NewGoal1),
    remove empty params (Goal2, NewGoal2).
remove_empty_params((Goal1 -> Goal2), (NewGoal1 -> NewGoal2)) :-
    !,
    remove empty params (Goal1, NewGoal1),
    remove empty params(Goal2, NewGoal2).
    % Primitive (non-compound) goal:
remove_empty_params(Goal, Goal).
remove addresses ( Sources:Goal, NewGoal) :-
    !,
    remove addresses(Goal, NewGoal).
remove addresses((Goal1, Goal2), (NewGoal1, NewGoal2)) :-
    1,
    remove addresses (Goal1, NewGoal1),
    remove addresses (Goal2, NewGoal2).
remove addresses((Goal1 ; Goal2), (NewGoal1 ; NewGoal2)) :-
    1,
    remove addresses (Goal1, NewGoal1),
    remove_addresses(Goal2, NewGoal2).
remove_addresses((Goal1 -> Goal2), (NewGoal1 -> NewGoal2)) :-
    1,
    remove addresses (Goal1, NewGoal1),
    remove addresses (Goal2, NewGoal2).
    % Primitive (non-compound) goal:
remove addresses(Goal, Goal).
/*\
chunkable_sources(+Sources1, +Sources2, -Sources).
Each argument is either: a single KS name (or numeric id); a list of
KS names (where 'facilitator' or 'parent' also count as KS
names), or the atom 'built_in'. (Empty list is OK.)
Sources1 gives the sources that can solve some goal, Sources2
gives the sources that can solve some other goal, and if this
pred. succeeds, Sources gives a set of sources that can solve
both together.
NOTES ON CHUNKING:
```

•

```
$1 A chunk is a sub-goal SG of a Goal such that
  (1) There is a nonempty set S of client agents each of which can solve
the entire chunk (that is, every predicate in the chunk is either an
icl BuiltIn or one of the agent's solvables), and
  (2) Performing the subgoal as (ks1:SQ ; ks2:SQ ; ... ; ksN:SQ), where
ks1 ... ksN are all the agents in S, does not in any way violate the
intended semantics of the overall Goal.
NOTE: chunking is done "conservatively", so as to preserve Prolog
semantics. So, for example, the following Goal:
    (a(1), b(2)),
where a and b are both solvable by ks1 and ks2, will be chunked as
follows:
    chunk(a(1), [ks1, ks2]), chunk(b(2), [ks1, ks2])
which amounts to no chunking at all, instead of
    chunk((a(1), b(2)), [ks1, ks2]).
The former results in execution
    (ks1:a(1) ; ks2:a2), (ks1:b(2) ; ks2:b(2))
whereas the latter would result in execution
    ks1:(a(1), b(2)) ; ks2:(a(1), b(2))
We might want to explore under what conditions more extensive chunking
can be done.
\times /
    % This just allows for single sources, not in a list:
chunkable sources (Source1, Source2, Sources) :-
    ( atomic(Source1) ->
      S1 = [Source1]
    | otherwise ->
      S1 = Source1
    ),
    ( atomic(Source2) ->
      S2 = [Source2]
    | otherwise ->
      S2 = Source2
    ),
    chunkable_srcs(S1, S2, Sources).
chunkable_srcs(built_in, Sources, Sources) :-
    % at least one element:
    Sources = [ ] ,
chunkable_srcs(Sources, built_in, Sources) :-
    Sources = [_ ],
    1.
chunkable_srcs([], [], []) :-
    !.
chunkable srcs([Source], [Source], [Source]) :-
    1.
chunkable_srcs([Source1], [Source2], [Source1]) :-
    ( number(Source1), atom(Source2) ;
      number(Source2), atom(Source1) ),
    1,
    find_address(Source1, Source),
    find_address(Source2, Source).
```

```
% chunkable sources(+SourcesIn, -SourcesOut).
        Does the same as chunkable_sources/3, but allows for a list
      of sources (length >= 1) as arg 1.  
chunkable sources([Sources], Sources).
chunkable sources([Sources1, Sources2 | RestSources], SourcesOut) :-
    chunkable sources (Sources1, Sources2, SourcesTemp),
    chunkable sources([SourcesTemp | RestSources], SourcesOut).
    % compatible params(+ParamLists).
        ParamLists is a list of 2 or more ParamLists. This predicate
    % succeeds IFF the ParamLists are compatible for purposes of
    % chunking.
compatible_params(_).
    % sources_for_goal(+RequestingKS, +Goal, +Params, -Sources).
    % @@ Here, depending on how the treatment of multiple facilitators evolves,
    % we may need to revisit the default use of the facilitator.
sources for goal (RequestingKS, ICLGoal, GlobalParams, Sources) :-
    icl_GoalComponents(ICLGoal, _, Goal, Params),
    append (Params, Global Params, All Params),
    findall(SomeKS,
          choose ks for goal (RequestingKS, Goal, _, AllParams, SomeKS, _),
          KSList),
    ( KSList = [] ->
      % @@Determine if there's a parent facilitator that can handle
      % the goal. This needs work; probably should have a local record
      % of what the parent can handle.
      find level (AllParams, Level, NewParams),
      ( (on exception(_, com:com GetInfo(parent, fac id(ParentBB)), fail), Level
> 0) ->
          Sources = [ParentBB]
      | otherwise ->
          Sources = []
      )
    | otherwise ->
        Sources = KSList
    ).
    % If Sources is bound, VERIFIES that all the Sources can be used
    % on the ICLGoal. If var(Sources), finds all the Sources that can
    % be used.
% sources_for_compound_goal(RKS, ICLGoal, GlobalParams, Sources) :-
/*\
complete_concurrency(+Goal, -ConcurrentGoal).
TBD.
\*/
complete_concurrency(Goal, Goal).
```


/*\

execute goal(+RequestingKS, +OrigGoal, +OrigParams, +CompleteGoal).

OrigGoal are OrigParams are exactly as submitted by some client agent (RequestingKS). CompleteGoal is the rewriting of OrigGoal that ensures complete addressing. OrigGoal and ICLGoal contain precisely the same var's.

See global comments near the top of this file.

Note: the meaning of variable "Goal" and other variables ending in "Goal" varies with context. In some places they indicate an ICL goal Source:Goal::Params (where Source and Params are both optional); in other places, they indicate just the Goal part of an ICL goal.

*/

execute goal (RKS, OrigGoal, OrigParams, ICLGoal) :-% Here, ICLGoal may or may not include a Sources component. Either % way, it gets handled by execute/7. % @@ What if OrigGoal's Params or GlobalParams has vars? % We remove addresses before calling term_vars only so as to avoid % a syntax error exception that comes up when ICLGoal = Addr:\+Goal remove addresses(ICLGoal, TempGoal), term vars(TempGoal, AllVars, Singletons, NonSingletons), new qoal id(Id), % This means simply, "When the Solvers and solutions (in the form of % Bindings for AllVars) are known for Goal, call % unify and return solutions(...)." assert(continuation(Id, Requestees, Solvers, Bindings, unify_and_return_solutions(Id,RKS,OrigGoal,OrigParams,AllVars, Requestees, Solvers, Bindings))), % This means: Find the Solvers and solutions: execute(Id, RKS, [], [], ICLGoal, OrigParams, AllVars).

/*\

execute(Id, RKS, Requestees, Solvers, Goal, InheritedParams, Vars).

execute/7 satisfies the ICL goal Goal. Id is an integer that identifies a continuation assertion. When the satisfaction of Goal has been completed, the continuation assertion tells what to do next. The satisfaction of Goal may be very simple, or may involve a number of steps, depending on the form of Goal.

Requestees is a list of source id's of all sources asked to participate in the satisfaction of whatever request contained Goal, and Solvers is a list of source id's of sources that succeeded in satisfying some part of the request (so Solvers is a subset of Requestees. These lists are being accumulated for return to the agent that submitted the request.

Conceptually, execute/7 does this:

```
findall(Vars, Goal, Bindings),
    append (Requestees, <list of KSs called on in the findall>, NewRequestees),
    append(Solvers, <list of KSs providing solutions in the findall>,
           NewSolvers),
    continue execution (Id, RKS, NewRequestees, NewSolvers, Bindings)
The behavior of continue execution, then, depends on a continuation/5
assertion, with Id as the first arg.
The important details have to do with how the satisfaction of the
"findall" part of this strategy may be delayed.
\*/
execute(Id, RKS, Requestees, Solvers, built in:ICLGoal, InheritedParams, Vars)
: -
    % This handles ICL built-ins, such as <, >, =, member/2, true, false, ...
    !,
    icl_GoalComponents(ICLGoal, _, Goal, Params),
    append (Params, Inherited Params, All Params),
    oaa Name (Facilitator),
    add element (Facilitator, Requestees, NewRequestees),
    % If the requestor wants to know the solver, bind it here:
    ( memberchk(get address(Facilitator), Params) -> true | true),
    ( oaa:passes tests(Params) ->
        % @@The use of solution limit and elsewhere here needs a close look:
        ( memberchk(solution_limit(N), AllParams) ->
          oaa:findNSolutions(N, Vars, call(Goal), Bindings)
      | otherwise ->
          findall(Vars, call(Goal), Bindings)
      )
    | otherwise ->
       Bindings = []
    ),
    ( Bindings == [] ->
        NewSolvers = Solvers
    | otherwise ->
        add element (Facilitator, Solvers, NewSolvers)
    ),
    ( memberchk(reply(none), AllParams) ->
        continue_execution(Id, RKS, NewRequestees, NewSolvers, [Vars])
    | otherwise ->
        continue execution(Id, RKS, NewRequestees, NewSolvers, Bindings)
    ).
    % Empty list of sources:
execute(Id, RKS, Requestees, Solvers, []:ICLGoal, InheritedParams, Vars) :-
    format('WARNING: No solvers for ICL goal or subgoal: -n ~q~n',
         ICLGoal),
    continue_execution(Id, RKS, Requestees, Solvers, []).
    % Single KS in a list:
execute(Id, RKS, Requestees, Solvers, [KS]:G, Params, Vars) :-
    !,
```

· ·

```
execute(Id, RKS, Requestees, Solvers, KS:G, Params, Vars).
    % Multiple KSs in a list:
execute(Id, RKS, Requestees, Solvers, [KS | Rest]:G, Params, Vars) :-
    1,
    execute for each ks(Id, RKS, Requestees, Solvers, G, Params,
                  Vars, [KS | Rest]).
    % Solver is facilitator (me):
execute(Id, RKS, Requestees, Solvers, Source:ICLGoal, InheritedParams, Vars) :-
    oaa Name (Facilitator),
    (Source = facilitator ; Source = Facilitator),
    1,
    icl_GoalComponents(ICLGoal, _, Goal, Params),
% If the requestor wants to know the solver, bind it here:
    ( memberchk(get_address(Facilitator), Params) -> true | true),
    append (Params, Inherited Params, All Params),
    findall(Vars,
            oaa:oaa solve local(Goal, InheritedParams),
          Bindings),
    ( memberchk(reply(none), AllParams) ->
        true
    | otherwise ->
      oaa Name(KSName),
      add element (KSName, Requestees, NewRequestees),
      ( Bindings == [] ->
            NewSolvers = Solvers
      | otherwise ->
            add_element(KSName, Solvers, NewSolvers)
      ),
      continue execution (Id, RKS, NewRequestees, NewSolvers, Bindings)
    ).
% Note: this code was inherited from pre-compound-query facilitator.
% One significant change: when a goal is sent to a parent, we used to
% automatically include local blackboard solutions also. We don't
% do this anymore.
% @@ Strategy should be re-evaluated at some point. For instance,
% the use of var P2 might now cause things to break (the requesting
% agent might try to unify its copy of Params with P2).
execute(Id, RKS, Requestees, Solvers, Sources:ICLGoal, InheritedParams, Vars) :-
    on exception(, com:com GetInfo(parent, fac_id(ParentBB)), fail),
    (Sources == parent ; Sources == ParentBB),
    !,
    icl_GoalComponents(ICLGoal, _, _Goal, Params),
    % If the requestor wants to know the solver, bind it here:
    % NO - it gets bound by the parent facilitator.
    % ( memberchk(get address(ParentBB), Params) -> true | true),
    append (Params, Inherited Params, All Params),
    % We don't need to check the level here (that's already been done),
    % but we do need to decrement its value by 1:
    find_level(AllParams, _Level, NewParams),
    oaa TraceMsg('~nRouting goal "solve(~p)" to parent ~p.~n',
```

. .

```
[ICLGoal, ParentBB]),
    new_goal_id(NewId),
    oaa PostEvent(ev post solve from bb(NewId, ICLGoal, NewParams), ·
                  [address(ParentBB)]),
    ( memberchk(reply(none), NewParams) ->
        unify and continue_execution(Id, RKS, ICLGoal, Vars,
          ParentBB, Requestees, Solvers, [ICLGoal])
    | otherwise ->
      % @@Shouldn't there be a time-check here?
      oaa:oaa add trigger local(
              comm,
              event (ev_reply_solved_by_bb(NewId, _KS, ICLGoal, _P2,
                                         Solutions),
                   ),
            ev_unify_and_continue_execution(Id, RKS, ICLGoal, Vars,
                      ParentBB, Requestees, Solvers, Solutions),
              [recurrence(when), on(receive)])
    ).
    % Send the goal to an agent:
execute(Id, RKS, Requestees, Solvers, KS:ICLGoal, InheritedParams, Vars) :-
    1.
    icl GoalComponents(ICLGoal, , Goal, Params),
    append (Params, InheritedParams, AllParams),
    % @@What if the KS' status has changed since it was specified?
    % find address allows for KS to be either numeric or symbolic.
    find address(KS, KSId),
    % If the requestor wants to know the solver, bind it here:
    ( memberchk(get_address(KSId), Params) -> true | true),
    % Could do another check of the agent's validity:
    % ks_ready(KSId, _),
*
      relevant_vars(Vars, Goal, GVars),
2
      OptimizedG = findall(GVars, Goal, All),
    % Output trace message:
    ( oaa:oaa trace(on) ->
        copy term(ICLGoal, TraceCopy),
      numbervars(TraceCopy, 0, _),
        copy term (InheritedParams, ParamsCopy),
      numbervars(ParamsCopy, 0, ),
      oaa TraceMsg(
        '% Routing goal to ~w:~n% ~w ~w~n~n',
        [KS, TraceCopy, ParamsCopy])
    | otherwise ->
        true
   ),
   new goal id (NewId),
8
     oaa_PostEvent(KS, RKS, solve(NewId, OptimizedG::Params, [])),
   oaa PostEvent (ev solve (NewId, ICLGoal, InheritedParams),
                  [from(RKS), address(KSId)]),
    ( memberchk(reply(none), AllParams) ->
        unify_and_continue_execution(Id, RKS, ICLGoal, Vars,
                          KSId, Requestees, Solvers, [ICLGoal])
         % If time_limit specified in parameters, setup
```

```
% time_trigger to wakeup if solutions hasn't been returned
         % in specified time.
    | otherwise ->
        ( memberchk(time_limit(NSecs), AllParams) ->
            add_time_check(NSecs, NewId, RKS, Goal,AllParams)
      true),
      oaa:oaa_add_trigger_local(
        comm,
        event(ev_solved(NewId, _KS, ICLGoal, _P2, Solutions), _),
        ev_unify_and_continue_execution(Id, RKS, ICLGoal, Vars,
                                      KSId, Requestees, Solvers, Solutions),
        [recurrence(when), on(receive)])
      poll_until_all_events([solved(Id, _KS, OptimizedG, P2, Solutions)]),
₽
₽
      Solutions = [findall(GVars, Goal, All)],
      respond query(Id, RKS, Solvers, KS, Goal, P2, Solutions)
8
    % Backtrack over solutions:
₽
      member(GVars, All).
    ).
    % Negation:
execute(Id, RKS, Requestees, Solvers, ICLGoal, InheritedParams, Vars) :-
    icl_GoalComponents(ICLGoal, _, (\+ G1), Params),
    1.
    append (Params, Inherited Params, New IParams),
    new goal id (NewId),
    assert(
        continuation (NewId, NewRequestees, NewSolvers, Bindings,
          continue negation(Id, RKS, NewRequestees, NewSolvers, NewIParams,
                      Vars, Bindings))),
    execute(NewId, RKS, Requestees, Solvers, G1, NewIParams, Vars).
    % Conjunction:
execute(Id, RKS, Requestees, Solvers, ICLGoal, InheritedParams, Vars) :-
    icl_GoalComponents(ICLGoal, _, (G1, G2), Params),
    !,
    append(Params, InheritedParams, NewIParams),
    new goal id (NewId),
    assert(
        continuation (NewId, NewRequestees, NewSolvers, Bindings,
          continue conjunction(Id, RKS, NewRequestees, NewSolvers, G2,
NewIParams,
                           Vars, Bindings))),
    execute(NewId, RKS, Requestees, Solvers, G1, NewIParams, Vars).
    % Local cut with alternative. Note: this clause must precede
    % that for disjunction.
execute(Id, RKS, Requestees, Solvers, ICLGoal, InheritedParams, Vars) :-
    icl GoalComponents(ICLGoal, , (G1 -> G2 | G3), Params),
    !,
    append (Params, Inherited Params, New IParams),
    new goal id (NewId),
    assert(
        continuation (NewId, NewRequestees, NewSolvers, Bindings,
          continue local_cut(Id, RKS, NewRequestees, NewSolvers, G2, G3,
NewIParams,
                       Vars, Bindings))),
    execute (NewId, RKS, Requestees, Solvers, G1, NewIParams, Vars).
```

```
% Local cut:
execute(Id, RKS, Requestees, Solvers, ICLGoal, InheritedParams, Vars) :-
    icl GoalComponents(ICLGoal, , (G1 -> G2), Params),
    1.
    append (Params, InheritedParams, NewIParams),
    new goal id (NewId),
    assert(
        continuation (NewId, NewRequestees, NewSolvers, Bindings,
          continue local cut(Id, RKS, NewRequestees, NewSolvers, G2, false,
NewIParams,
                       Vars, Bindings))),
    execute (NewId, RKS, Requestees, Solvers, G1, NewIParams, Vars).
    % Disjunction:
execute(Id, RKS, Requestees, Solvers, ICLGoal, InheritedParams, Vars) :-
    icl_GoalComponents(ICLGoal, _, (G1; G2), Params),
    1.
    append (Params, Inherited Params, New IParams),
    new_goal id(Id1),
    new goal id(Id2),
    assert(
        multiple continuation([Id1, Id2], Requestees, AllRequestees,
                        Solvers, AllSolvers,
                        [], AllBindings,
          continue execution(Id, RKS, AllRequestees, AllSolvers, AllBindings))),
    execute(Id1, RKS, Requestees, Solvers, G1, NewIParams, Vars),
    execute(Id2, RKS, Requestees, Solvers, G2, NewIParams, Vars).
    % Occasionally, a goal may have the form G::P (that is, no
    % address, and P is not compound), but it is still valid, so
    % long as G is valid.
    % Ex.: ([7]:a1(1)::[...])::[...]
execute(Id, RKS, Requestees, Solvers, Goal::Params, InheritedParams, Vars) :-
    !,
    append(Params, InheritedParams, NewIParams),
    execute(Id, RKS, Requestees, Solvers, Goal, NewIParams, Vars).
execute(Id, RKS, Requestees, Solvers, G, _Params, _Vars) :-
format('WARNING (execute/7): unrecognized goal form:~n
                                                               ~w~n', [G]),
    continue execution(Id, RKS, Requestees, Solvers, []).
execute for each ks(Id, RKS, Requestees, Solvers, Goal, Params, Vars, KSs) :-
    length(KSs, NumKSs),
    new_goal_ids(NumKSs, Ids),
    assert(
        multiple continuation (Ids, Requestees, AllRequestees, Solvers,
AllSolvers, [], AllBindings,
          continue_execution(Id, RKS, AllRequestees, AllSolvers, AllBindings))),
    exec for each ks(NumKSs, Ids, KSs, RKS, Requestees, Solvers, Goal,
                 Params, Vars).
```

```
% GOAL EXECUTION: INTERMEDIATE STEPS
```

- % The predicates in this group define intermediate steps in the satisfaction
- % of various ICL goal forms.

```
₽
% Note: intermediate steps in handling of DISJUNCTION are handled by
% continue_execution, using the multiple_continuation assertion.
% This is used in satisfying [KS1, KS2, ...]:Goal. Note that this is
    % equivalent to a disjunction (KS1:Goal ; KS2:Goal ; ....). So we
    % are able to use the multiple continuation assertion to accumulate
    % the solutions.
    s.
    % We don't need Solvers, because ...
exec for_each_ks(NumKSs, Ids, KSs, RKS, _Requestees, _Solvers,
            Goal, Params, Vars) :-
    retractall( ks num( ) ),
    assert( ks num(1) ),
    repeat,
    ks num(Num),
    ( Num > NumKSs ->
    otherwise ->
     nth1(Num, KSs, KS),
     nth1(Num, Ids, Id),
     % We use a local cut to prevent some (harmless) backtracking.
     % This is one place where we don't need to pass Requestees and
     % Solvers through to execute (3rd and 4th args), because they are
     % filled in by handle multiple continuation.
     ( execute(Id, RKS, [], [], KS:Goal, Params, Vars) -> true ),
     NextNum is Num + 1,
     retractall( ks num( ) ),
     assert( ks_num(NextNum) ),
     fail
    ).
    % This is used in satisfying (\+ Goal). When this
    % pred. is called, Goal has just been completed. Bindings gives
    % the solutions to Goal.
continue negation(Id, RKS, Requestees, Solvers, _Params, Vars, []) :-
    1,
   continue_execution(Id, RKS, Requestees, Solvers, [Vars]).
continue_negation(Id, RKS, Requestees, Solvers, _Params, _Vars, _Bindings) :-
   continue execution (Id, RKS, Requestees, Solvers, []).
    % This is used in satisfying (Goal1, Goal2). When this
    % pred. is called, Goal1 has just been completed. Bindings gives
    % the solutions to Goal1.
continue conjunction (Id, RKS, Requestees, Solvers, Goal2, Params, Vars, [])
: -
    !,
   continue execution(Id, RKS, Requestees, Solvers, []).
continue conjunction(Id, RKS, Requestees, Solvers, Goal2, Params, Vars,
Bindings) :-
   length(Bindings, NumBindings),
   new_goal_ids(NumBindings, Ids),
```

```
assert(
        multiple continuation(Ids, Requestees, AllRequestees, Solvers,
AllSolvers, [], AllBindings,
          continue execution(Id, RKS, AllRequestees, AllSolvers, AllBindings))),
    exec for each binding (NumBindings, Ids, Bindings, RKS, Requestees, Solvers,
Goal2.
              Params, Vars).
    % We don't need Requestees or Solvers, because they are filled in
    % by handle multiple continuation.
exec for each binding (NumBindings, Ids, Bindings, RKS, Requestees, Solvers,
            Goal, Params, Vars) :-
    retractall( binding num( ) ),
    assert( binding num(1) ),
    repeat,
    binding_num(Num),
    ( Num > NumBindings ->
    | otherwise ->
      nth1(Num, Bindings, Binding),
      nth1(Num, Ids, Id),
      Vars = Binding,
      % We use a local cut to prevent some (harmless) backtracking.
      % This is one place where we don't need to pass Solvers through
      % to execute (3rd arg):
      ( execute(Id, RKS, [], [], Goal, Params, Binding) -> true ),
      NextNum is Num + 1,
      retractall( binding_num(_) ),
      assert ( binding num (NextNum) ),
      fail
    ).
    % This is used in satisfying Goal1 -> Goal2 | Goal3. When this
    % pred. is called, Goall has just been completed. Bindings gives
    % the solutions to Goal1.
    % No solutions to Goal1:
continue local cut(Id, RKS, Requestees, Solvers, Goal2, Goal3, Params,
               Vars, []) :-
    !,
    ( Goal3 = false ->
        continue_execution(Id, RKS, Requestees, Solvers, [])
    otherwise ->
      execute(Id, RKS, Requestees, Solvers, Goal3, Params, Vars)
    ).
    % Some solutions:
continue_local_cut(Id, RKS, Requestees, Solvers, Goal2, _Goal3, Params,
               Vars, [Binding1 ]) :-
    new goal id (NewId),
    assert(
        continuation (NewId, NewRequestees, NewSolvers, Bindings,
          continue_execution(Id, RKS, NewRequestees, NewSolvers, Bindings))),
    Vars = Binding1,
    % local cut to prevent some (harmless) backtracking:
    ( execute (NewId, RKS, Requestees, Solvers, Goal2, Params, Binding1) -> true
).
```

```
% GOAL EXECUTION: COMPLETION
% This is called when the goal associated with Id has been completely
% satisfied.
continue_execution(Id, _RKS, Requestees, Solvers, Bindings) :-
     % Here we are BINDING the Solvers and Bindings var's. in the
     % continuation assertion. The var. also appears in Continuation:
    ( retract (continuation (Id, Requestees, Solvers, Bindings, Continuation)) ->
     call(Continuation)
    | multiple_continuation(Ids, _, _, _, _, _, _),
     memberchk(Id, Ids) ->
     handle_multiple_continuation(Id, Requestees, Solvers, Bindings, Ids)
    | otherwise ->
     format ('Internal Error: no continuation with id ~w~n', [Id])
    ).
handle multiple continuation(Id, Requestees, Solvers, Bindings, Ids) :-
    retract(multiple_continuation(Ids, PrevRequestees,
                        AllRequestees, PrevSolvers, AllSolvers,
                        PrevBindings, AllBindings,
                        Continuation)),
   del_element(Id, Ids, NewIds),
    append (PrevBindings, Bindings, NewBindings),
    append (PrevRequestees, Requestees, NewRequestees),
    append(PrevSolvers, Solvers, NewSolvers),
    (NewIds = [] ->
     AllBindings = NewBindings,
     AllRequestees = NewRequestees,
     AllSolvers = NewSolvers,
     call (Continuation)
    | otherwise ->
     assert (multiple continuation (NewIds, NewRequestees, AllRequestees,
                           NewSolvers, AllSolvers,
                           NewBindings, AllBindings,
                           Continuation))
   ).
% @@Let's see, if these args included the vars for any
% nested solvers params, we could probably instantiate solvers
% params in Goal...
unify_and_continue_execution(Id, RKS, Goal, Vars, Requestee, Requestees,
                     Solvers, Solutions) :-
   add_element(Requestee, Requestees, NewRequestees),
    ( Solutions == [] ->
       NewSolvers = Solvers
    | otherwise ->
       add_element(Requestee, Solvers, NewSolvers)
   ),
   findall(Vars,
         member(Goal, Solutions),
         Bindings),
   continue_execution(Id, RKS, NewRequestees, NewSolvers, Bindings).
```

```
% GENERAL UTILITIES
term vars (Term, AllVars, SingletonVars, NonSingletonVars) :-
   with output to chars (portray clause (Term), Chars),
   with input from chars(
             read term([variable names(Names), singletons(Singletons)],
                 Term1).
             Chars),
   extract vars (Names, Singletons, AllVars, SingletonVars, NonSingletonVars),
   Term = Term1.
extract_vars([], _Singletons, [], [], []).
extract_vars([Name = Var | RestNames], Singletons, [Var | RestVars],
         [Var | RestSV], NonSingletonVars) :-
   memberchk(Name = Var, Singletons),
   1,
   extract_vars(RestNames, Singletons, RestVars, RestSV, NonSingletonVars).
extract vars([ Name = Var | RestNames], Singletons, [Var | RestVars],
         RestSV, [Var | NonSingletonVars]) :-
   extract_vars(RestNames, Singletons, RestVars, RestSV, NonSingletonVars).
% DEBUGGING UTILITIES
% static test :-
     Class = root,
욯
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     KSName = dontcare,
윻
     BBName = dontcare,
윻
     oaa_read_setup_file,
융
     oaa_init_flags,
웅
     assert (oaa class (Class)),
용
     oaa_SetupCommunication(Class, KSName, BBName, []),
윰
     on_exception(_, oaa_AppInit, true),
웅
     oaa_Ready(true).
융
% connect :-
     % go(leaf, shell, root).
₽
€
     static test.
₽
% ce :-
₽
       repeat,
₽
       oaa GetEvent(CallingKS, Event, 0),
€
       ( Event = timeout ->
₽
       !,
          format('No events~n', [])
¥
€
       | otherwise ->
€
           oaa process event (CallingKS, Event),
웅
       fail
£
       ).
* ce :-
¥
     format('No events~n', []).
```

*

```
¥
% OrigGoal must be used in the return event, so that the
% requesting KS will identify it correctly.
unify and return solutions (Id, RKS, OrigGoal, OrigParams, Vars, Requestees, Solvers, Bi
ndings) :-
  findall(OrigGoal,
     member(Vars, Bindings),
     Solutions),
  oaa TraceMsg('~nRouting answers back to ~p:~n ~p~n',
       [RKS, Solutions]),
  cancel time check(Id),
  remove dups (Requestees, RequesteesSet),
  remove dups(Solvers, SolversSet),
  % If present, bind solvers request in OrigParams:
  ( memberchk(get address(RequesteesSet), OrigParams) -> true | true ),
  ( memberchk(get satisfiers(SolversSet), OrigParams) -> true | true ),
  oaa PostEvent (ev reply solved (RequesteesSet, SolversSet, OrigGoal,
OrigParams, Solutions),
          [address(RKS)]).
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```

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APPENDIX A.II

Source code file named fac.pl.

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```
$*
                *****
   File : fac.pl
*
₽
   Primary Authors : Adam Cheyer, David Martin
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   Purpose : Provides communications and coordination of the activities
€
           of a dynamic collection of client agents.
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   Updated : 12/98
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   Unpublished-rights reserved under the copyright laws of the United States.
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   Unpublished Copyright (c) 1998, SRI International.
   "Open Agent Architecture" and "OAA" are Trademarks of SRI International.
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s.
% fac.pl : the facilitator agent
                                      Adam Cheyer
                                           David Martin
% Provides communications and coordination of the activities of a
% dynamic collection of client agents.
% The blackboard can respond to the following external requests:
₽
€
     ev post event (AgentID, Cmd) : sends event to the agent
웅
     ev post event(Cmd)
                          : sends event to all
     ev post declare (Mode, Solvables, Params)
웋
黔
                             : adds, removes or replaces solvables ON
₽
                             : the facilitator
웅
     ev post update (Mode, Clause, Params)
₽
                             : adds, removes, or replaces data
€
                              on appropriate agents
ક્ર
     ev_post_trigger_update(Mode,TriggerType,Condition,Action,Params)
₿
                             : adds or removes a trigger
on appropriate agents
ક્ર
     ev_post_solve(Goal, Params): finds agent(s) to solve Goal
€
     connected (Connection)
                           : records that a client agent has connected
∛
       ev_connect(AgentInfo)
₽
                             : additional information from a client
ક્ષ
                             : agent (having version > 3.0)
₽
     end of file (Connection) : records that a client has closed its
₽
                       connection
옿
     ev register solvables : records the goals that an agent can solve.
€
% A facilitator uses the following events internally as trigger actions:
¥
옿
     ev respond query(Id, ToKS, ByKS, G, OrigParams, Params, S)
₽
                             : Sends the result of a query back to KS
¥
$
:- use module(library(lists)).
:- use module(library(basics)).
:- use_module(library(strings)).
:- use_module(library(charsio)).
```

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Page 167 of 778
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```
:- use module(library(sets)).
:- use module(library(samsort)). % for samsort(Ordered, Raw, Sort)
:- use module(library(tcp), [tcp_now/1, tcp_time_plus/3,
                       tcp schedule wakeup/2, tcp cancel wakeup/2]).
% The file containing the com module is normally specified here. For
% more info, see comments near the top of oaa.pl.
:- use module(com tcp, all).
:- use_module(oaa, all).
% Whether or not to load translations and compound query code
% is determined right here:
* :- [compound].
:- [translations].
:- multifile oaa_AppDoEvent/2.
:- dynamic time_limit_trigger/5.
                                   % time_limit_trigger(Id,When,KS,Goal,Params)
:- dynamic goal count/10.
                                 % goal count(GoalId,Goal,Params,EvParams,
                                       ToBeCalled, Called, Responders, Solvers,
                                   움
                                       Answers, NumAnswers)
                                   ₽
                                 % update count(GoalId,NumAgentsRequested,
:- dynamic update count/4.
                           ¥
                               KSs, Updaters)
initial solvables([
  solvable(agent_data(_Id, _Status, _Solvables, _Name), [type(data)],
                                                       [write(true)]),
    % Locations of all facilitators (currently maintained only by the 'root'
    % facilitator:
  solvable(agent location( Id2, Name2, Host2, Port2), [type(data)],
                                                          [write(true)]),
    % Host (if known) of each client agent:
  solvable(agent_host(_Id3, _Name3, _Host3), [type(data)], [write(true)]),
  agent_version(_Id1, _Language1, _Version1),
  can_solve(_Goal4, _IdList4),
    % For backwards compatibility. In translations.pl, some events
    ₽
      (write bb, etc.) specify updates to this solvable. Also, old-style
    % data triggers refer to it:
  solvable(data(_Item, _Data), [type(data)], [write(true)])
]).
/* Agent specific declarations */
oaa AppInit :-
   oaa SetTimeout(0).
/* This is the event generated by the TCP library. Will be followed
   immediately by ev connect/4, which is constructed by the client agent */
oaa_AppDoEvent(connected(Connection), _) :-
        1,
     format('~nKnowledge source connected: ~p~n~n', [Connection]),
     Id = Connection,
     oaa:oaa_add_data_local(agent_data(Id, open, [], Id), []),
      %% Maintain information of currently connected data.
     add_connected(Id, Connection).
```

•

```
/* For now, the ID of a client agent is the same as its connection (socket).
   This could change in the future, so we store Id and Connection
   as two separate entities. */
oaa_AppDoEvent(ev_connect(AgentInfoList), Params) :-
        memberchk( connection id(Id), Params),
      oaa Name (MyName),
      oaa Id(MyId),
      MyLanguage = prolog,
      oaa LibraryVersion(MyVersion),
      update_connected(Id, AgentInfoList),
      % preferred TCP transfer mechanism
      MyFormat = quintus binary,
      % Inform the client of his Id, and info about me.
        com SendData(Id,
         event (ev connected ([oaa id(Id), fac id(MyId), fac name (MyName),
           fac_lang(MyLanguage), fac_version(MyVersion),
           format(MyFormat)]),
             [])).
/* Removes meta-data for KS when the KS deconnects */
oaa AppDoEvent(end of file(Connection), _) :-
        Id = Connection,
      remove connected(Id),
      oaa:oaa_remove_data_local(agent_data(Id, _Status, _Solvable, AgentName),
[]),
      format('~nKnowledge source disconnected: ~p (~p)~n~n', [Id,AgentName]),
        % remove all facts written by the agent
      % TBD: Is this getting all relevant triggers (see commented code below)?
        oaa:oaa remove_data_owned_by(Id),
% Do we really want to do this? I think clients who are interested could
% register a trigger on the agent data predicate.
% Rather, I think we should check to see if any agents are currently waiting
% for this agent to solve some goal -- if the agent disconnects, we can assume
% that it won't be solving the goal anytime soon, and we should send back
% failure to the requesting agent. See OAA 1.0 Facilitator, end of file()
% method. [AJC, 11/24/97]
      post to all clients (ev agent disconnected (Id)).
₽
      fail.
% TBD: This needs update to look at the persistence param.
% oaa_AppDoEvent(end_of_file(KS), _) :-
ક્ષ
      % remove all triggers for KS
      on_exception(_, trigger(KS, Type, Kind, OpMask, Template, Cond, Action),
ዬ
fail),
      retract(trigger(KS, Type, Kind, OpMask, Template, Cond, Action)),
₽
      fail.
% oaa AppDoEvent(end of file( KS), ) :- !.
oaa AppDoEvent(ev ready(Name), Params) :-
        memberchk(from(Id), Params),
      % TBD: Let's have an error message if this fails:
      oaa:oaa_remove_data_local(agent_data(Id, _OldStatus, Solvables, _Name),
Params),
```

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```
oaa:oaa_add_data_local(agent_data(Id, ready, Solvables, Name), Params).
/* Stores the goals that a KS knows how to solve */
% Is this obsolete?
oaa AppDoEvent(ev register solvables(Goals), Params) :-
        memberchk(from(KS), Params),
      oaa AppDoEvent(ev register solvables(add,Goals,KS,[]), Params), !.
    % IMPORTANT: We assume the Solvables are in standard form and can
    % legally be added/removed/replaced for this agent. Also, we take
    % care to keep the facilitator's copy of each client's solvables
    % identical to that stored at the client. (Compare to code in
    % liboaa.pl, pred. oaa_declare_local).
oaa AppDoEvent (ev register solvables (Mode, Solvs, AgentName, EvParams), Params) :-
        memberchk(from(KS), Params),
      oaa Name (KSName),
      (oaa:oaa_remove_data_local(agent_data(KS, Status, List, _AgentName),
Params)
       format('STRANGE! register solvables called by unknown KS!!!: ~p~n',
            [KS]),
       Status = ready,
       List = []
      ),
      icl ConvertSolvables(PrettySolvs, Solvs),
      ( Mode == add, memberchk(if exists(overwrite), EvParams) ->
          NewList = Solvs,
          format('~p (~p) can solve: ~n ~p~n~n', [KS, AgentName,
                                         PrettySolvs])
      | Mode == add ->
          append(List, Solvs, NewList),
          format('~p (~p) has added solvables: ~n ~p~n~n',
               [KS, AgentName, PrettySolvs])
      | Mode == remove ->
          subtract(List, Solvs, NewList),
          format('~p (~p) has removed solvables: ~n ~p~n~n',
               [KS, AgentName, PrettySolvs])
      Mode == replace ->
          memberchk(with(NewSolvable), EvParams),
          Solvs = [Solvable],
          oaa:replace element(Solvable, List, NewSolvable, NewList),
          format('~p (~p) has replaced solvable:~n ~p~nwith solvable:~n
~p~n~n',
               [KS, AgentName, Solvable, NewSolvable])
      ),
      oaa:oaa_add_data_local(agent_data(KS, Status, NewList, AgentName),
Params),
      % if a parent exists (not root), pass goals upward.
      (com:com_GetInfo(parent, connection(_C)) ->
         oaa PostEvent( ev register solvables(Mode, Solvs, EvParams, KSName),
                        [address(parent)])
      true),
      1.
```

, : .

```
/* A client has requested that I declare certain solvables.
   TBD: This is still sketchy; should include some validation of the
   request, and should ensure the perms and params are right. */
oaa_AppDoEvent(ev_post_declare(Mode, Solvables, Params), EvParams) :-
    memberchk(from(RequestingKS), EvParams),
    oaa:oaa_declare_local(Mode, Solvables, Params, NewSolvables),
    icl ConvertSolvables (PrettySolvs, NewSolvables),
    oaa Id(MyId),
    oaa Name(MyName),
    format('~p (~p) has added solvables: ~n ~p~n~n',
         [MyId, MyName, PrettySolvs]),
    oaa PostEvent(
             ev_reply_declared(Mode, Solvables, Params, NewSolvables),
             [address(RequestingKS)]).
% A client requests a data solvable update operation (add, remove, replace)
% on the appropriate agents.
oaa_AppDoEvent(ev_post_update(Mode, Clause, Params), EvParams) :-
    ( Clause = (Head :- Body) ->
      true
    | otherwise ->
      Head = Clause
    ),
    memberchk(from(RequestingKS), EvParams),
    % see if the query is addressed using address(KS) in Params
    check address (Params, AddrKS),
    choose_agents_for_data(RequestingKS,Head,AddrKS,write,false,KSList),
    dispatch update request (RequestingKS, Mode, Clause, Params, KSList).
% A client requests a trigger update operation (Mode = add, remove, replace)
% on the appropriate agents. For triggers of type comm' and time', the
% address parameter must be present (otherwise, the request should not
% have come to the facilitator). For the other types, the address is
% optional.
oaa_AppDoEvent(ev_post_trigger_update(Mode, data, Condition,
                              Action, Params), EvParams) :-
    1,
    memberchk(from(RequestingKS), EvParams),
    % see if the query is addressed using address(KS) in Params
    check address (Params, AddrKS),
    choose_agents_for_data(RequestingKS,Condition,AddrKS,call,false,KSList),
    append (Params, EvParams, AllParams),
    dispatch trigger_request (RequestingKS, Mode, data, Condition, Action,
                             AllParams, KSList).
oaa_AppDoEvent(ev_post_trigger_update(Mode, task, Condition,
                              Action, Params), EvParams) :-
    !,
   memberchk(from(RequestingKS), EvParams),
    % see if the query is addressed using address(KS) in Params
    check address (Params, AddrKS),
    choose agents for goal (RequestingKS, Condition, AddrKS, Params, false, KSList),
    append (Params, EvParams, AllParams),
    dispatch trigger request (RequestingKS, Mode, task, Condition, Action,
                             AllParams, KSList).
```

oaa_AppDoEvent(ev_post_trigger_update(Mode, Type, Condition,

```
Action, Params), EvParams) :-
    memberchk(from(RequestingKS), EvParams),
    check address (Params, KSList),
    is list(KSList),
    append (Params, EvParams, AllParams),
    dispatch trigger request (RequestingKS, Mode, Type, Condition, Action,
                      AllParams, KSList).
% TBD: New for compound goals:
% If satisfaction of a compound goal is requested, and the compound query
% interpreter is not included, signal error condition:
oaa AppDoEvent(ev post solve(Goal, Params), EvParams) :-
    \+ current predicate(complete goal, complete goal( , , , )),
    \+ icl BasicGoal(Goal),
   1,
   format('ERROR: This facilitator does not support compound goals-n', []),
    format(' Returning 0 solutions for goal:~n ~w~n', [Goal]),
    oaa Id(Facilitator),
   memberchk(from(RequestingKS), EvParams),
    oaa PostEvent(
            ev reply solved([Facilitator],[],Goal,Params,[]),
[address(RequestingKS)]).
% If compound goal capabilities are included, ALL ev post solve events are
% handled here. Otherwise, they fall through to later clauses.
oaa AppDoEvent(ev post solve(Goal, Params), EvParams) :-
   current predicate(complete_goal, complete_goal(_,_,_)),
   1,
   memberchk(from(RequestingKS), EvParams),
   complete goal (RequestingKS, Goal, Params, CompletedGoal),
   execute goal (RequestingKS, Goal, Params, CompletedGoal).
/* Finds all KSs for a goal, asks them to solve it, then returns */
/* the answers to the calling KS
                                                      */
oaa_AppDoEvent(ev_post_solve(Goal, Params), EvParams) :-
       memberchk(from(RequestingKS), EvParams),
      % see if the query is addressed using address(KS) in Params
     check address (Params, AddrKS),
       choose agents for goal (RequestingKS, Goal, AddrKS, Params, true, KSList),
      % if none of my agents know how to solve goal, send to parent
      (KSList = [] ->
        find_level(Params, Level, NewParams),
        ((com:com_GetInfo(parent, fac_name(ParentName)),
          Level > 0) ->
             oaa TraceMsg('~nRouting goal "ev solve(~p)" to parent ~p.~n',
           [Goal, ParentName]),
           new goal id(Id),
           oaa_PostEvent( ev_post_solve_from_bb(Id, Goal, NewParams),
                          [address(parent)]),
```

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% if answers requested,
            % send parent's answers directly back to requestingKS
            % as well as blackboard solutions
            (memberchk(reply(none), NewParams) -> true |
             % No longer valid:
             % send_blackboard_solutions(RequestingKS, Goal, Params),
             oaa:oaa add trigger local(
                 comm,
               event(ev_reply_solved_by_bb(Id,SomeKS,Goal,Params2,Solutions),
                   _),
             ev_respond_query(Id,RequestingKS,SomeKS,Goal,Params,Params2,
                           Solutions),
             [recurrence(when), on(receive)])
            )
         % root blackboard: doesn't know anyone who can solve goal
           (memberchk(reply(none), NewParams) -> true
              oaa Id(KSID),
              oaa_PostEvent(
               ev reply solved([KSID],[],Goal,Params,[]),
               [address(RequestingKS)])
           )
        )
      | otherwise ->
          dispatch solve request(RequestingKS, Goal, Params, EvParams, KSList)
      ).
/* Finds all KSs for a goal, asks them to solve it, then returns */
/* the answers to the calling BB
                                                        */
oaa AppDoEvent (ev post solve from bb(Id, Goal, Params), EvParams) :-
        memberchk(from(RequestingKS), EvParams),
      % see if the query is addressed using address(KS) in Params
      check address (Params, AddrKS),
      choose_agents_for_goal(RequestingKS,Goal,AddrKS,Params,true,KSList),
      % if none of my agents know how to solve goal, send to parent
      (KSList = [] ->
         find_level(Params, Level, NewParams),
         % try to ask parent
         ((com:com_GetInfo(parent, fac_name(ParentName)),
           com:com_GetInfo(parent, fac_id(ParentId)), Level > 0) ->
              oaa_TraceMsg('~nRouting goal "ev_solve(~p)" to parent ~p.~n',
            [Goal, ParentName]),
            oaa PostEvent( ev post solve from bb(Id, Goal, NewParams),
                           [address(parent)]),
            (memberchk(reply(none), NewParams) -> true
              oaa:oaa add trigger local(
                 comm,
               event (ev reply solved by bb(Id, SomeKS, Goal, P2, Solutions),
                   _),
               ev_respond_bb_query(RequestingKS, ParentId, Id, Goal, Params,
                              P2, Solutions),
```

```
[recurrence(when), on(receive)])
            )
         % root blackboard : knows no solvers
            (memberchk(reply(none), Params) -> true |
              oaa Name (KSName),
              oaa PostEvent(
               ev reply_solved by bb(Id, KSName,Goal,Params, []),
               [address(RequestingKS)])
            )
         )
         member(SomeKS, KSList),
                                    % backtrack over all KSs.
           oaa TraceMsg('~nRouting goal to ~p: ~p~n',
                       [SomeKS, Goal]),
         oaa PostEvent ( ev solve (Id, Goal, Params),
                         [address(SomeKS), from(RequestingKS)]),
         (memberchk(reply(none), Params) -> fail |
           oaa:oaa add trigger local(
              comm.
              event(ev_solved(Id, _SomeKS, Goal, P2, Solutions), _),
              ev respond bb or post higher (RequestingKS, SomeKS, Id,
              Goal, P2, Solutions),
            [recurrence(when), on(receive)])
         ),
                  % send events to all KSs that can solve goal.
         fail
      ).
oaa AppDoEvent(wakeup(time limit(Id)), EvParams) :-
      retract(time_limit_trigger(Id,_When,RequestingKS,Goal,Params)),
      oaa TraceMsg('~nTime limit expired. Goal failed:~n ~p~n', [Goal]),
      oaa Id(KSId),
                        % get local ksid
f
       interpret(KSId,
₽
         ev_respond_query(-1,RequestingKS, KSId, Goal, Params, Params, [])).
      oaa Interpret(
          ev respond query(-1,RequestingKS, KSId, Goal, Params, Params, []),
        [from(KSId)]).
% When asked by parent blackboard to solve a goal,
% route all answers back using "ev solved(Id, KS, Goal, Params, Solutions)".
oaa AppDoEvent (ev solve (Id, Goal, Params), EvParams) :-
        memberchk(from(ParentBB), EvParams),
      oaa Name (KSName),
      % see if the query is addressed using address(KS) in Params
      check address (Params, AddrKS),
      choose agents for goal (KSName, Goal, AddrKS, Params, true, KSList),
      % if none of my agents know how to solve goal, send empty solutions
      (KSList = [] ->
         (memberchk(reply(none), Params) -> true |
            oaa_PostEvent( ev_solved(Id,KSName,Goal,Params,[]),
                            [address(ParentBB)])
```

```
)
         member(SomeKS, KSList), % backtrack over all KSs.
           oaa TraceMsg('~nRouting goal "ev solve(~p)" to ~p.~n', [Goal,
SomeKS]),
         oaa PostEvent( ev solve(Id, Goal, Params),
                        [address(SomeKS), from(ParentBB)]),
         (memberchk(reply(none), Params) -> fail |
           oaa:oaa_add_trigger_local(
              comm,
              event(ev_solved(Id, _SomeKS, Goal, P2, Solutions), _),
              ev_respond_to_parent(ParentBB,KSName,Id,Goal,Params,
                                 P2, Solutions),
            [recurrence(when), on(receive)])
         ),
         fail
                  % send events to all KSs that can solve goal.
      ).
/* If a KS is available, send it the message */
oaa AppDoEvent(ev post event(Event), EvParams) :-
        memberchk(from(KS), EvParams),
        choose_ks_for_goal(KS, Event, _, [], SomeKS, _),
      oaa_PostEvent(Event, [address(SomeKS), from(KS)]),
      fail.
/* If a KS is available, send it the message */
oaa_AppDoEvent(ev_post_event(KSName, Event), EvParams) :-
      oaa Name(KSName), !,
      % interpret(KS, Event).
      oaa Interpret (Event, EvParams).
oaa AppDoEvent (ev post event (KSName, Event), EvParams) :-
        memberchk(from(KS), EvParams),
        % agent must be "ready" to receive messages, or just
      % open if it is an agent compiled with old agentlib.
        (oaa:oaa_solve_local(agent_data(RealKS, ready, _Solvable,AgentName), [])
;
       oaa:oaa_solve_local(agent_data(RealKS, open, _Solvable,AgentName), []),
       oaa_Version(RealKS, Language, Version),
       Version < 2.0),
      (match ks(KSName, RealKS) ; KSName = AgentName),
      oaa_PostEvent(Event, [address(RealKS), from(KS)]),
      fail.
% oaa AppDoEvent(ev post event(KS, Event), _KS) :- !.
oaa AppDoEvent(ev post event(KS, Event), EvParams) :- !.
% Send back solutions to KS who originally requested them (with ev post solve)
¥
% 970219: DLM: Added arg. OrigParams. There is now a requirement that
% the params returned in a ev_reply_solved event must be unifiable with the
original
% params (from the corresponding solve event).
oaa_AppDoEvent(ev_respond query(Id,RequestingKS, Requestee, Goal, OrigParams,
                      Params,Solutions), _EvParams) :-
        oaa TraceMsg('~nRouting answers back to ~p:~n ~p~n',
```

```
[RequestingKS, Solutions]),
      cancel time check(Id),
      unify params (OrigParams, Params, UParams),
      ( Solutions == [] ->
          Solvers = []
      | otherwise ->
          Solvers = [Requestee]
      ),
      oaa PostEvent( ev reply solved([Requestee], Solvers, Goal, UParams,
Solutions).
                   [address(RequestingKS)]), !.
% Send back solutions to KS who originally requested them (with ev post solve)
% If no solutions, ask a higher blackboard
oaa AppDoEvent(
   ev respond or post higher(RequestingKS, Solver, Id, Goal, P, Solutions),
   _EvParams) :-
      ((Solutions \== [] ; oaa:oaa class(root)) ->
         cancel time check(Id), !,
         return solutions (RequestingKS, Solver, Id, Goal, P, Solutions)
      1
         % @@DLM: The following needs work. Must check goal count status
         % before posting higher
         % sub-agents found no solutions: post higher
         com:com GetInfo(parent, fac id(ParentId)),
         find level(P, Level, NewParams),
         Level > 0,
         oaa PostEvent( ev post solve from bb(Id, Goal, NewParams),
                        [address(parent)]),
         oaa:oaa add trigger_local(
            comm,
            event(ev_reply_solved_by_bb(Id, _SomeKS, Goal, P2, Solutions),
                  _),
            ev respond query(Id,RequestingKS,ParentId,Goal,P,P2, Solutions),
            [recurrence(when), on(receive)])
      ).
% Send back acknowledgement to agent that originally requested an update.
oaa AppDoEvent(
   ev return update(RequestingKS, Mode, Solver, Id, Clause, Params, Updaters),
  EvParams) :-
      return update(RequestingKS, Mode, Solver, Id, Clause, Params, Updaters).
% Send back acknowledgement to agent that originally requested a trigger
% update.
oaa AppDoEvent(
  ev_return_trigger_update(RequestingKS, Mode, Solver, Id, Type, Condition,
                      Action, Params, Updaters),
   EvParams) :-
        oaa TraceMsg('~nRouting trigger updaters back to ~p:~n ~p~n',
                [RequestingKS, Updaters]),
      return_trigger_update(RequestingKS, Mode, Solver, Id, Type, Condition,
                        Action, Params, Updaters).
% Send back solutions to a blackboard who requested them
    (with ev post solve from bb)
₽
```

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Page 176 of 778
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% 970219: DLM: Added arg. OrigP. There is now a requirement that
% the params returned in a ev solved event must be unifiable with the original
% params (from the corresponding solve event).
oaa AppDoEvent (ev respond bb query (RequestingBB, Solver, Id, Goal,
                         OrigP, P, Solutions), EvParams) :-
        unify params (OrigP, P, UP),
        oaa TraceMsg('~nRouting answers back to blackboard ~p:~n ~p~n',
                [RequestingBB, Solutions]),
      oaa_PostEvent( ev_reply_solved_by_bb(Id,Solver,Goal,UP,Solutions),
                   [address(RequestingBB)]), !.
% Send back solutions to a blackboard who requested them
oaa AppDoEvent(
    ev respond bb or post higher (RequestingBB, Solver, Id, Goal, P, Solutions),
    EvParams) :-
      ((Solutions \== [] ; oaa:oaa_class(root)) ->
           oaa_TraceMsg('~nRouting answers back to blackboard ~p:~n ~p~n',
                [RequestingBB, Solutions]),
         oaa PostEvent( ev reply solved by bb(Id, Solver, Goal, P,Solutions),
                    [address (RequestingBB)])
      % sub-agents found no solutions: post higher
         com:com GetInfo(parent, fac id(ParentId)),
         find level (P, Level, NewParams),
         Level > 0,
         oaa PostEvent ( ev post solve from bb(Id, Goal, NewParams),
                        [address(parent)]),
         oaa:oaa add trigger_local(
            comm.
            event(ev_reply_solved_by_bb(Id, _SomeKS, Goal, P2, Solutions),
                  ),
            ev respond bb query (RequestingBB, ParentId, Id, Goal, P, P2, Solutions),
            [recurrence(when), on(receive)])
     ).
% Send back solutions to KS who originally requested them (with ev post solve)
Ŷ
% 970219: DLM: Added arg. OrigP. There is now a requirement that
% the params returned in a ev solved event must be unifiable with the original
% params (from the corresponding solve event).
oaa_AppDoEvent(ev_respond_to_parent(ParentBB,Solver,Id,Goal, OrigP,
                           P, Solutions), _EvParams) :-
        unify params (OrigP, P, UP),
        oaa TraceMsg('~nRouting answers back to parent bb ~p:~n
                                                                   ~p~n',
                [ParentBB, Solutions]),
      oaa_PostEvent( ev_solved(Id, Solver, Goal, UP, Solutions),
                   [address(ParentBB)]), !.
oaa_AppDoEvent(ev_check_agent_name(KSName), EvParams):-
       memberchk(from(KS), EvParams),
        findall(KSName, oaa:oaa_solve_local(agent_location(_KSID, KSName ,_,),
[]), L),
        (L==[] ->
         % @@tcp send shouldn't be used:
        tcp_send(KS, 'UNIQUE');
        findall(KS1, oaa:oaa_solve_local(agent_location(_, KS1, _,_), []), R),
```

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tcp send(KS, R)),!.
oaa AppDoEvent(ev_register_port number(Name,Address), EvParams) :- %+KS, +Port,
+Host
        memberchk(from(KS), EvParams),
       Address = .. [address, Port, Host],
       oaa:oaa remove data local(agent location(KS, Name, Port, Host),
[]),!,
        oaa:oaa_add_data_local(agent_location(KS, Name, Port, Host), []),
        format('Agent ~p has Port: ~p , Host: ~p ~n', [KS, Port, Host]),
        !.
oaa AppDoEvent (ev register port number (Name, Address), EvParams) :- %+KS, +Port,
+Host
        memberchk(from(KS), EvParams),
       Address =.. [address, Port, Host],
        oaa:oaa add data local(agent location(KS, Name, Port, Host), []),
        format('Agent ~p has Port: ~p , Host: ~p ~n', [KS, Port, Host]),
        !.
oaa AppDoEvent (ev continue execution (Id, RKS, Requestees, Solvers, Solutions),
             EvParams) :-
        continue_execution(Id, RKS, Requestees, Solvers, Solutions).
% This is called from a trigger set in compound.pl.
oaa AppDoEvent(
   ev unify and continue execution(Id, RKS, Goal, Vars, Requestee, Requestees,
Solvers, Solutions),
   ) :-
   unify and continue execution (Id, RKS, Goal, Vars, Requestee, Requestees,
Solvers, Solutions).
/* Facilitator solvable: report the version and language of some
  connected agent. */
oaa_AppDoEvent(agent_version(Id, Language, Version), EvParams) :-
   1.
   oaa Version(Id, Language, Version).
/* Facilitator solvable: Find all agents who can solve goal */
oaa_AppDoEvent(can_solve(Goal, KSList), EvParams) :-
        ( memberchk(from(KS), EvParams) -> true | oaa Id(KS) ),
      findall(SomeKS, choose_ks_for_goal(KS, Goal, _, [], SomeKS, _), KSList).
% choose agents for goal (RequestingKS, Goal, AddrKS, Params, Sort, Agents).
 % The first 4 arguments are exactly as expected by choose ks for goal.
 % Sort, a boolean, tells whether to sort on utility.
choose_agents for goal(RequestingKS,Goal,AddrKS,Params,Sort,Agents) :-
   findall(
     p(Agent, Utility),
     choose ks for goal (RequestingKS, Goal, AddrKS, Params, Agent, Utility),
     Pairs
   ),
    ( Sort ->
     samsort(oaa_utility_compare, Pairs, SortedPairs)
    | otherwise ->
```

```
SortedPairs = Pairs
    ),
    findall(Agent, member(p(Agent, Utility), SortedPairs), Agents).
  % choose agents for data(RequestingKS,Goal,AddrKS,Perm,Sort,Agents).
  ¥
  % The first 4 arguments are exactly as expected by choose ks for data.
  % Sort, a boolean, tells whether to sort on utility.
choose agents for data (RequestingKS, Goal, AddrKS, Perm, Sort, Agents) :-
    findall(
      p(Agent, Utility),
      choose ks for data(RequestingKS, Goal, AddrKS, Perm, Agent, Utility),
      Pairs
    ),
    ( Sort ->
      samsort (oaa utility compare, Pairs, SortedPairs)
    | otherwise ->
      SortedPairs = Pairs
    ),
    findall(Agent, member(p(Agent,_Utility), SortedPairs), Agents).
oaa utility compare(p( Agent1, Utility1), p( Agent2, Utility2)) :-
   Utility1 >= Utility2.
/* Finds a KS that knows how to solve Goal */
% backtracks over all KSs that know how to solve
    a particular goal, except for RequestingKS, which is the
¥
    KS who asked for the goal to be solved in the
    first place. (RequestingKS is included if the 'reflexive' Param
윩
8
    is present.)
% MemberList can be a list used to reduce the set to at most MemberList
   or can be a specific KS to try, or a variable.
% If an address is specified in MemberList, it can be the same as
   RequestingKS (DLM, 96/10/30).
% Solvable lists can contain complex tests (AC, 97/2/5)
      e.g. [goal1(Y), (g(X) :- X > 1, X < 10), goal2]
¥
% Params is now used to check for 'reflexive' (DLM, 97/03/06).
% Utility is the numeric value the KS has associated with the
÷
    solvable.
choose_ks_for_goal(RequestingKS, Goal, MemberList, Params, SomeKS, Utility) :-
       var(MemberList),
      !,
        ks ready (SomeKS, ListOfGoals),
      ( icl GetParamValue(reflexive(true), Params) ->
            true
      | otherwise ->
          SomeKS \== RequestingKS
      ),
      oaa:oaa goal_matches_solvables(Goal, ListOfGoals, , Matched),
      Matched = solvable(_, SolveParams, ),
      icl GetParamValue(utility(Utility), SolveParams).
choose_ks_for_goal(_RequestingKS, Goal, MemberList, _Params, SomeKS, Utility) :-
      (is list (MemberList) ->
         member(SomeKS, MemberList)
      SomeKS = MemberList),
```

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oaa:icl true id(SomeKS, TrueId),
        ks ready(TrueId, ListOfGoals),
      oaa:oaa_goal_matches_solvables(Goal, ListOfGoals, _, Matched),
      Matched = solvable(_, SolveParams, _),
      icl GetParamValue(utility(Utility), SolveParams).
% backtracks over all KSs that know how to write a particular goal (or
% read, though that's not currently used), except for RequestingKS,
% which is the KS who asked for the goal to be solved in the first
% place. RequestingKS is never included, because he does the
% appropriate asserts locally, when appropriate.
% Perm is 'read' or 'write'.
choose ks for data(RequestingKS, Goal, MemberList, Perm, SomeKS, Utility) :-
        var(MemberList),
      1,
        ks ready (SomeKS, ListOfGoals),
      SomeKS \== RequestingKS,
      oaa:oaa data_matches_solvables(Goal, ListOfGoals, Perm, _, Matched),
      Matched = solvable(_, SolveParams, _),
      icl GetParamValue(utility(Utility), SolveParams).
choose ks for data (RequestingKS, Goal, MemberList, Perm, SomeKS, Utility) :-
      (is list (MemberList) ->
         member(SomeKS, MemberList)
      SomeKS = MemberList),
        ks ready (SomeKS, ListOfGoals),
      oaa: oaa data matches solvables (Goal, ListOfGoals, Perm, , Matched),
      Matched = solvable(_, SolveParams, _),
      icl GetParamValue(utility(Utility), SolveParams).
% ks ready(*SomeKS, *ListOfGoals).
    Backtracks over all agents that are ready to solve goals.
Ł
    If SomeKS is bound (with an agent's local ID), only that agent is
    considered.
*
ks_ready(SomeKS, ListOfGoals) :-
        % agent must be "ready" to receive messages, or just
      % open if it is an agent compiled with old agentlib.
        (oaa:oaa_solve_local(agent_data(SomeKS, ready, ListOfGoals,_AgentName),
[]);
       oaa:oaa solve local(agent data(SomeKS, open, ListOfGoals, AgentName),
[]),
       oaa Version(SomeKS, Language, Version),
       Version < 2.0).
% Facilitator agents look up their own solvables in oaa_solvables/1.
ks ready (SomeKS, ListOfGoals) :-
    oaa Id(SomeKS),
    oaa:oaa solvables(ListOfGoals).
match ks(all, KS).
match ks(KS, KS).
% If params contains a VALID address (symbolic name or id) for one or more
% agents, return the agents' ids.
% If params contains an INVALID address, remove it from the list returned.
% Otherwise, KSAddr should return a variable.
% 97-05-23 (DLM): The address param now should always contain a list,
```

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% but we'll check just to be safe.
check address (Params, 'KSAddr) :-
      memberchk (address (Addr), Params),
      ( is list(Addr) ->
          AddrList = Addr
          AddrList = [Addr]),
      find addresses (AddrList, KSAddr),
      1.
check address ( Params, SomeKS).
find addresses([], []).
find_addresses([Addr | Addrs], [Id | Ids]) :-
    find address(Addr, Id),
    !,
    find addresses (Addrs, Ids).
find_addresses([_Addr | Addrs], Ids) :-
    find_addresses(Addrs, Ids).
% Given an agent id (eg. 5) or a symbolic name (eg. 'interface')
% returns the local id for the reference.
% TBD: This does not yet handle remote addresses (associated with a different
% facilitator).
find address(addr(Addr), SomeKS) :-
    com:com GetInfo(incoming, oaa addr(Addr)),
    % That's me, the facilitator.
    1,
    oaa Id(SomeKS).
find address(addr(Addr, SomeKS), SomeKS) :-
    com:com GetInfo(incoming, oaa addr(Addr)),
    % One of my clients.
    1,
    % Make sure it's current:
    oaa:oaa_solve_local(agent_data(SomeKS, _, _ListOfGoals, _AgentName), []).
find address (name (Name), SomeKS) :-
    1,
    atom(Name),
    oaa:oaa solve_local(agent_data(SomeKS, _, _ListOfGoals, Name), []).
find address(SomeKS, SomeKS) :-
    oaa:oaa_solve_local(agent_data(SomeKS, _, _ListOfGoals, _AgentName), []),
    !.
find level (Params, Level, NewParams) :-
      oaa:remove element(level limit(Level), Params, Params2), !,
      (Level > 0 ->
         NewLevel is Level - 1
        NewLevel is 0),
      NewParams = [level limit(NewLevel) | Params2].
find_level(Params, 1, Params).
post_to_all_clients(Event) :-
        oaa Id(FacId),
        oaa:oaa_solve_local(agent_data(ClientId, ready, _Solvable,_AgentName),
[]),
```

```
ClientId \ = FacId,
      oaa PostEvent(Event, [address(ClientId), from(FacId)] ),
      fail.
post to all clients ( Event).
    % This is called when length of KSList is > 0.
    % goal count(GoalId,Goal,Params,EvParams,ToBeCalled,Called,
                 Responders, Solvers, Answers, NumAnswers)
dispatch solve request (RequestingKS, Goal, Params, EvParams, KSList) :-
    new goal id(Id),
    % Note that reply (none) overrides parallel ok (false). We can't
    % provide parallel ok (false) if no replies come back from solvers.
    ( memberchk(reply(none), Params) ->
      dispatch_solve_events(KSList, Id, RequestingKS, Goal, Params, EvParams)
    memberchk(parallel ok(false), Params) ->
      % Dispatch to one KS; save the rest for later.
      KSList = [FirstKS | Rest],
        assert(goal_count(Id, Goal, Params, EvParams, Rest,
                         [FirstKS], [], [], [], 0)),
      dispatch solve_event(Id, RequestingKS, Goal, Params, EvParams, FirstKS)
    | otherwise ->
      % Dispatch to all KSs.
      assert(goal count(Id, Goal, Params, EvParams, [],
                         KSList, [], [], [], 0)),
      dispatch solve events (KSList, Id, RequestingKS, Goal, Params, EvParams)
    ).
dispatch_solve events([], Id, RequestingKS, Goal, Params, EvParams).
dispatch solve events ([SomeKS | Rest], Id, RequestingKS, Goal,
                  Params, EvParams) :-
    dispatch solve event(Id, RequestingKS, Goal, Params, EvParams, SomeKS),
    dispatch solve events (Rest, Id, RequestingKS, Goal, Params, EvParams).
dispatch_solve event(Id, RequestingKS, Goal, Params, EvParams, SomeKS) :-
    oaa Id(SomeKS),
    % That's me, the facilitator.
    1,
    icl_GoalComponents(Goal, _, _, GoalParams),
append(Params, EvParams, InheritedParams),
    append (GoalParams, InheritedParams, AllParams),
    findall(Goal,
              % InheritedParams here is right, not AllParams:
            oaa:oaa solve local(Goal, InheritedParams),
          Solutions),
    ( memberchk(reply(none), AllParams) ->
      true
    | otherwise ->
        oaa AppDoEvent(
ev_respond_or_post_higher(RequestingKS,SomeKS,Id,Goal,Params,Solutions),
        [])
    ).
dispatch_solve_event(Id, RequestingKS, Goal, Params, _EvParams, SomeKS) :-
    oaa_TraceMsg('~nRouting goal "ev solve(~p)" to ~p.~n', [Goal, SomeKS]),
```

```
% ask a sub-agent to try and solve goal.
             if solutions are returned, pass them to requestingKS.
             otherwise, ask higher blackboard to try and solve goals.
         % note: send ev solve(id(Id,SomeKS), ...) as a means of insuring
             that each ev solved() trigger is unique and only matches
         *
             exactly one response. We use SomeKS in the field indicating
         ¥
             which agent actually solved the goal because individual
         *
             agents don't necessarily know their internal unique ID #.
         ¥
    oaa_PostEvent( ev_solve(id(Id,SomeKS), Goal, Params),
                   [address(SomeKS), from(RequestingKS)]),
    ( memberchk(reply(none), Params) ->
        true
    | otherwise ->
           % If time limit specified in parameters, setup
           % time trigger to wakeup if solutions hasn't been returned
           % in specified time.
        ( memberchk(time limit(NSecs), Params) ->
          add time check (NSecs, Id, RequestingKS, Goal, Params)
      | true),
     oaa:oaa_add_trigger_local(
        comm,
        event(ev solved(id(Id,SomeKS), _SomeKS, Goal, P2, Solutions),
                                                                        ),
        ev_respond_or_post_higher(RequestingKS, SomeKS, Id, Goal, P2, Solutions),
        [recurrence(when), on(receive)])
    ).
% return solutions(+RequestingKS, +Responder, +Id, +Goal, +P, +NewSolutions).
% Having just received solutions from a Responder, take the appropriate action.
% Even though the Responder has returned copies of the goal and params,
% we don't need them because we have a local copy in goal count.
₽
8 @@DLM: Unresolved question about streaming: Should we stream the
% responses with 0 solutions? [My thinking is "yes".]
return_solutions(RequestingKS, Responder, Id, _Goal, _P, NewSolutions) :-
    % ToBeCalled lists solvers not yet called. PrevCalled lists
    % the called solvers that have yet to respond.
   retract(goal_count(Id, Goal, Params, EvParams,
                       ToBeCalled, PrevCalled, PrevResponders,
                       PrevSolvers, PrevSolutions, PrevNumSol)),
    1,
     % Take Responder out of the called list:
    ( selectchk(Responder, PrevCalled, Called) ->
        true
    | otherwise ->
     format('ERROR: Inappropriate ev solved event received:~n', []),
     format(' ~w ~w ~w ~w~n', [RequestingKS, Responder, Id, Goal]),
     Called = PrevCalled
   ).
     % and put him into the responder list:
   append (PrevResponders, [Responder], Responders),
     % The solvers are just the responders that succeeded:
    ( NewSolutions = [] ->
     NewSolvers = []
    | otherwise ->
     NewSolvers = [Responder]
   ),
```

```
append(PrevSolvers, NewSolvers, Solvers),
append (PrevSolutions, NewSolutions, Solutions),
length(NewSolutions, NewNumSol),
NumSol is PrevNumSol + NewNumSol,
  % This case means that either: (1) we've gotten responses from all
  % solvers; and/or (2) we have reached the desired number of solutions.
  % By not saving goal count, we ensure that any additional returned
  % solutions are ignored:
( ((ToBeCalled == [], Called == []) ;
   (memberchk(solution limit(Limit), Params), NumSol >= Limit)) ->
      % This test is a place-holder; streaming not yet official:
     ( memberchk(reply(streaming), Params) ->
        Return = ev reply solved([Responder], NewSolvers, Goal, Params,
                                NewSolutions)
  | otherwise ->
        Return = ev_reply_solved(Responders, Solvers, Goal, Params,
                                Solutions)
  ),
  Save = false
  % This case happens with parallel ok(false):
| ToBeCalled = [Next | Rest] ->
  dispatch solve event(Id, RequestingKS, Goal, Params, EvParams, Next),
      % This test is a place-holder; streaming not yet official:
    ( memberchk(reply(streaming), Params) ->
        Return = ev_reply_solved([Responder], NewSolvers, Goal, Params,
                                NewSolutions),
        Save = goal count(Id, Goal, Params, EvParams,
                        Rest, [Next | Called], [], [], [], NumSol)
    | otherwise ->
      Return = false,
        Save = goal_count(Id, Goal, Params, EvParams,
                         Rest, [Next | Called], Responders, Solvers,
                    Solutions, NumSol)
    ì
  % Still waiting for some called solvers to respond:
| Called = [_ | _] ->
      % This test is a place-holder; streaming not yet official:
    ( memberchk(reply(streaming), Params) ->
        Return = ev_reply_solved([Responder], NewSolvers, Goal, Params,
                                NewSolutions),
        Save = goal count(Id, Goal, Params, EvParams,
                         ToBeCalled, Called, [], [], [], NumSol)
    | otherwise ->
      Return = false,
        Save = goal_count(Id, Goal, Params, EvParams,
                        ToBeCalled, Called, Responders, Solvers,
                    Solutions, NumSol)
    )
),
( Save == false ->
    true
| otherwise ->
   assert (Save)
).
( Return == false ->
    true
```

```
otherwise ->
        oaa TraceMsg('~nRouting answers back to ~p:~n ~p~n',
                    [RequestingKS, Return]),
        oaa PostEvent(Return, [address(RequestingKS)])
    ).
return solutions (_RequestingKS, _Responder, _Id, _Goal, _P, _NewSolutions).
dispatch update request (RequestingKS, Mode, Clause, Params, []) :-
    % No agents able to perform the requested update:
    1,
    ( memberchk(reply(none), Params) ->
      true
    | otherwise ->
      Event = ev reply updated(Mode, Clause, Params, [], []),
      oaa PostEvent(Event, [address(RequestingKS)])
    ).
dispatch update request (RequestingKS, Mode, Clause, Params, KSList) :-
    new goal id(Id),
    length(KSList,NumKSsForGoal),
    % if more than one KS can solve the goal, remember so that
    % we can collect answers from all of them later
    ( NumKSsForGoal > 1 ->
        assert(update count(Id, NumKSsForGoal, [], []))
    | otherwise ->
        true
    ),
                               % backtrack over all KSs.
    member(SomeKS, KSList),
    dispatch update event(Id, RequestingKS, Mode, Clause, Params, SomeKS),
    fail.
dispatch update request( RequestingKS, _Mode, _Clause, _Params, _KSList).
dispatch update event(Id, RequestingKS, Mode, Clause, Params, SomeKS) :-
    oaa Id(SomeKS),
    % That's me, the facilitator.
    1,
    ( Mode == add ->
        Functor = oaa_add_data_local
    Mode == replace ->
        Functor = oaa_replace_data_local
    | otherwise ->
        Functor = oaa_remove_data_local
    ),
    append(Params, [from(RequestingKS)], AllParams),
    Goal =.. [Functor, Clause, AllParams],
    ( call(oaa:Goal) ->
        Updaters = [SomeKS]
    | otherwise ->
        Updaters = []
   ),
    ( memberchk(reply(none), Params) ->
      true
    | otherwise ->
        % Params must be returned here (not AllParams):
        return update (RequestingKS, Mode, SomeKS, Id, Clause, Params, Updaters)
    ).
dispatch_update_event(Id, RequestingKS, Mode, Clause, Params, SomeKS) :-
    oaa TraceMsg('-nRouting request "ev_update(~p, ~p, ~p)" to ~p.~n',
```

```
[Mode, Clause, Params, SomeKS]),
    append (Params, [from (RequestingKS)], AllParams),
    oaa PostEvent(
             ev update(id(Id,SomeKS), Mode, Clause, AllParams),
             [address(SomeKS)]),
    ( memberchk(reply(none), Params) ->
      true
    | otherwise ->
      % TBD: Do we want to set a time trigger here?
      oaa:oaa add trigger local(
          comm,
          event(ev updated(id(Id,SomeKS), Mode, Clause, P2, Updaters), ),
            % Params must be returned here (not AllParams):
          ev return update (RequestingKS, Mode, SomeKS, Id,
                               Clause, Params, Updaters),
          [recurrence(when), on(receive)])
    ).
% Returns, to requesting KS, the addresses of all agents (including
% facilitator if appropriate), that attempted (NewKSs) and that actually
% satisfied (Updaters) an update request.
% NewUpdaters is always either [], or a singleton list.
¥
% Possible values for Mode: add, remove, replace.
% Note: Params must be returned in ev reply updated, so it must be
% unifiable with the params embedded in the requesting event (ev post event).
return update (RequestingKS, Mode, Responder, Id, Clause, Params,
            NewUpdaters) :-
      retract(update_count(Id, AgentsLeft, PrevKSs, PrevUpdaters)),
      append (PrevUpdaters, NewUpdaters, Updaters),
      append(PrevKSs, [Responder], NewKSs),
      ( AgentsLeft > 1 ->
         NewAgentsLeft is AgentsLeft - 1,
         assert(update count(Id, NewAgentsLeft, NewKSs, Updaters))
      | otherwise ->
          oaa TraceMsg('~nRouting updaters back to ~p:~n
                                                            ~p~n',
                   [RequestingKS, Updaters]),
          Event = ev reply updated (Mode, Clause, Params, NewKSs, Updaters),
          oaa PostEvent(Event, [address(RequestingKS)])
      ), !.
return update (RequestingKS, Mode, Responder, Id, Clause, Params, Updaters) :-
    oaa TraceMsg('~nRouting updaters back to ~p:~n
                                                    ~p~n',
             [RequestingKS, Updaters]),
   Event = ev reply updated(Mode, Clause, Params, [Responder], Updaters),
   oaa PostEvent(Event, [address(RequestingKS)]).
    % No agents able to install this trigger:
dispatch_trigger request (RKS, Mode, Type, Condition, Action, Params, []) :-
    !,
    ( memberchk(reply(none), Params) ->
      true
    | otherwise ->
      Event = ev_reply_trigger_updated (Mode, Type, Condition, Action, Params,
```

```
[], []),
      oaa PostEvent(Event, [address(RKS)])
    ).
dispatch trigger request (RKS, Mode, Type, Condition, Action, Params, KSList) :-
    new goal id(Id),
    length(KSList,NumKSsForGoal),
    % if more than one KS can solve the goal, remember so that
    % we can collect answers from all of them later
    ( NumKSsForGoal > 1 ->
        assert(update count(Id, NumKSsForGoal, [], []))
    | otherwise ->
        true
    ),
    member(SomeKS, KSList),
                               % backtrack over all KSs.
    dispatch trigger event (Id, RKS, Mode, Type, Condition, Action, Params,
SomeKS),
    fail.
dispatch_trigger_request(_RKS, Mode, Type, Condition, Action, _Params,
                   KSList).
dispatch_trigger_event(Id, RKS, Mode, Type, Condition, Action, Params,
                   SomeKS) :-
    oaa Id(SomeKS),
    % That's me, the facilitator.
    1,
    ( Mode == add ->
        Functor = oaa add trigger local
    | otherwise ->
        Functor = oaa remove trigger local
    ),
    Goal = .. [Functor, Type, Condition, Action, Params],
    ( call(oaa:Goal) ->
        Updaters = [SomeKS]
    | otherwise ->
        Updaters = []
    ),
    ( memberchk(reply(none), Params) ->
      true
    | otherwise ->
        return_trigger_update(RKS, Mode, SomeKS, Id, Type,
                            Condition, Action, Params, Updaters)
dispatch_trigger_event(Id, RKS, Mode, Type, Condition, Action, Params,
                   SomeKS) :-
    oaa TraceMsg('~nRouting request~n ev_update_trigger(~p, ~p, ~p, ~p, ~p)~nto
~p.~n',
              [Mode, Type, Condition, Action, Params, SomeKS]),
   oaa PostEvent(
       ev update trigger(id(Id,SomeKS), Mode, Type, Condition, Action, Params),
       [address(SomeKS), from(RKS)]),
    ( memberchk(reply(none), Params) ->
      true
    | otherwise ->
      % TBD: Do we want to set a time trigger here?
      oaa:oaa_add_trigger_local(
          comm,
```

ì

```
event (ev_trigger_updated (id (Id, SomeKS), _Mode, _Type, _Condition,
_Action, P2, Updaters), _),
         ev_return_trigger_update(RKS,Mode,SomeKS,Id,
                             Type, Condition, Action, P2, Updaters),
          [recurrence(when), on(receive)])
   ).
% Returns, to requesting KS, the addresses of all agents (including
% facilitator if appropriate), that attempted (NewKSs) and that actually
% satisfied (Updaters) a trigger update request.
% NewUpdaters is always either [], or a singleton list.
% Possible values for Mode: add, remove.
return trigger update (RequestingKS, Mode, Responder, Id,
                 Type, Condition, Action, Params, NewUpdaters) :-
     retract(update count(Id, AgentsLeft, PrevKSs, PrevUpdaters)),
     append (PrevUpdaters, NewUpdaters, Updaters),
     append(PrevKSs, [Responder], NewKSs),
      ( AgentsLeft > 1 ->
        NewAgentsLeft is AgentsLeft - 1,
        assert(update_count(Id, NewAgentsLeft, NewKSs, Updaters))
      | otherwise ->
         Event = ev_reply_trigger_updated(Mode,Type,Condition,Action,
                                  Params, NewKSs, Updaters),
         oaa_PostEvent(Event, [address(RequestingKS)])
     ), !.
return_trigger_update(RequestingKS, Mode, Responder, _Id,
                 Type, Condition, Action, Params, Updaters) :-
   Event = ev_reply_trigger_updated(Mode, Type, Condition, Action,
                            Params, [Responder], Updaters),
   oaa PostEvent(Event, [address(RequestingKS)]).
   % unify params(+OrigParams, +Params, -UnifiedParams).
   8
   % There is now (970219) a requirement that the params returned in
   % a ev solved or ev solved by bb event must be unifiable with the original
   % params from the corresponding solve request. In some situations*, the
   % Params returned to the facilitator by a solver may not unify with
   % the OrigParams, but may contain individual elements with variables
   % instantiated by the solver. This pred. can be used to save these
   % instantiations.
   ÷
   % *Such as, when find_level has been used to create a new params list.
unify_params([], _Params, []).
unify params([OrigParam | Rest], Params, [OrigParam | UnifiedRest]) :-
    ( memberchk(OrigParam, Params) | true ),
   !,
   unify params (Rest, Params, UnifiedRest).
% These are extremely simple predicates for maintaining com connection_info/5,
% which keeps info about the agents to which this agent currently has
```

```
% a communications channel.
```

ĩ

```
add connected(Id, Connection) :-
   assert (com:com connection info(Id, unknown, child,
                         [connection(Connection), oaa id(Id)], connected)).
update connected (Id, AddInfo) :-
   com AddInfo(Id, AddInfo).
% remove connected(+Id).
remove connected(Id) :-
   retractall(com:connection info(Id, _, _, _, )).
% if the time limit(NSec) parameter is sent, install wakeup on server
% to indicate the request has failed if not achieved in the correct time.
add time check (NSecs, Id, RequestingKS, Goal, Params) :-
   (time_limit_trigger(Id,_When, RequestingKS,_Goal,_Params) ->
             % already added for this goal request
      true
   tcp now (Now),
      tcp_time_plus(Now, NSecs, Soon),
      tcp schedule wakeup (Soon, time limit(Id)),
      assert(time limit trigger(Id, Soon, RequestingKS, Goal, Params)),
      oaa TraceMsq('~nTime limit check added for ~p~n', [Goal])
   ), !.
% if solutions are returned before a time limit trigger has expired,
% remove the trigger.
cancel time check(Id) :-
   retract(time limit trigger(Id,When, RequestingKS,Goal, Params)),
   tcp cancel wakeup(When,time limit(Id)),
   oaa TraceMsg('~nTime limit check removed because solution returned.~n
~p~n',
      [Goal]), !.
cancel_time_check(_Id).
/* Generates a unique ID for a goal.
/* ID's should be unique across blackboards*/
/* which is why we use the KSName prefix */
/* Goal counters are used to make sure the */
/* solution really matches the query.
new_goal id(NewId) :-
      oaa_Name(KSName),
      concat(KSName, ' ', Tmp),
      gensym(Tmp, NewId).
% Returns a list containing Num new goal ids.
new goal ids(Num, [NewId | RestIds]) :-
   Num > 0,
    !,
   new_goal id(NewId),
   NewNum is Num - 1,
   new_goal_ids(NewNum, RestIds).
new_goal_ids(_Num, []).
```

÷

```
start :-
    runtime_entry(start).
runtime entry(start) :-
    initial solvables (Solvables),
    com_ListenAt(incoming, CInfo),
    format('Listening at ~p~n~n', [CInfo]),
    oaa_RegisterCallback(app_do_event, user:oaa_AppDoEvent),
    oaa_Register(incoming, 'root', Solvables),
    on exception(, oaa AppInit, true),
    oaa MainLoop(true).
runtime_entry(abort) :- !.
      format('Closing all connections...~n',[]),
₽
¥
      close_all_connections.
% If the Facilitator is killed (ctrl-c) before disconnecting
% all clients, it will not free the port.
% This code is an attempt to fix this problem, but it doesn't
% help. Why not???
% close_all_connections :-
ક્ષ
      tcp connected(X,Y),
€
      tcp_destroy_listener(Y),
z
      tcp_shutdown(X),
      fail.
¥
% close_all connections :-
욲
      tcp_reset, fail.
```



APPENDIX A.III

Source code file named libcom_tcp.pl.

```
File : libcom_tcp.pl
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   Primary Authors : Adam Cheyer, David Martin
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   Purpose : TCP instantiation of lowlevel communication primitives for OAA
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   Updated : 01/98
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   Unpublished-rights reserved under the copyright laws of the United States.
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   Unpublished Copyright (c) 1993-98, SRI International.
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   "Open Agent Architecture" and "OAA" are Trademarks of SRI International.
   -------
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%* RCS Header and internal version
:- module(com,
      [com Connect/2,
      com Disconnect/1,
      com ListenAt/2,
      com SendData/2,
      com SelectEvent/2,
      com AddInfo/2,
      com GetInfo/2]).
% rcs version number
rcsid(libcom tcp, '$Header:
/tmp mnt/home/zuma1/martin/OAA/agents/beta/prolog/RCS/com tcp.pl,v 1.10
1998/05/06 22:35:36 martin Exp $').
:- use_module(library(sets)).
:- use module(library(tcp)).
:- use module(library(basics)).
:- use module(library(lists)).
:- use_module(library(charsio)). % for sprintf and with_output_to_chars
:- use module(library(ask)). % for ask oneof
:- use module(library(environ)). % read environment vars
:- use module(library(files)).
                            % can open file
:- use module(library(strings)). % for concat
:- dynamic
    com_connection info/5, % id, commtype, client/server, commInfo, status
      com_already_loaded/1. % filename
com_Connect(+ConnectionId, ?Address)
% name:
% purpose: Given a connection ID and an address, initiates a client connection
% remarks:
```

٠

```
% - if Address is a variable, instantiates the Address by using
¥
    com ResolveVariables, which looks in a setup file, command line, and
8
     environment variables for the required info.
  - stores the connection info for connection ID in com connection info/5.
8
% - fails if connection can't be made
com Connect(ConnectionId, tcp(Host,Port)) :-
     ground (ConnectionId),
     % if variable address, look it up...
     ((var(Host) ; var(Port)) ->
       com ResolveVariables([
          [cmd('-oaa_host',Host), cmd('-oaa_port', Port)],
          [env('OAA_HOST', Host), env_int('OAA_PORT', Port)],
          [setup('setup.pl', oaa_host, Host),
           setup('setup.pl',oaa port, Port)]
        ])
     true),
     tcp connect(address(Port, Host), RootConnection),
     assert (com connection info (ConnectionId, tcp, client,
          [addr(tcp(Host,Port)),
           oaa host(Host), oaa port(Port), connection(RootConnection)],
          connected)).
% name:
         com Disconnect(+ConnectionId)
% purpose: Given a connection ID of type 'client', shuts down the connection.
% remarks: Succeeds silently if there is not an open connection having the
¥
         given id.
******
com_Disconnect(ConnectionId) :-
    ground (ConnectionId),
     com connection info(ConnectionId, tcp, client, Info, connected),
     com GetInfo(ConnectionId, connection(Connection)),
     tcp shutdown (Connection),
    retract(com connection info(ConnectionId,tcp,client,_Info,connected)),
     1.
com_Disconnect(_ConnectionId).
com ListenAt(+ConnectionId, ?Address)
% name:
% purpose: Given a connection ID and an address, initiate a server connection
% remarks:
% - if Address is a variable, instantiates the Address by using
     com ResolveVariables, which looks in a setup file, command line, and
₽
    environment variables for the required info.
₽
  - stores the connection info for connection ID in com connection info/5.
$
  - fails if connection can't be made
com ListenAt(ConnectionId, tcp(Host,Port)) :-
    ground (ConnectionId),
     % if variable address, look it up...
     ((var(Host) ; var(Port)) ->
       com_ResolveVariables([
```

```
[cmd('-oaa host',Host), cmd('-oaa port', Port)],
            [env('OAA_HOST', Host), env_int('OAA_PORT', Port)],
            [setup('setup.pl',oaa_host, Host),
             setup('setup.pl',oaa_port, Port)]
          1)
      true),
      repeat,
      (on exception(E,
                 tcp_listen_at_port(Port, Host),
                 Exception = E) ->
         (var(Exception) ->
            assert(com_connection_info(ConnectionId, tcp, server,
               [addr(tcp(Host,Port)), oaa host(Host), oaa port(Port)],
               connected)),
            1
         | otherwise ->
            com ask about tcp exception(Port, Host, Response),
            ( Response == yes ->
                  fail
            | otherwise ->
                  halt
            )
         )
            com ask_about_tcp_exception(Port, Host, Response),
            ( Response == yes ->
                  fail
            | otherwise ->
                  halt
            )
      ).
com ask about tcp exception (Port, Host, Response) :-
      repeat,
      with_output_to_chars(
             format('Currently unable to access -w port -w.-n Try again? -w',
                   [Host, Port, '[y)es, n)o, h)elp]']),
            Chars),
      name(Prompt, Chars),
      ask_oneof(Prompt, [yes, no, help], Response),
      ( Response == help ->
            com print tcp exception help,
            fail
      | otherwise ->
            1
      ).
com_print_tcp_exception_help :-
   write('
I''ve just attempted to listen on the specified port, but was unable
to gain control of it. This could be because there''s already a
Facilitator, or some other program, making use of that port. Or, it
could be that a Facilitator using that port was just terminated.
                                                                   In
such cases, the port may be inaccessible for a brief period (usually
only a few seconds, but sometimes more). It may help to kill any
```

.

```
client agents which may still be connected to the defunct Facilitator.
If you think the specified port may now be accessible, enter "y" and
I''ll try again. You may request retry any number of times.
If you want me to listen on a different port, enter "n", which will
cause me to terminate. Then change your port specification (it''s
either in a setup file or an environment variable). Then restart me.
1).
com SendData(+ConnectionId, +Data)
% name:
% purpose: Sends data to the specified connection ID
% remarks:
% - Checks format for destination connection
com SendData(ConnectionId, Data) :-
     ground (ConnectionId),
     ( com connection info(ConnectionId, Type, _ClientServer, InfoList,
          connected),
       (Type = tcp ; Type = unknown), !,
       memberchk(connection(Dest), InfoList)
       format('~nError: cannot find open connection for ~p!~n',
          [ConnectionId]),
       fail
     ),
     ( memberchk(format(F), InfoList) ->
         true
     memberchk(agent language(c), InfoList) ->
         F = special case c
     | otherwise ->
         F = default
     ),
     1,
     com_send_data_by_format(Dest, F, Data).
% guintus binary: for inter-guintus communication
com send data by format (Dest, quintus binary, Data) :- !,
     tcp send(Dest, Data).
% prolog: a synonym for quintus binary
com send data by format (Dest, prolog, Data) :- !,
     tcp send(Dest, Data).
% pure ascii: don't wrap data in term() wrapper
com send data by format (Dest, pure ascii, Data) :- !,
       current_output (CurrentOutput),
       flush output(CurrentOutput),
       tcp output stream (Dest, TcpOutput),
       set_output(TcpOutput),
```

```
WriteParams =
           [quoted(true),
                                     % make input acceptable for read
            ignore ops(false),
                                    % false so list will be printed as '[1,2]'
            % !!! could be a problem with +, other opts.
           numbervars(true), % print vars as f(A).
            character_escapes(false), % write actual character, not \255
           max depth(0)],
                                    % no depth limit
       write term(Data, WriteParams),
        flush output (TcpOutput),
        set_output(CurrentOutput), !.
% special_case_c: This is the same as default, EXCEPT for the use of
% nl, nl. See comments within the clause for default format.
% Currently we don't understand why it matters.
com send data by format(Dest, special case c, Data) :- !,
       current output (CurrentOutput),
        flush output (CurrentOutput),
        tcp_output_stream(Dest, TcpOutput),
        set output(TcpOutput),
       WriteParams =
           [quoted(true),
                                     % make input acceptable for read
            ignore ops(false),
                                % false so list will be printed as '[1,2]'
            % !!! could be a problem with +, other opts.
           numbervars(true), % print vars as f(A).
           character escapes(false), % write actual character, not \255
           max depth(0)],
                                    % no depth limit
       write term(term(Data), WriteParams),
       write('.'),
       nl, nl,
       flush output (TcpOutput),
       set output(CurrentOutput), !.
% DefaultOAA: wrap in term() wrapper for easy parsing
com send data by format(Dest, DefaultOAA, Data) :-
       current_output (CurrentOutput),
       flush output(CurrentOutput),
       tcp_output_stream(Dest, TcpOutput),
       set output(TcpOutput),
       WriteParams =
                                    % make input acceptable for read
           [quoted(true),
                                    % false so list will be printed as '[1,2]'
           ignore ops(false),
           % !!! could be a problem with +, other opts.
           numbervars(true),
                              % print vars as f(A).
           character_escapes(false), % write actual character, not \255
                                   % no depth limit
           max_depth(0)],
       write_term(term(Data), WriteParams),
       write('.'),
       % nl, nl,
% The preceding does not work between two Quintus agents
% (neither does a single nl, nor does it help to use nl(TcpOutput)),
% so we went to the following. However, the following does not work
```

```
% when a QP facilitator sends to the C interface agent. For now,
% we'll solve this problem by defining the special case c format.
% (DLM, 97-04-09)
    put(TcpOutput, 10),
    % This causes the agents to disconnect (at least under UNIX):
      % put(TcpOutput, 13),
      flush output (TcpOutput),
      set output(CurrentOutput), !.
com SelectEvent(+TimeOut, -Event)
% name:
% purpose: Waits and returns an incoming event, or 'timeout' if TimeOut expires
% remarks:
% - TimeOut may be a real number, and represents seconds.
com SelectEvent(0, Event) :- !,
    on exception(E,tcp select(Event), com print_err(E)).
com SelectEvent(Seconds, Event) :-
    on exception(E,tcp select(Seconds, Event),com print err(E)).
% name:
        com print err
% purpose: Print error message if problem reading the event
com_print_err(E) :-
  format('~n======== READ ERROR !!! ==========n',[]),
  format('| Messages in this block are rejected~n', []),
  format('| by the system.~n',[]),
  format('-----n',[]),
  print message(error, E),
  % name: com AddInfo
% purpose: Adds or changes information about connection
% remarks:
¥
   Info may be status(S), type(T), protocol(P) or any element (or list
   of elements) to be stored in InfoList.
욹
com_AddInfo(ConnectionId, NewInfo) :-
    retract(com connection info(ConnectionId, Protocol, Type,
         InfoList, Status)),
    (NewInfo = status(NewStatus), C = true ; NewStatus = Status),
    (NewInfo = protocol (NewProtocol), C = true ; NewProtocol = Protocol),
    (NewInfo = type(NewType), C = true ; NewType = Type),
    (NewInfo = [_H|_T] \rightarrow
      union([InfoList, NewInfo], NewInfoList)
     (ground(C) ; union([InfoList, [NewInfo]], NewInfoList))
    ),
    assert (com connection info (ConnectionId, NewProtocol, NewType,
```

.

```
NewInfoList, NewStatus)), !.
```

```
com GetInfo
% name:
% purpose: Looks up information about connection
% remarks:
    Info may be status(S), type(T), protocol(P) or any element stored
    in InfoList.
com GetInfo(ConnectionId, Info) :-
     com connection_info(ConnectionId, Protocol, Type,
          InfoList, Status),
     (Info = status(Status) ;
     Info = type(Type) ;
     Info = protocol(Protocol) ;
     memberchk(Info, InfoList)),
     !.
٩.
% name:
         com ResolveVariables
% purpose: Tries to instantiate the arguments by looking in the command
8
       line arguments, environment variables, and setup files
8
 inputs:
ક્ર
   - VarList:
               A list of lists: the first sublist that completely resolves
¥
       provides the value for com ResolveVariables.
% remarks:
€
    sublists may contain elements in the following format:
₽
      env(EnvVar, Val) : looks for "EnvVar" in environment vars
8
     env_int(EnvVar, Val)
                        : Returns value for EnvVar as an integer
¥
     cmd(CmdVar, Val) : looks for "CmdVar <Val>" on command line
¥
     setup(File,SVar, Val) : reads SVar from setup file File
% example:
€
    resolves host and port by searching first commandline, then environment
€
    variables, finally reads setup file.
₽
₽
    com_ResolveVariables([
        [cmd('-oaa host',Host), cmd('-oaa port', Port)],
옿
∛
       [env('OAA HOST', Host), env int('OAA PORT', Port)],
옿
      [setup('setup.pl',oaa host, Host),
₽
       setup('setup.pl',oaa_port, Port)]
€
     1)
*********************
com ResolveVariables([VarList ]) :-
     com_resolve_variables(VarList), !.
com_ResolveVariables([_VarList|Rest]) :-
     com ResolveVariables (Rest).
com_resolve_variables([]).
com_resolve_variables([env_int(EnvVar, Val)|Rest]) :- !,
     environ (EnvVar, EnvAtom),
     name (EnvAtom, EnvChars),
```

```
number chars(Val, EnvChars),
     com resolve variables (Rest).
com resolve variables([env(EnvVar, Val)|Rest]) :- !,
     environ(EnvVar, Val),
     com resolve variables (Rest).
com resolve variables([cmd(CmdVar, Val)|Rest]) :- !,
     % get command line arguments
     unix(argv(ListOfArgs)),
     append(, [CmdVar, Val], ListOfArgs),
     com resolve variables (Rest).
com_resolve_variables([setup(File,SVar, Val)|Rest]) :- !,
     % read setup file to load all values
     com_read_setup_file(File),
     Pred =.. [SVar, Val],
       on exception(, Pred, fail),
     com resolve variables(Rest).
com read setup file
% name:
% purpose: Finds and loads setup file
% remarks:
s,
    Always succeeds.
    The search path for 'setup.pl' is as follows:
₽
ዩ
      1. Current directory
뫆
      2. Home directory for user
com read setup file(File) :-
     com already loaded(File), !.
com read setup file(File) :-
     ( absolute file name(File, LocalSetupFile),
       can_open_file(LocalSetupFile, read, fail) ->
         SetupFile = LocalSetupFile
       concat('~/',File, HomeName),
       absolute file name (HomeName, UserSetupFile),
         can open file(UserSetupFile, read, fail) ->
           SetupFile = UserSetupFile
     ),
     (ground(SetupFile) ->
        format('Loading setup file:~n ~w~n~n', [SetupFile]),
        ( com consult(SetupFile, ) ->
           assert(com already loaded(File))
        otherwise ->
           format('-w: A problem was encountered in loading the setup file-n',
                ['WARNING'])
        )
     | true).
```

, .

```
com consult(+FilePath, -AbsFileName).
% name:
% purpose:
% remarks: We don't use Quintus' builtin consult, because it's too picky
       about associating predicates with files.
₽
com consult(FilePath, AbsFileName) :-
  absolute file name(FilePath, AbsFileName),
  can open file (AbsFileName, read, fail),
  open (AbsFileName, read, Stream),
  load clauses(Stream),
  close(Stream).
load clauses(+Stream).
% name:
% purpose:
load clauses(Stream) :-
  repeat,
  read_term(Stream, [], Term),
  ( Term = ':-'( Body) ->
    true
  | Term = end of file ->
   true
  | otherwise ->
     load clause (Term)
  ),
  ( at end of file(Stream) ->
    1
  | otherwise ->
   fail
  ).
¥ name:
       load clause (+Term).
% purpose:
load clause (Term) :-
  assert ( Term ).
```

، س، ب



APPENDIX A.IV

Source code file named liboaa.pl.

```
*******
  File : liboaa.pl
₽
욹
  Primary Authors : Adam Cheyer, David Martin
8
   Purpose : Prolog version of library for the Open Agent Architecture
ક્ષ
  Updated : 12/98
¥
÷
   ₽
  Unpublished-rights reserved under the copyright laws of the United States.
웅
¥
웋
  Unpublished Copyright (c) 1998, SRI International.
₽
   "Open Agent Architecture" and "OAA" are Trademarks of SRI International.
₽
     _____
ዩ
¥
% Note: internal functions use the naming convention oaa function name(),
    while public predicates use oaa PublicPredicate().
s.
% Version 2.0 (change oaa_version assertion)
ક
   - corrects FromKS in do events by changing event format to include this
æ
    info.
   - messages are only sent to READY agents. For previous versions, an
₽
₽
    agent may be either READY or just OPEN.
% Version 2.1 (change oaa version assertion)
   - triggers have 2 new arguments, OpMask and Template, and
옿
8
    more general semantics. Backwards compatibility is provided.
% Version 3.0 (change oaa_version assertion)
₽
  - primitives changed to start with oaa (and icl) prefixes
₽
   - Major restructuring and cleanup, including many new capabilities,
¥
    for first public release (a.k.a. "OAA 2")
:- module(oaa,
      [icl GetParamValue/2,
      icl GetPermValue/2,
      icl BasicGoal/1,
      icl GoalComponents/4,
      icl ConsistentParams/2,
      icl BuiltIn/1,
      icl ConvertSolvables/2,
      oaa LibraryVersion/1,
      oaa Register/3,
      oaa RegisterCallback/2,
      oaa ResolveVariables/1,
      oaa_Ready/1,
      oaa MainLoop/1,
      oaa SetTimeout/1,
      oaa_GetEvent/3,
      oaa ProcessEvent/2,
      oaa Interpret/2,
      oaa DelaySolution/1,
      oaa_ReturnDelayedSolutions/2,
      oaa AddDelayedContextParams/3,
```

```
oaa_PostEvent/2,
       oaa CanSolve/2,
       oaa Version/3,
       oaa Ping/3,
       oaa Declare/5,
       oaa DeclareData/3,
       oaa Undeclare/3,
       oaa Redeclare/3,
       oaa AddData/2,
       oaa RemoveData/2,
       oaa ReplaceData/3,
       oaa CheckTriggers/3,
       oaa AddTrigger/4,
       oaa RemoveTrigger/4,
       oaa Solve/2,
       oaa InCache/2,
       oaa_AddToCache/2,
       oaa ClearCache/0,
       oaa TraceMsg/2,
       oaa ComTraceMsg/2,
       oaa Inform/3,
       oaa Id/1,
       oaa Name/1
      ]).
%* RCS Header and internal version
% rcs version number
rcsid('$Header: /home/trestle4/OAA/src/V2/prolog/RCS/oaa.pl,v 1.127 1998/12/23
23:14:18 martin Exp cheyer $').
:- op(599,yfx,::).
% Include files
:- use_module(library(basics)).
:- use_module(library(read sent)).
:- use module(library(lists)).
:- use module(library(sets)).
:- use module(library(strings)).
:- use module(library(files)).
:- use module(library(environ)). % read environment vars
:- use_module(library(ctr)).
:- use_module(library(charsio)). % for sprintf and with_output_to_chars
:- use_module(library(ask)). % for ask_oneof
:- use_module(library(samsort)). % for samsort(Ordered,Raw,Sort)
:- use module(library(date)). % for now(Time)
:- use_module(library(tcp), [tcp_now/1, tcp_time_plus/3]).
% IMPORTANT: COM module. We don't want to hard code the name of the
```

```
% file that contains module 'com'. So, when this file is loaded,
% we first check to see if module 'com' is already present, then
% we check to see if the file containing 'com' has been specified
% on the command line, and if neither of those works, we load the
% default file (./com tcp).
¥
% In the case where the module has already been
% loaded, the following seems like the right thing to do:
     :- use_module(com, _File, all).
₽
% BUT when compiling, this approach results in "undefined" errors from
% gcon. Thus, for now, in oaa.pl, we are explicitly using com: with all
% calls to the com module.
:- ( current_predicate(_, com:_) ->
      use_module(com, _File, all)
  unix(argv(ListOfArgs)), append(_, ['-com', File | _], ListOfArgs) ->
      use module(File, all)
  | otherwise ->
      use_module(com_tcp, all)
  ).
% Global variables
:- dynamic
                               % record if file already loaded
          oaa_already_loaded/1,
              oaa_solvables/1,
                                   % list of agent capabilities
                                   % a built-in solvable
              oaa_trigger/5,
                               % trace mode: on or off
          oaa_trace/1,
          oaa com trace/1, % com trace mode: on or off
          oaa debug/1,
                               % debug mode: on or off
          oaa_cache/2,
                               % cached solutions
          oaa delay/2,
                               % the current goal is delayed
          oaa data ref/3,
                           % bookkeeping for 'data' solvables
          oaa current contexts/2, % Solve parameters to be propagated
                               % Record of app-specific callbacks
          oaa_callback/2,
   % These may appear in setup.pl:
                                   % for root, my host; otherwise,
              oaa_host/1,
                               % host of my parent
                                  % ... similarly ...
              oaa port/1.
oaa_LibraryVersion(3.0).
```

% solvables shared by all agents % Note: all built-in DATA solvables must be declared dynamic to avoid % QP warnings and exceptions. oaa_built_in_solvables([% @@DLM: If we do away with TriggerId, we could use param % unique values(true).

```
solvable(oaa_trigger(_TriggerId, _Type, _Condition, _Action, _Params),
                              [type(data)], [write(true)])
]).
% We'll always have exactly one oaa solvables fact. Note that application
% code should NOT include a declaration or clause for oaa solvables/1.
oaa solvables([]).
***********
% Initialization and connection functions
&****
                                               *********************
oaa Register
% name:
% purpose: Once a comm link is established, either as a client to a Facilitator
% or as a server for other agents, oaa_Register will setup and registration
% information for this agent.
% inputs:
₽
   - ConnectionId: the symbolic connection Id (client or server connection)
욯
   - AgentName: the name of the agent
₽
    - Solvables: solvable list
% remarks:
₽
   The following information is stored about the current connection,
₽
   accessible through com GetInfo(ConnectionId, Info):
€
₽
     oaa name(Name)
                     : the name of the current agent
웋
     oaa id(Id) : the Id for the agent
₽
       connection(C)
                    : system-level communications handle
f
                           (e.g., socket number)
¥
€
   if connecting as client, this is also available:
₽
    fac id(Id) : the Facilitator's Id
₽
     fac name(Name)
                    : the Facilitator's name
욯
     fac_lang(L) : the Facilitator's language
ક્ષ
                     : the version of the Facilitator's agent library
     fac_version(V)
ક્ષ
૪
   In addition, the following predicates are written to parent Facilitator,
ક્ષ
   or locally if the ConnectionId is a server connection:
₽
€
     agent host (Id, Name, Host)
왐
₽
   Solvables are also written using oaa Declare()
€
₽
   It is possible for an agent to create both server and client connections:
윻
   such an agent was classified in OAA 1.0 as an agent of class "node"
ક્ષ
    (as opposed to a pure client "leaf" or pure server "root").
₽
% examples:
黔
   % connecting to a Facilitator
₽
     MySolvables = [do(something)],
g
     com_Connect(parent, ConnectionInfo),
€
     oaa_Register(parent, my_agent_name, MySolvables).
€
¥
   % connecting as a Facilitator
```

```
€
     MySolvables = [],
€
      com ListenAt(incoming, ConnectionInfo),
¥
      oaa Register(incoming, root, MySolvables).
$
% For client connecting to Facilitator
oaa Register(ConnectionId, AgentName, Solvables) :-
      % succeeds only if exists an open client connection for ConnectionId
          as created by com Connect()
      8
      com:com connection info(ConnectionId, Protocol, client, Info,
connected),
      com:com AddInfo(ConnectionId, oaa name(AgentName)),
      % FIXED HACK: default now works thanks to update in com tcp.pl for
          the default mode
      s.
      % HACK!!! Why doesn't this work right without it?
      % for some reason, when we send the handshaking info in
          default mode (instead of quintus_binary), the facilitator's
      ዩ
          tcp select(VerySmallTimeout, Event) doesn't timeout!!!!
      ዩ
          So it keeps hanging until some other event (such as disconnect)
      ₽
          arrives.
      ዩ
      com:com AddInfo(ConnectionId, format(default)),
      % lookupversion number
     oaa LibraryVersion(Version),
      %%% handshaking with Facilitator -- exchange information...
      % note: for this first communication, no format is defined for the
             connection, so it will be sent using default (ascii) format.
     8
     ₽
             Information coming back from Facilitator will update the
     ÷
             format() field for the connection, improving future
     ዬ
             communication.
     com:com SendData(ConnectionId,
           event(ev_connect([oaa name(AgentName), agent_language(prolog),
            format(quintus_binary), agent version(Version)]), [])),
     %% Get the connection acknowledgement:
     % potential bug: what if selected event is NOT from FacId connection?
     oaa_GetEvent(ConnEvent, _Parms, 0),
     ConnEvent = ev connected (FacInfoList),
     com:com AddInfo(ConnectionId, FacInfoList),
     oaa Id(MyId),
       % write host
        ( environ('HOST', MyHost) ->
          oaa_AddData(agent_host(MyId, AgentName, MyHost), [address(parent)])
       | true),
       % Declare solvables (and post to parent facilitator):
       % Note: OK if Solvables = [].
       oaa_Declare(Solvables, [], [], [if_exists(overwrite)], _).
% For Faciliator serving client agents
oaa_Register(ConnectionId, AgentName, Solvables) :-
```

```
% succeeds only if exists an open client connection for ConnectionId
          as created by com Connect()
     com:com connection info(ConnectionId, Protocol, server, Info,
connected),
     AgentId = 0, % A facilitator's ID is always 0
     com:com AddInfo(ConnectionId, [oaa id(AgentId),oaa name(AgentName)]),
     % The fac. records its own agent data in the same way as its clients'.
        % Note that we can't call oaa_add_data_local until after the solvables
        % have been declared, and we can't declare solvables until we're
        % open - so we have to bootstrap this assertion:
       oaa assertz(agent data(AgentId, open, [], AgentName), AgentId, ),
        % Note: OK if Solvables = [].
       oaa Declare(Solvables, [], [], [if_exists(overwrite)], _),
        % write host
        ( environ('HOST', MyHost) ->
          oaa add data local(agent host(AgentId, AgentName, MyHost),[])
```

```
true).
```

```
욲
∛ name:
         oaa ResolveVariables(+VariableList)
% purpose: Tries to instantiate the arguments by looking in the command
       line arguments, environment variables, and setup files
₽
% inputs:
ዮ
               A list of lists: the first sublist that completely resolves
  - VarList:
웊
       provides the value for oaa ResolveVariables.
% remarks:
¥
    sublists may contain elements in the following format:
₽
       env(EnvVar, Val) : looks for "EnvVar" in environment vars
f
     env_int(EnvVar, Val) : Returns value for EnvVar as an integer
움
     cmd(CmdVar, Val) : looks for "CmdVar <Val>" on command line
€
     setup(SVar, Val) : reads SVar from setup file
% example:
€
    resolves host and port by searching first commandline, then environment
₽
    variables, finally reads setup file.
₽
₽
     oaa ResolveVariables([
욲
         [cmd('-oaa host',Host), cmd('-oaa port', Port)],
ક
       [env('OAA HOST', Host), env int('OAA PORT', Port)],
₽
       [setup(oaa host, Host), setup(oaa port, Port)]
₽
     1)
oaa_ResolveVariables([VarList]]) :-
     oaa_resolve variables(VarList), !.
oaa_ResolveVariables([_VarList|Rest]) :-
     oaa_ResolveVariables(Rest).
oaa_resolve_variables([]).
oaa_resolve_variables([env_int(EnvVar, Val)|Rest]) :- !,
```

```
environ(EnvVar, EnvAtom),
     name(EnvAtom, EnvChars),
     number chars(Val, EnvChars),
     oaa resolve variables(Rest).
oaa resolve variables([env(EnvVar, Val)|Rest]) :- !,
     environ(EnvVar, Val),
     oaa resolve variables (Rest).
oaa_resolve_variables([cmd(CmdVar, Val) | Rest]) :- !,
     % get command line arguments
     unix(argv(ListOfArgs)),
     append(_, [CmdVar, Val|_], ListOfArgs),
     oaa_resolve_variables(Rest).
oaa resolve variables([setup(SVar, Val)|Rest]) :- !,
     % read setup file to load all values
     oaa read setup file,
     Pred =.. [SVar, Val],
       on_exception(_, Pred, fail),
     oaa resolve variables (Rest).
*******
        oaa_read_setup_file
% name:
% purpose: Finds and loads setup file
% remarks:
    Always succeeds.
¥
    The search path for 'setup.pl' is as follows:
¥
¥
      1. Current directory
8
      2. Home directory for user
oaa_read_setup file :-
     oaa already loaded(setup), !.
oaa read setup file :-
     ( absolute file name('setup.pl', LocalSetupFile),
       can open file(LocalSetupFile, read, fail) ->
         SetupFile = LocalSetupFile
     absolute_file_name('~/setup.pl', UserSetupFile),
         can open file(UserSetupFile, read, fail) ->
            SetupFile = UserSetupFile
     ),
     (ground (SetupFile) ->
        format('Loading OAA setup file:~n ~w~n', [SetupFile]),
        ( oaa consult(SetupFile, ) ->
           assert (oaa already loaded (setup))
        | otherwise ->
           format('~w: A problem was encountered in loading the setup file~n',
                ['WARNING'])
        )
     | true).
```

```
¥ name:
        oaa Ready
% purpose: Changes the agent's 'open' status to 'ready', indicating that the
۹.
      agent is now ready to receive messages.
% remarks:
₽
   if requested, prints 'Ready' to standard out.
oaa Ready(ShouldPrint) :-
   % replaces 'open' status with 'ready'.
   ((\+ oaa class(root), oaa Name(MySymbolicName)) ->
    oaa PostEvent(ev ready(MySymbolicName), [])
   | true),
   % if ShouldPrint, print ready
   (on_exception(_,ShouldPrint,fail) ->
     format('Ready.~n', [])
   true).
% Classifying and Manipulating ICL expressions
% name:
       icl BuiltIn(+Goal).
% purpose: Test whether an expression is an ICL built-in goal.
% remarks:
8
    - icl_BuiltIn differs significantly from the Quintus Prolog predicate
¥
      built in, in that here we do not include basic constructors such
₽
      as ',' and ';'.
8
    - oaa Interpret/2 must be defined for every goal for which
¥
      icl BuiltIn succeeds.
*********************
icl BuiltIn((_A = _B)).
icl_BuiltIn(( A == B)).
icl BuiltIn(( A = B)).
icl_BuiltIn((_A =< _B)).</pre>
icl_BuiltIn((A \ge B)).
icl_BuiltIn((A < B)).
icl_BuiltIn((A > B)).
icl_BuiltIn(member(_,_)).
icl_BuiltIn(memberchk(_,_)).
icl BuiltIn(findall(_,_,_)).
icl BuiltIn(icl ConsistentParams( , )).
icl BasicGoal(+Goal).
% name:
% purpose: Test whether an expression is an ICL basic (non-compound) goal;
₽
        that is, just a functor with 0 or more arguments.
% remarks:
€
    - Basic goals include built-in's as well as solvables.
z
    - This is a syntactic test; that is, we're not checking whether the
```

% Goal is a declared solvable.

```
icl BasicGoal(Goal) :-
   var(Goal), !, fail.
icl BasicGoal(Goal) :-
   is list(Goal), !, fail.
icl BasicGoal(Goal) :-
   icl_compound_goal(Goal), !, fail.
icl BasicGoal(Goal) :-
   icl BuiltIn(Goal),
   1.
icl BasicGoal(Goal) :-
   Goal = .. [Functor ] ],
   atom(Functor).
icl compound goal(+Goal).
¥ name:
% purpose: Test whether an expression is an ICL compound goal.
***********************
icl_compound_goal(_X:_Y).
icl compound goal (X:: Y).
icl compound_goal((\+ _P)).
icl_compound_goal((_P -> _Q ; _R)).
icl_compound_goal((_P -> _Q)).
icl_compound_goal((_X, _Y)).
icl compound goal((_X ; _Y)).
icl_GoalComponents(+ICLGoal, -A, -G, -P).
% name:
s.
         icl GoalComponents(-ICLGoal, +A, +G, +P).
         icl GoalComponents(+ICLGoal, +A, +G, +P).
₽
% purpose: Assemble, disassemble, or match against the top-level components
         of an ICL goal.
8
% remarks:
8
    - The top-level structure of an ICL goal is Address:Goal::Params,
R
      with Address and Params BOTH OPTIONAL. Thus, every ICL goal
₽
      either explicitly or implicitly includes all three components.
8
    - This may be used with any ICL goal, basic or compound.
    - When P is missing, its value is returned or matched as []. When A is
8
*
      missing, its value is returned or matched as 'unknown'.
% The first 4 clauses handled all cases where the ICL Goal is bound;
% the remainder handle those where it is a var.
icl_GoalComponents(A:G::P, Address, Goal, Params) :-
   + var(A), + var(G), + var(P),
   1,
   Address = A, Goal = G, Params = P.
icl GoalComponents(A:G, Address, Goal, Params) :-
   + var(A), + var(G),
   1,
   Address = A, Goal = G, Params = [].
icl GoalComponents(G::P, Address, Goal, Params) :-
   + var(G), + var(P),
   1,
   Address = unknown, Goal = G, Params = P.
```

```
icl GoalComponents(G, Address, Goal, Params) :-
    + var(G),
   !,
   Address = unknown, Goal = G, Params = [].
icl GoalComponents(Goal, unknown, Goal, []) :-
    !.
icl GoalComponents(Address:Goal, Address, Goal, []) :-
icl GoalComponents(Goal::Params, unknown, Goal, Params) :-
   Ι.
icl GoalComponents(Address:Goal::Params, Address, Goal, Params) :-
   1.
% Permissions and parameter lists
۶
% These procedures are used in processing solvables permissions, and
% parameter lists of all kinds (including those used with solvables,
% those contained in events, and those used in calls to various
% library procedures).
% All permissions and many parameters have default values.
¥
% Permissions and parameters lists have a standard form, as defined by
% the predicates below. To save bandwidth and promote readability, a
% "perm" or "param" list in standard form OMITS default values. For
% easier processing (e.g., comparing/merging param lists), boolean
% params in standard form always include a single argument 'true' or
% 'false'.
% In definitions of solvables and calls to documented library
% procedures, it's OK to include default params in a Params list, if
% desired. For boolean params, when the intended value is 'true', it's
% OK just to specify the functor, for example, instead of
% cache(true), it's OK just to include 'cache'.
% icl_standardize_perms(+Perms, +KeepDefaults, -Standardized).
icl_standardize_perms([], _KeepDefaults, []).
icl_standardize_perms([Perm | Perms], KeepDefaults, [SPerm | SPerms]) :-
   icl perm standard form (Perm, SPerm),
   ( KeepDefaults ; (\+ icl_perm_default(SPerm)) ),
   !.
   icl standardize perms (Perms, KeepDefaults, SPerms).
icl standardize perms([ Perm | Perms], KeepDefaults, SPerms) :-
   icl standardize perms (Perms, KeepDefaults, SPerms).
icl perm standard form(Perm, SPerm) :-
   atom (Perm),
   1.
   SPerm =.. [Perm, true].
icl perm standard form (Perm, Perm).
icl_perm_default(call(true)).
```

```
icl perm default(read(false)).
icl perm default(write(false)).
% icl standardize params(+Params, +KeepDefaults, -Standardized).
% Normally there's no need to keep the default value of a param,
% but there are exceptional situations. If KeepDefaults is true,
% default values are kept.
icl_standardize_params([], _, []).
icl standardize params([Param | Rest], KeepDefaults, AllStandardized) :-
    icl_param_standard_form(Param, FullStandardized),
    ( KeepDefaults ->
      Standardized = FullStandardized
    | otherwise ->
      icl remove default params (FullStandardized, Standardized)
    ),
    icl standardize params (Rest, KeepDefaults, RestStandardized),
    append (Standardized, RestStandardized, AllStandardized).
% icl_param_standard_form(+Param, -StandardParams).
% Maps from an element of a parameter list to a list of elements
% in standardized form. The parameter list element can be from
% any context (from a call to Solve, AddTrigger, AddData, etc.).
icl_param_standard_form(reply(false), [reply(none)]) :-
    1.
    % broadcast has been retained, as a synonym for reply(none):
icl_param_standard_form(broadcast, [reply(none)]) :-
    !.
icl param standard form(broadcast(true), [reply(none)]) :-
    1.
icl param standard form(broadcast(false), [reply(true)]) :-
    1.
icl_param_standard_form(address(Addr), [address(SAddr)]) :-
    1,
    icl standardize address (Addr, SAddr).
icl param standard form(strategy(query), [parallel ok(true)]) :-
icl param standard form(strategy(action),
                  [parallel_ok(false), solution_limit(1)]) :-
    1.
icl_param_standard_form(strategy(inform),
                  [parallel_ok(true), reply(none)]) :-
icl param standard form(callback(Mod:Proc), [callback(Mod:Proc)]) :-
icl param standard form(callback(Proc), [callback(user:Proc)]) :-
    !.
icl param standard form(Param, [SParam]) :-
   atom (Param),
    1,
    SParam =.. [Param, true].
icl param standard form(Param, [Param]).
icl_param_default(from(unknown)).
```

```
icl param default(priority(5)).
icl param default(utility(5)).
icl param_default(if_exists(append)).
icl param default(type(procedure)).
icl param default(private(false)).
icl param default(single value(false)).
icl param default(unique values(false)).
icl param default (rules ok (false)).
icl param default(bookkeeping(true)).
icl param_default(persistent(false)).
icl param default(at beginning(false)).
icl param default (do all(false)).
icl_param_default(reflexive(true)).
icl_param_default(parallel_ok(true)).
icl_param_default(reply(true)).
icl_param_default(block(true)).
icl param default(cache(false)).
icl param default(flush events(false)).
icl_param_default(recurrence(when)).
icl_remove_default_params([], []).
icl remove default params([Param | Rest], Removed) :-
    icl param default (Param),
    1,
    icl remove default params (Rest, Removed).
icl_remove_default_params([Param | Rest], [Param | Removed]) :-
    icl remove default params(Rest, Removed).
% icl GetParamValue(+Param, +ParamList).
윷
% Param must have a functor, but its argument(s) can be either ground
% or variables. E.g., persistent(X).
% To get or test the value of a parameter that has a default, it is
% best to call icl GetParamValue. For a parameter that has no default,
% you can use icl_GetParamValue OR memberchk.
icl_GetParamValue(Param, ParamList) :-
   predicate skeleton(Param, Skel),
   memberchk(Skel, ParamList),
    1,
   Skel = Param.
icl_GetParamValue(Param, _ParamList) :-
   predicate skeleton(Param, Skel),
    icl param default(Skel),
    1,
   Skel = Param.
icl_GetPermValue(Perm, PermList) :-
   predicate skeleton(Perm, Skel),
   memberchk(Skel, PermList),
    !,
   Skel = Perm.
icl_GetPermValue(Perm, _PermList) :-
   predicate skeleton(Perm, Skel),
   icl_perm_default(Skel),
    !,
```

```
Skel = Perm.
```

```
% name:
          icl ConsistentParams(+Test, +ParamList)
% purpose: Often used in solvable declarations to filter on a certain
*
        condition.
% definition:
₽
          Test a param list: if one or more values are given in a parameter
₽
        list for parameter ParamName, then ParamValue must be defined as
8
        one of the values to succeed. If ParamValue is NOT defined, then
¥
        icl ConsistentParams succeeds.
% example:
ક્ર
    A natural language parser agent can only handle English definitions:
웅
¥
        convert(nl, icl,Input,Params,Output) :-
¥
           icl ConsistentParams(language(english), Params).
융
ક્ષ
    if "language (english)" is defined in parameter list of a solve request,
₽
       the nl agent will receive the request.
8
    if "language(spanish)" is defined in the parameter list, the nl agent
¥
       WILL NOT receive the request.
    if no language parameter is specified, the request WILL be sent
ዩ
ક્ષ
    if "language(X)" is specified, the request WILL be sent to the nl agent
% remarks:
    - Test may contain either a single predicate or a list of test predicates,
*
*
      in which case icl ConsistentParams will execute all consistency tests.
    - Interesting note: icl ConsistentParams() checks consistency as a
₽
욯
      relation between the two arguments, so it doesn't matter which argument
      specifies the test list and which the parameters to test.
₽
icl_ConsistentParams(_TestList, []) :- !.
icl_ConsistentParams([], _ParamList) :- !.
icl ConsistentParams([Test|RTest], [P1|RParams]) :- !,
  ParamList = [P1 | RParams],
  predicate_skeleton(Test, TestWithVars),
   (memberchk(TestWithVars, ParamList) ->
     memberchk(Test, ParamList)
  | true),
  icl ConsistentParams(RTest, ParamList).
% either Test or Params is NOT a list
icl ConsistentParams (Test, Param) :-
     (Test = [ ] ->
        NewTest = Test
     NewTest = [Test]),
     (Param = [__] ->
       NewParam = Param
       NewParam = [Param]),
     icl_ConsistentParams(NewTest, NewParam).
% Agent identity and addressing
```

```
% and a local address (or "local ID"). A full address has the form:
                                      for a facilitator (if TCP is protocol)
¥
     addr(tcp(Host,Port))
¥
     addr(tcp(Host,Port), LocalID)
                                    for a client agent.
8
% Even though it doesn't appear in the full address, a facilitator also
% has a local ID, for consistency and convenient reference. The
% local ID of a client agent is assigned to it by its facilitator.
% This, and the facilitator's local ID, are passed to the client at
% connection time.
% Full addresses are globally unique, and local addresses are unique with
% respect to a facilitator. Symbolic names are NOT unique in any sense.
% The local ID happens to be an integer, but developers should not rely
% on this.
% When specifying addresses, in address/1 params for calls to
% oaa_AddData, oaa Solve, etc., either names or addresses may be used.
% In addition, for convenience, reserved terms 'self', 'parent', and
% 'facilitator' may also be used.
8
% More precisely, the address parameter may contain any of the following:
% a full address; a local ID (when the addressee is known to be either
% the facilitator or a peer client); a name, enclosed in the name/1 functor;
% 'self'; 'parent'; or 'facilitator'. ('parent' and 'facilitator are
% synonymous.)
% Address parameters are standardized as follows: A full address for the
% local facilitator or a peer client is changed to the local ID; all
% other full addresses are left as is. Names are left as is. 'self',
% 'parent', and 'facilitator' are changed to the appropriate local ID.
¥
% This can only be used AFTER oaa SetupCommunication has been called,
   % because of the reliance here on com:com connection info/5.
icl_standardize_address(Addr, SAddr) :-
   \+ is_list(Addr),
    !,
   icl_standardize address([Addr], SAddr).
icl standardize address([], []).
icl standardize address([Addr | Addrs], [SAddr | SAddrs]) :-
   icl standardize addressee(Addr, SAddr),
   1,
   icl standardize address (Addrs, SAddrs).
icl standardize address([_Addr | Addrs], SAddrs) :-
   icl standardize address (Addrs, SAddrs).
icl standardize addressee(addr(Addr), ParentId) :-
   com:com GetInfo(parent, addr(Addr)),
   com.com_GetInfo(parent, fac_id(ParentId)),
   !.
icl standardize addressee(addr(Addr), addr(Addr)) :-
   1
icl standardize addressee(addr(Addr, LID), LID) :-
```

```
com:com_GetInfo(parent, addr(Addr)),
    1.
icl_standardize_addressee(addr(Addr, LID), LID) :-
    com:com GetInfo(incoming, addr(Addr)),
    1.
icl standardize addressee(addr(Addr, LID), addr(Addr, LID)) :-
    1.
icl_standardize_addressee(name(Name), name(Name)) :-
    !,
    icl_name(Name).
icl_standardize_addressee(Name, name(Name)) :-
    icl name (Name),
    1,
   format('~w (~w): addressee name, in address/1 param, should be specified
as:~n name(~w)~n',
         ['WARNING', 'liboaa.pl', Name]).
icl standardize addressee(Id, TrueId) :-
    icl true id(Id, TrueId),
    1.
icl_standardize_addressee(Whatever, _) :-
    format('~w (~w): Illegal addressee, in address/1 param, discarded:~n ~w~n',
         ['WARNING', 'liboaa.pl', Whatever]),
    fail.
icl_true_id(self, Me) :-
   1,
   oaa Id(Me).
icl_true_id(parent, Parent) :-
   1,
   com:com GetInfo(parent, fac id(Parent)).
icl_true_id(facilitator, Parent) :-
   1,
   com:com_GetInfo(parent, fac_id(Parent)).
icl true id(Id, Id) :-
   icl_id(Id).
icl id(Num) :-
   integer (Num),
   Num >= 0.
icl_name(self) :-
    !, fail.
icl_name(parent) :-
    !, fail.
icl name(facilitator) :-
    !, fail.
icl name (Atom) :-
   atom(Atom).
% name:
          icl ConvertSolvables(+ShorthandSolvables, -StandardSolvables).
¥
          icl ConvertSolvables(-ShorthandSolvables, +StandardSolvables).
€
% purpose: Convert between shorthand and standard forms of solvables list.
% remarks:
     - In the standard form, each element is a term solvable (Goal,
8
```

```
¥
        Params, Permissions), with Permissions and Params both lists.
€
      In the Permissions and Params lists, values appear only when they
        are OTHER than the default.
¥
¥
      - In the shorthand form, each element can be solvable/3, as above,
€
        or solvable (Goal, Params), or solvable (Goal), or just Goal.
€
      - Note that "shorthand" means "anything goes" - so shorthand
₽
        solvables are a superset of standard solvables.
ક્ર
      - Permissions (defaults in square brackets):
ક્ષ
          call(T F) [true], read(T F) [false], write(T F) [false]
₽
      - Params (defaults in square brackets):
₽
          type (Data Procedure) [procedure],
₽
          callback(Functor) [no default]
ક્ષ
          utility(N) [5]
          synonym(SynonymHead, RealHead) [none]
¥
ક્ષ
          rules ok(T F) [false],
ક્ષ
          single_value(T_F) [false],
۶ł
        unique_values(T_F) [false],
¥
          private(T F) [false]
          bookkeeping(T_F) [true]
¥
ક્ર
          persistent(T F) [false]
옿
      - Refer to Agent Library Reference Manual for details on Permissions
ક્ષ
        and Params.
- (@@DLM) This might be the place to check the validity of solvables,
÷
        such as using only built-ins in tests. Also, check for dependencies
ક્ર
        between solvables; e.g., when persistent(false) is there,
÷.
        bookkeeping(true) must also be there.
icl ConvertSolvables (ShorthandSolvables, StandardSolvables) :-
    var(StandardSolvables),
    1,
    icl standardize solvables (ShorthandSolvables, StandardSolvables).
icl ConvertSolvables(ShorthandSolvables, StandardSolvables) :-
    icl_readable_solvables(StandardSolvables, ShorthandSolvables).
    % icl standardize solvables(+ShorthandSolvables,
                                      -StandardSolvables).
icl_standardize_solvables([], []).
icl standardize solvables([Shorthand | RestSH], [Standard | RestStan]) :-
    icl_standardize_solvable(Shorthand, Standard),
    icl_standardize_solvables(RestSH, RestStan).
    % icl_standardize solvable(+Shorthand, -Standard).
icl standardize solvable(solvable((Goal :- Test), Params, Perms), Standard) :-
    1,
    append([test(Test)], Params, NewParams),
    icl_standardize solvable(solvable(Goal, NewParams, Perms), Standard).
icl standardize solvable(solvable((Goal :- Test), Params), Standard) :-
    1.
    icl_standardize_solvable(solvable(Goal, [test(Test) | Params], []),
                       Standard).
icl standardize solvable(solvable((Goal :- Test)), Standard) :-
    1,
    icl_standardize solvable(solvable(Goal, [test(Test)], []), Standard).
icl_standardize solvable((Goal :- Test), Standard) :-
    !,
    icl_standardize_solvable(solvable(Goal, [test(Test)], []), Standard).
```

```
icl standardize solvable(solvable(Goal, Params, Perms),
                  solvable(Goal, NewParams, NewPerms)) :-
    1,
   icl standardize params (Params, false, NewParams),
   icl standardize perms (Perms, false, NewPerms).
icl standardize solvable(solvable(Goal, Params),
                  solvable(Goal, NewParams, [])) :-
    1,
   icl standardize params (Params, false, NewParams).
icl standardize solvable(solvable(Goal), solvable(Goal, [], [])) :- !.
icl standardize solvable(Goal, solvable(Goal, [], [])) :- !.
   % icl readable solvables(+StandardSolvables,
                                    -ShorthandSolvables).
   % This is provided for use in "pretty-printing" solvables, in trace
   % messages, etc.
icl readable solvables([], []).
icl readable solvables([Standard | RestStan], [Shorthand | RestSh]) :-
   icl_readable_solvable(Standard, Shorthand),
   icl readable solvables (RestStan, RestSh).
   % icl_readable_solvable(+Standard, -Shorthand).
icl_readable_solvable(solvable(Goal, [], []), Goal) :- !.
icl readable solvable(solvable(Goal, Params, []), solvable(Goal, Params)) :- !.
icl readable solvable(solvable(Goal, Params, Perms),
                 solvable(Goal, Params, Perms)) :- !.
% name:
          icl minimally instantiate solvables(+ShorthandSolvables,
8
                                             -MinimalSolvables).
% purpose: Convert from shorthand (or standard form) to minimally instantiated
ዩ
          solvables list.
% remarks: - This is special-purpose. It's used to massage a list of solvables
            that are to be UNdeclared, to make sure each of them will unify
ક્ષ
ક્ર
            with some existing solvable. Perms and Params are completely
¥
            ignored in the unification; only the Goal is relevant. So each
¥
            minimally instantiated solvable is simply solvable (Goal, _, _).
8
          - Note that "shorthand" means "anything goes" - so shorthand
            solvables are a superset of standard solvables.
% icl_minimally instantiate solvables(+ShorthandSolvables,
                                        -Solvables).
icl minimally instantiate solvables([], []).
icl minimally instantiate solvables ([Shorthand | RestSH],
                           [Minimal | RestMin]) :-
   icl minimally instantiate solvable (Shorthand, Minimal),
   icl minimally instantiate solvables (RestSH, RestMin).
   % icl minimally instantiate solvable(+Shorthand, -Minimal).
icl_minimally_instantiate_solvable(solvable((Goal :- _Test), Params, Perms),
                         Minimal) :-
   icl_minimally_instantiate_solvable(solvable(Goal, Params, Perms),
                             Minimal).
icl_minimally_instantiate_solvable(solvable((Goal :- _Test), Params),
                         Minimal) :-
```

```
!,
   icl minimally instantiate solvable(solvable(Goal, Params, []), Minimal).
icl minimally instantiate solvable(solvable((Goal :- Test)), Minimal) :-
    1,
   icl minimally instantiate solvable(solvable(Goal, [], []), Minimal).
icl minimally instantiate solvable((Goal :- _Test), Minimal) :-
    !,
   icl minimally instantiate solvable(solvable(Goal, [], []), Minimal).
icl minimally instantiate solvable (solvable (Goal, Params, Perms),
                  solvable(Goal, _, _)) :-
    1.
icl_minimally_instantiate_solvable(solvable(Goal, _Params),
                  solvable(Goal, _, _)) :-
    1.
icl minimally_instantiate_solvable(solvable(Goal), solvable(Goal, _, _)) :- !.
icl minimally instantiate solvable(Goal, solvable(Goal, , _)) :- !.
oaa goal matches_solvables(+Goal, +Solvables,
% name:
                                    -RealGoal, -MatchedSolvable).
₽.
% purpose: Determine whether a call to Goal is handled by the agent with
z
          these Solvables.
% arguments:
     - Goal must be non-compound (basic) to match: no address, no params,
ક
¥
       no subgoals.
     - Solvables must be in standard form.
¥
     - RealGoal is what should actually be called, after taking synonyms
움
움
       into account.
욹
     - MatchedSolvable is the solvable record corresponding to RealGoal.
% remarks:
윻
   - A solvable's params may contain a single test, but it can
¥
       be compound:
₽
       solvable(g(X), [test((X > 1, X < 10))], [...]).</pre>
₽
       Tests should contain only prolog builtins.
   - Any solvable can be a synonym of another solvable (including a
욯
¥
       synonym of a synonym), but eventually there must be a non-synonym
욯
       solvable. Synonyms must be used with care. If predicate A
욯
       is synonymed to predicate B, there must be a solvable for clause B,
₽
       for A to be usable.
₽
   - When a predicate A is synonymed to predicate B, all other params
₽
       and all permissions associated with A are ignored.
   - Uses would unify (and + +) so that any variables in the goal are
₽
₽
       not bound by the solvable, thereby unnecessarily constraining query
€
       I forget why: I think it was because we had some problems
옿
       matching solutions coming back. However, this has an unusual
€
       side effect: if your solvable is t(6) and your query is t(X),
€
       the query arrives at the agent as t(X), not t(6), which might
욹
       be unexpected. Look into this more someday ...
      However, when Goal is a synonym, variables in the synonym param DO
¥
¥
      get unified correctly.
oaa_goal_matches_solvables(Goal, Solvables, RealGoal, RealMatched) :-
   oaa built_in_solvables(BuiltIns),
   append(BuiltIns, Solvables, AllSolvables),
   oaa_goal_in_solvables(Goal, AllSolvables, Matched),
   Matched = solvable(, Params, ),
```

```
% See if Goal is a synonym predicate
    ( icl GetParamValue(synonym(Goal, SynGoal), Params) ->
       oaa qoal matches solvables (SynGoal, Solvables, RealGoal, RealMatched)
    | otherwise ->
       RealGoal = Goal,
     RealMatched = Matched
   ),
   1.
% name:
          oaa goal in solvables(+Goal, +Solvables, -MatchedSolvable).
% purpose: Determine whether a call to Goal is handled by the agent with
£
          these Solvables.
% purpose: Determine whether Goal appears in Solvables, with
          appropriate Params and Perms for it to be called.
8
% arguments:
¥
     - Goal must be non-compound (basic) to match: no address, no params,
욹
       no subgoals.
$
     - Solvables must be in standard form.
% remarks:
   - Should not be called directly; only by oaa goal matches solvables.
8
oaa goal in solvables (Goal, [solvable (G1, Params, Perms) | Rest],
                solvable(G1, Params, Perms)) :-
     would unify (Goal, G1),
       icl_GetParamValue(synonym(Goal, _RealGoal), Params),
     1.
oaa goal in solvables (Goal, [solvable (G1, Params, Perms) | Rest],
                solvable(G1,Params,Perms)) :-
     would unify (Goal, G1),
     icl GetPermValue(call(true), Perms),
     ( icl_GetParamValue(test(T), Params) ->
         + + oaa_Interpret((Goal = G1, T), [])
     | otherwise ->
         true
     ),
     1.
oaa_goal_in solvables(Goal, [_|Rest], Matched) :-
     oaa_goal_in_solvables(Goal, Rest, Matched).
% name:
         oaa data matches solvables (+Clause, +Solvables, +Perm
₽
                                   -RealClause, -MatchedSolvable).
% purpose: Determine whether Clause can be read or written by the agent with
         these Solvables, and return the "real" form of the clause that
8
₽
          takes synonyms into account.
% arguments:
     - Clause must be non-compound (basic) to match: no address, no params,
*
₽
      no subClauses.
¥
     - Solvables must be in standard form.
     _ Perm is 'read' or 'write'.
- RealClause is what should actually be used (asserted, retracted,
8
¥
¥
       replaced).
æ
     - MatchedSolvable is the solvable record corresponding to RealClause.
% remarks:
```

```
¥
     "Writing" means making an assertion.
     "Reading" is different than "calling". "Reading" is retrieving the
¥
8
       definition clauses of a predicate (including the bodies, if any).
¥
       Reading is not currently supported by any library procedures.
¥
     Any solvable can be a synonym of another solvable (including a
뭉
       synonym of a synonym), but eventually there must be a non-synonym
¥
       solvable. Synonyms must be used with care. If predicate A
¥
       is synonymed to predicate B, there must be a solvable for clause B,
욹
       for A to be usable.
     When a predicate A is synonymed to predicate B, all other params
¥
s.
       and all permissions associated with A are ignored.
oaa_data_matches_solvables(Clause, Solvables, Perm, RealClause, RealMatched) :-
   oaa built in solvables (BuiltIns),
   append(BuiltIns, Solvables, AllSolvables),
   oaa_data in solvables(Clause, AllSolvables, Perm, Matched),
   Matched = solvable(_, Params, _),
    ( Clause = (Head :- Body) ->
     true
    | otherwise ->
     Head = Clause
   ),
   % See if Clause is a synonym predicate
    ( icl GetParamValue(synonym(Head, SynHead), Params) ->
       ( Clause = (Head :- Body) ->
         SynClause = (SynHead :- Body)
     | otherwise ->
         SynClause = SynHead
     ),
       oaa data matches_solvables(SynClause, Solvables, Perm,
                              RealClause, RealMatched)
   | otherwise ->
       RealClause = Clause,
     RealMatched = Matched
   ),
   Ι.
oaa data in solvables(+Clause, +Solvables, +Perm, -MatchedSolvable).
% name:
% purpose: Determine whether (the Head of) Clause appears in Solvables, with
٩
         appropriate Params and Perms for it to be read or written.
% arguments:
¥
     - Clause must be non-compound (basic) to match: no address, no params,
9
       no subClauses.
     - Solvables must be in standard form.
٩.
% remarks:
     - Should not be called directly; only by oaa data matches solvables.
æ
oaa_data_in_solvables(Clause, [solvable(G1,Params,Perms) | _Rest], _Perm,
                solvable(G1,Params,Perms) ) :-
       ( Clause = (Head :- _Body) ->
          true
     | otherwise ->
         Head = Clause
     would unify (Head, G1),
       icl_GetParamValue(synonym(Head, _RealHead), Params),
```

```
% @@DLM: OK, so it's a synonym, but shouldn't we check
    % the permissions and type(data) for the referenced solvable?
     1.
oaa data in solvables(Clause, [solvable(G1, Params, Perms) | Rest], Perm,
              solvable(G1, Params, Perms) ) :-
      icl GetParamValue(type(data), Params),
      ( Clause = (Head :- _Body) ->
         icl GetParamValue( rules ok(true), Params)
     | otherwise ->
        Head = Clause
    ),
    would unify (Head, G1),
     ( Perm == write ->
        icl GetPermValue(write(true), Perms)
     | otherwise ->
        icl GetPermValue(call(true), Perms)
    ),
     1
oaa_data_in_solvables(Clause, [ |Rest], Perm, Matched) :-
    oaa_data_in_solvables(Clause, Rest, Perm, Matched).
% Retrieving and managing events
&**********************
                        ************
*************************
% name:
        oaa MainLoop
% purpose: The main event loop for the application.
8
        Reads an event, executes (interprets) it,
옿
       checks on receive triggers for the event,
*
       checks any application-dependent triggers,
**********************
oaa_MainLoop(ShouldPrint) :-
   oaa Ready (ShouldPrint),
   repeat,
     oaa GetEvent (Event, Params, 0),
     oaa ProcessEvent (Event, Params),
   fail.
% name: oaa ProcessEvent
% purpose: Interprets an incoming event
    - For a timeout, checks task triggers and calls user's idle procedure
욯
¥
    - Otherwise, oaa Interprets the event, checks on receive comm
¥
     triggers, and then checks task triggers.
oaa_ProcessEvent(timeout, _Params) :- !,
    oaa_CheckTriggers(task, _, _), !,
    oaa_call_callback(app_idle, _, []).
oaa_ProcessEvent(Event, Params) :-
```

```
( oaa Interpret(Event, Params) -> true | true ),
      oaa CheckTriggers(task, , ), !.
oaa SetTimeout
% name:
% purpose: Sets the timeout value used by oaa GetEvent
oaa SetTimeout(NSecs) :-
     % Make sure NSecs is valid number
     number (NSecs),
     (NSecs < 0 ->
       TimeOut = 0
      TimeOut = NSecs),
     oaa TraceMsg('~nSetting event timeout to ''~q''.~n', [TimeOut]),
     on_exception(_,retractall(oaa_timeout(_)), true),
     assert(oaa timeout(TimeOut)).
oaa GetEvent
% name:
% purpose: Return the next event to execute
% remarks:
₽
    - if a oaa timeout(Secs) is set to a positive real number by
      oaa SetTimeout, wait Secs for an event.
₽
₽
      If none arrives in this time, return Event = `timeout'
웋
    - Reads ALL events available on communication stream, sorts the events
₽
      according to priority, chooses the next event to execute,
₽
      and then saves the rest for next time oaa GetEvent is called.
₽
    - The communication stream is read every time oaa GetEvent is called, even
욯
      if there are already saved events (a new one might have a higher
s.
     priority!)
¥
    - If saved events exist, return immediately (timeout not considered).
oaa_GetEvent(Event, Params, LowestPriority) :-
     % see if previously saved events to process
     ( retract(oaa event buffer(SavedEvents)) ->
        true
     | otherwise ->
        SavedEvents = []
     ),
     % If at least one event can be found with an appropriate priority
         from among the saved events, no timeout needed -- flush tcp
         buffer, and read all available
     (oaa choose event(LowestPriority, SavedEvents, OneEvent, Remainder) ->
       TimeoutSecs = 0.01
       on exception(_,oaa timeout(TimeoutSecs),TimeoutSecs=0)
     TimeoutSecs=0
    ),
     oaa_read all events(TimeoutSecs, MoreEvents, FlushPriority),
     % if one of the new events has a flush in it, see if it
```

```
flushes any of the saved events
     % note: MoreEvents have already been flushed by FlushPriority
     oaa flush events (SavedEvents, FlushPriority, RemainingSavedEvents),
     % These are the events we've read so far and haven't executed yet...
     append (RemainingSavedEvents, MoreEvents, EventList),
     (oaa sort and get event (EventList, LowestPriority, Event, Params) ->
       % we are able to find an appropriate event from list
       % The event will be returned, so fire triggers on it
         oaa CheckTriggers (comm, event (Event, Params), receive)
     % no good event found, return timeout
       Event = timeout,
       Params = []
     ),
       % This cut is essential to avoid faulty behavior (DLM):
      1.
oaa sort and get event
¥ name:
% purpose: Sort raw events by priority, choose the highest priority event
¥
    or FirstIn if equal priority, extract event data and sender,
¥
    and store the rest of events
% remarks:
    The chosen event must be of HIGHER priority than LowestPriority, and
    oaa sort and get event can fail if no appropriate event is found
ક્ષ
oaa sort and get event(EventList, LowestPriority, Event, Params) :-
     samsort (oaa priority compare, EventList, SortedList),
     oaa_choose_event(LowestPriority, SortedList, RawEvent, Remainder),
     oaa_extract_event(RawEvent, Event, Params),
     (Remainder = [];
     assert(oaa event buffer(Remainder))),
     !.
oaa priority compare(E1, E2) :-
     oaa_extract_event_param(E1, _, priority(P1)),
     oaa extract_event_param(E2, _, priority(P2)),
     !, P1 >= P2.
% name: oaa choose event
% purpose: Extracts the first event from a list which has a HIGHER priority
       than the required lowest. Fails if none found.
₽
oaa_choose_event(LowestPriority, [Event|Remainder], Event, Remainder) :-
      oaa_extract_event_param(Event, _, priority(P)),
      Lowest Priority < P,
      1.
oaa_choose event(LowestPriority, [E|Rest], Event, [E|Rest2]) :-
      oaa choose event (Lowest Priority, Rest, Event, Rest2).
```

```
% name:
          oaa read all_events
% purpose: Flush the communication event queue, reading ALL available events and
          returning a list of them, or empty list if none available.
Ŷ.
% remarks:
웅
    - Events are retrieved in raw (unextracted) form.
ક
    - We check to make sure the event is Validated (security hook)
€
      before returning it
¥
    - We check to see if the event is flushed by a later event.
¥
      If so, we notify event sender of the flush and we don't return the
₽
      event.
oaa read all events (TimeOut, Events, FlushPriority) :-
     oaa select event(TimeOut, E), !,
     (E == timeout ->
        Events = [],
        FlushPriority = 0
                           % lowest event priority: don't flush events
     % read one event, so read all the rest
        oaa read all events(0.0001, RestEvents, RestFlushPriority),
        % check if read Event is acceptable (security hook)
        (oaa ValidateEvent(E,OkEvent) ->
           oaa ComTraceMsg('~n[COM received]:~n ~q~n', [OkEvent]),
           % get event's priority
           oaa extract event param(OkEvent, , priority(P)),
           % if less than some higher priority flush event, discard event
               and perhaps notify sender
           (P < RestFlushPriority ->
            % event will be removed,
            oaa flush notification(OkEvent),
            FlushPriority = RestFlushPriority,
            Events = RestEvents
            % keep event: not flushed
             Events = [OkEvent | RestEvents],
            % see if this event adds a flush:
               if so record new flush priority
              (oaa event param(OkEvent, flush events(true)) ->
              FlushPriority = P
              FlushPriority = RestFlushPriority)
           }
        % Not validated, skip event
        Events = RestEvents)
     ).
% name:
         oaa ValidateEvent
% purpose: Check that an incoming lowlevel event should be processed.
٠
          This is the place to put security checks on events.
    The default behavior defined by the library can be made more
¥
    stringent by individual agents using the callback oaa AppValidateEvent
```

```
% remarks:
```

```
oaa ValidateEvent has the right to modify the incoming event,
Ł
   or refuse it altogether by failing.
oaa ValidateEvent(E,OkEvent) :-
    % if oaa AppValidateEvent is defined, use it.
    predicate property(user:oaa AppValidateProperty(_,_), _),
    1,
    user:oaa AppValidateProperty(E, OkEvent).
% currently, no security checks are performed
oaa_ValidateEvent(OkEvent,OkEvent).
% name:
        oaa flush events
% purpose: Flushes any events with a lower priority than the FlushPriority
***********************
oaa flush events([], FlushPriority, []).
oaa flush events([Event|RestEvents], FlushPriority, RemainingEvents) :-
    oaa flush events (RestEvents, FlushPriority, RestSaved),
    % get event's priority
    oaa extract event param(Event, , priority(P)),
    % if lower priority than we are flushing, notify and remove
    (P < FlushPriority ->
      oaa flush notification(Event),
      RemainingEvents = RestSaved
      RemainingEvents = [Event | RestSaved]
    ).
% name: oaa flush notification
* purpose: Given a raw event, grabs its real event and looks up whether
        a notification should be sent out regarding the event's
ዮ
      cancellation due to a flush.
÷
oaa flush notification(RawEvent) :-
    oaa extract_event(RawEvent, Event, Params),
    (oaa get flush notify(Event, NotifyEvent) ->
      oaa PostEvent(NotifyEvent, [])
    | true), !.
% name: oaa get flush notify
% purpose: Records a list of events which require a return notification
      if the event is flushed.
¥
% remarks:
   currently, only the ev solve() event returns a message;
   all other events are flushed without notification
¥
% @@Additional entries needed here:
oaa_get_flush_notify(ev_solve(ID, Goal, Params),
             ev solved(ID, FromMe, Goal, Params, [])) :-
```

```
(icl_GetParamValue(reply(none), Params) ->
    fail
    l oaa Id(FromMe)).
```

```
% name: oaa select event
% purpose: If a positive timeout is defined, wait N seconds for an event
s.
    to arrive
    Otherwise block-wait until an event arrives.
*
% remarks: IMPORTANT: Connected/1 gets special handling, because we want
         the connection ID and oaa ID to be assigned immediately.
₽
         Otherwise, oaa translate incoming event and oaa unwrap event
¥
         won't always work properly for subsequent events from the
옿
         new connection (or would have to be more complicated).
¥
oaa select event (TimeOut, Event) :-
     com:com SelectEvent(TimeOut, InEvent),
     ( InEvent = connected( ) ->
        oaa ProcessEvent(InEvent, []),
        oaa select event (TimeOut, Event)
     | otherwise ->
        oaa translate incoming event (InEvent, TranslatedEvent),
        oaa unwrap event(TranslatedEvent, Connection, Event)
     ).
oaa unwrap event(+TranslatedEvent, -Connection, -Event).
% name:
% arguments: TranslatedEvent: An event from another agent, which has already
웋
           been translated for version compatibility, if necessary.
           Event: An event term in our standard internal format, as required
₽
₽
              by all other library procedures.
욹
           Connection: The CONNECTION of the immediate agent
¥
              from which this message came (note that an agent's CONNECTION
Ŷ
              can be different than its ID).
% purpose: Remove an event term from its communications wrapper (if any),
¥
         and returns it in our standard internal form:
₽
         'timeout' OR event (Content, Params).
% timeout is the ONLY event that doesn't get embedded in event/2:
oaa_unwrap_event(timeout, unknown, timeout) :-
   !.
oaa_unwrap_event(term(Connection, event(Content, Params)), ConnectionId,
              event(Content, NewParams)) :-
   !,
   ( com:com GetInfo(ConnectionId, connection(Connection)) ->
     true
   | otherwise ->
     format(
        '-w: incoming event from an unrecognized connection (-w):-n -w-n',
       ['INTERNAL ERROR', Connection, event(Content, Params)]),
       ConnectionId = unknown
   ),
   ( memberchk(from( ), Params) ->
      NewParams = [connection_id(ConnectionId) | Params]
   Content = ev_connected(InfoList),
```

```
memberchk(fac id(Id), InfoList) ->
       NewParams = [from(Id), connection id(ConnectionId) | Params]
    ConnectionId = parent,
     com:com GetInfo(ConnectionId, fac id(Id)) ->
       NewParams = [from(Id), connection id(ConnectionId) | Params]
    com:com GetInfo(ConnectionId, oaa id(Id)) ->
       NewParams = [from(Id), connection id(ConnectionId) | Params]
    otherwise ->
     % With current code, this should never happen. But I can
     % imagine code changes that might need this (DLM 98/02/18):
       NewParams = [from(unknown), connection id(ConnectionId) | Params]
   ).
% This handles connected/1, end of file/1, wakeup/1:
oaa unwrap event(Content, unknown, event(Content, [])).
% name: oaa translate incoming event(+InEvent, -OutEvent).
% purpose: Provides backwards compatibility by calling a hook
    (user:oaa event translation/7) that translates incoming events from agents
of
    other versions. Also allows for event differences based on language.
¥
$
    The idea is to return an event with both format and contents that
₽
    are appropriate for the agent receiving the event.
% remarks: user:oaa event translation/7 can be hard-coded, loaded at runtime,
    or whatever. If it's not present, we return the same event.
욹
    Note that the translation hook is somewhat limited. It allows a single
¥
    event to be translated to another single event, and with essentially
8
*
    no information about context. This inadequate or awkward for some cases.
ջ
    Those cases are handled using extra clauses of user: oaa AppDoEvent (in
웈
    translations.pl).
% Special cases. There's no need to translate these. And, it could be
% problematical, because we don't yet know the language and version of
% the sender.
oaa_translate incoming event(term(Conn, event(Contents, Params)),
                     term(Conn, event(Contents, Params))) :-
     ( Contents = ev connect( ) ;
       Contents = ev connected()),
   !.
oaa translate incoming event (term (Connection, InEvent),
                     term(Connection, OutEvent)) :-
   current predicate (oaa event translation,
                user:oaa_event_translation(_,_,_,_,_,_)),
   ( com:com GetInfo(ConnectionId, connection(Connection)) ->
     true
```

```
),

% These assumptions may not always be right, but will

% nearly always get the desired results.
```

```
% :
( ground(ConnectionId),
```

| otherwise ->

true

```
com:com GetInfo(ConnectionId, agent version(PriorVersion)) ->
     true
   | otherwise ->
     PriorVersion = 2.1
   ),
   ( ground (ConnectionId),
    com:com GetInfo(ConnectionId, agent language(PriorLanguage)) ->
     true
   | otherwise ->
     PriorLanguage = c
   ),
   oaa LibraryVersion(MyVersion),
   ( MyVersion \== PriorVersion ; PriorLanguage \== prolog ),
   user:oaa event translation(PriorVersion, PriorLanguage, MyVersion, prolog,
                  Connection, InEvent, OutEvent),
   !.
% This handles timeout/0, connected/1, end of file/1, wakeup/1.
% Also passes through any event for which there is no translation.
oaa_translate_incoming_event(Event, Event) :- !.
oaa extract event
% name:
% purpose: Extract the content and parameters from an event term.
% remarks: Always succeeds.
9
       The content part of the term is often (loosely) called the Event.
oaa extract event(event(Content, Params), Content, Params) :-
  1.
% name:
       oaa extract event param
% purpose: Extract the content and a parameter value from an event term.
% remarks: Always succeeds - unless you ask for a param that has no default
*
       value.
₽
       The content part of the term is often (loosely) called the Event.
oaa extract event param(event(Content, Params), Content, Param) :- !,
     icl GetParamValue(Param, Params).
oaa event param
% name:
% purpose: Extract a parameter from an event term.
% remarks: This FAILS if the parameter isn't present (unlike
        oaa extract event param).
oaa_event param(event( Content, Params), Param) :- !,
     memberchk(Param, Params).
% Interpreting EVENTS
```

```
oaa Interpret(+ICLExpression, +Params)
% name:
% purpose: Executes an incoming event
% remarks: Implements a simple meta-interpreter for executing complex goals.
         Agent goals are interpreted by oaa exec event().
₽
€
ⴻ
         The contents of Params will vary depending on context.
욯
        When oaa Interpret is called on an incoming event, Params
8
        will (usually) include from (Sender). Calls generated internally
₽
        may contain from(self). Additional params may
æ
        accumulate through recursive calls to oaa Interpret.
**********************
oaa_Interpret(Goal, _) :- var(Goal), !, fail. % How could this happen?
oaa_Interpret(true, _) :- !.
oaa_Interpret(fail, _) :- !, fail.
oaa_Interpret(false, _) :- !, fail.
oaa Interpret((\+ P), Params) :- !, \+ oaa Interpret(P, Params).
oaa_Interpret((P -> Q ; _R), Params) :-
   oaa_Interpret(P, Params), !, oaa Interpret(Q, Params).
oaa_Interpret((_P -> _Q ; R), Params) :- !, oaa_Interpret(R, Params).
oaa_Interpret((P -> Q), Params) :- !, oaa_Interpret((P -> Q ; fail), Params).
oaa Interpret((X, Y), Params) :- !,
   oaa_Interpret(X, Params), oaa_Interpret(Y, Params).
oaa Interpret((X ; Y), Params) :- !,
    (oaa_Interpret(X, Params) ; oaa_Interpret(Y, Params)).
oaa Interpret(findall(Var, Goal, All), Params) :- !,
   findall(Var, oaa Interpret(Goal, Params), All).
oaa_Interpret(P, _Params) :- icl_BuiltIn(P), !, call(P).
oaa Interpret(X, Params) :- oaa exec event(X, Params).
% name:
         oaa exec event
% purpose: Defines execution of events built into all agents
% remarks: Goals that can't be handled by oaa exec event are passed to the
s.
         user-declared app do event callback, if present.
% turn on trace
oaa_exec_event(ev_trace_on, _) :-
     abolish(oaa trace/1),
     assert(oaa_trace(on)),
     format('~nTrace on.~n', []), !.
% turn off trace
oaa exec event(ev trace_off, _) :-
     abolish(oaa trace/1),
     assert(oaa trace(off)),
     format('~nTrace off.~n', []), !.
% tcp level trace
oaa_exec_event(ev com trace on, ) :-
     abolish(oaa com trace/1),
     assert (oaa com trace (on)),
     format('~nCOMMUNICATION PROTOCOL trace on.~n', []), !.
% tcp level trace
```

```
oaa exec event(ev com trace off, ) :-
      abolish(oaa_com_trace/1),
      assert(oaa com trace(off)),
      format('~nCOMMUNICATION PROTOCOL trace off.~n', []), !.
% turn on debug
oaa exec event (ev debug on, ) :-
      abolish(oaa_debug/1),
      assert (oaa debug (on)),
      format('~nDebug on.~n', []), !.
% turn off debug
oaa_exec_event(ev_debug_off, _) :-
      abolish (oaa debug/1),
      assert (oaa_debug(off)),
      format('~nDebug off.~n', []), !.
% Set the timeout value
oaa_exec_event(ev_set_timeout(N), _) :-
      abolish(timeout/1),
      assert(timeout(N)),
      format('~nTimeout set to ~q.~n', [N]), !.
% Notification that some other agent has disconnected. Currently, this applies
% only to peer client agents, and the arg. will always be a local ID.
oaa exec_event(ev_agent_disconnected(LID), _) :-
        oaa_remove_data_owned_by(LID).
% quit to UNIX
oaa_exec_event(ev_halt, _) :-
      format('~nDisconnecting...~n', []),
      com:com Disconnect(parent),
      ( oaa_call_callback(app_done, _, []) ; true ),
      halt.
oaa_exec_event(ev update(ID, Mode, Clause, Params), EvParams) :-
      oaa_Id(AgentId),
      append(Params, EvParams, AllParams),
      (Mode = add ->
          Functor = oaa add data local
      Mode = remove ->
          Functor = oaa_remove_data_local
      | Mode = replace ->
          Functor = oaa_replace data local
      ).
      Call = .. [Functor, Clause, AllParams],
      ( call(Call) ->
          Updaters = [AgentId]
      | otherwise ->
          Updaters = []
      ).
      (icl GetParamValue(reply(none), AllParams) -> true |
           oaa_PostEvent(ev_updated(ID, Mode, Clause, Params, Updaters),
                   [])
      ).
```

```
% add or remove a local trigger
oaa exec_event(ev update trigger(ID, Mode, Type,
                         Condition, Action, TrigParams),
             Params) :-
      oaa Id(AgentId),
      append (TrigParams, Params, NewParams),
      ( Mode == add ->
          Functor = oaa_add_trigger_local
      Mode == remove ->
          Functor = oaa_remove_trigger local
      ),
      Call = .. [Functor, Type, Condition, Action, NewParams],
      ( call(Call) ->
          Updaters = [AgentId]
      | otherwise ->
          Updaters = []
      ),
      ( icl GetParamValue(reply(none), Params) ->
         true
      | otherwise ->
           oaa PostEvent(ev_trigger updated(ID, Mode, Type, Condition,
                                  Action, TrigParams, Updaters),
                   [])
      ),
      (Mode = add ->
            oaa Inform(trigger, 'trigger added(~q,~q,~q,~q)~n',
                   [Type, Condition, Action, NewParams])
      true
      ).
% When asked to solve a goal, see if you know how to solve
% it, then find all solutions. Send the solutions to the
% caller.
% The various params lists must be used with care. Searching different
% lists may be appropriate for different params, depending on their
% meanings. Another consideration is that Solve params and Goal params,
% as returned to the requesting agent, must unify with the original
% lists that came from the requesting agent.
oaa_exec_event(ev_solve(ID, FullGoal, SolveParams), Params) :-
     oaa class(leaf),
        icl GoalComponents(FullGoal, , , GoalParams),
        % More "local" params take precedence, so they go to the
      % beginning of the list:
     append([SolveParams, Params], InheritedParams),
     append([GoalParams, InheritedParams], AllParams),
     % Assert context:
     findall(context(C), member(context(C), AllParams), Contexts),
     asserta( oaa_current_contexts(ID, Contexts) ),
     oaa_TraceMsg('~n~nAttempting to solve:~n Goal:~q~n Params:~q~n',
                   [FullGoal, InheritedParams]),
        findall (FullGoal,
                oaa_solve_local(FullGoal, InheritedParams),
            Solutions),
```

```
oaa TraceMsg('~nSolutions found for ~q:~n
                                                     ~q~n',
                       [FullGoal, Solutions]),
      % If user has requested to delay the solution (oaaDelaySolution)
      % save current userId, Goal and Params in delay table, to be
      % sent back in an ev solved() msg later (oaaReturnDelayedSolutions).
      (retract(oaa delay(ID, UserId)) ->
         assert(oaa_delay_table(ID, UserId, FullGoal, SolveParams, AllParams))
         (icl GetParamValue(reply(none), AllParams) -> true |
            (oaa Id(FromKS) ; FromKS = unknown), !,
              oaa PostEvent (ev solved (ID, FromKS, FullGoal, SolveParams,
                                   Solutions), [])
         )
      ),
      % Retract context:
      retractall( oaa current_contexts(ID, ) ).
% This is for subgoals (of goals passed in solve events) that have
% Params. Subgoals with no params will fall through to the next clause.
oaa exec event(Goal::GoalParams, Params) :-
        oaa solve local(Goal::GoalParams, Params).
% call user events. Must not have a cut, to return all solutions.
oaa exec event (Event, Params) :-
      oaa turn on debug,
      ( oaa_solvables(Solvables) -> true | otherwise -> Solvables = []),
      ( (oaa goal matches solvables (Event, Solvables, Goal, Matched),
         Matched = solvable(_, SolvParams, _),
         (icl GetParamValue(callback(CB), SolvParams) ;
          oaa callback(app do event, CB)))
      ;
        (oaa callback(app do event, CB),
        Goal = Event)
      ),
      1,
      ( CB = Module:Functor ->
          true
      | otherwise ->
         Module = user,
          Functor = CB
      ),
      Call = .. [Functor, Goal, Params],
      on exception(E,
        Module:Call,
         ( oaa TraceMsg('WARNING (agent.pl): Exception raised thru callback
handler (~w):~n ~q~n',
                    [Functor, E]),
           fail )),
     oaa_turn_off_debug.
% What to do about test(TEST)?
% if test(TEST) is listed in arguments, solve
```

```
it locally.
옿
passes tests(Params) :-
     oaa_class(leaf),
     icl GetParamValue(test(Test), Params),
     !,
     oaa Solve(Test, [level_limit(0)]).
% With compound goals, we also want to allow tests on the facilitator.
% @@DLM: Is this the best way?
passes_tests(Params) :-
     (oaa class(root);oaa class(node)),
     icl GetParamValue(test(Test), Params),
     1.
     oaa_solve_local(Test, []).
passes_tests(_Params) :-
     true.
*****
% name:
       oaa DelaySolution
% purpose: Requests that the current AppDoEvent not return solutions to the
       current goal until a later time.
₽
% inputs:
   - Id: an Id which will be used to later match solutions to request
₽
***********************
oaa DelaySolution(Id) :-
     oaa_current_contexts(GoalId, _Contexts), !,
     assert (oaa delay (GoalId, Id)).
oaa ReturnDelayedSolutions
% name:
% purpose: Returns the list of solutions for a delayed request
% inputs:
   - Id: an Id referring to a previously saved oaa_DelaySolution
÷.
oaa ReturnDelayedSolutions(Id, SolutionList) :-
     (retract(oaa_delay_table(GoalId, Id, Goal, SolveParams,AllParams)) ->
       (icl GetParamValue(reply(none), AllParams) -> true |
          (oaa Id(FromKS) ; FromKS = unknown), !,
          % make sure all Solutions unify with original goal
          findall(Goal, member(Goal, SolutionList), Solutions),
            oaa_PostEvent(ev_solved(GoalId, FromKS, Goal, SolveParams,
                           Solutions),[])
       )
     | true).
oaa AddDelayedContextParams
<u> የ</u> name:
% purpose: When a goal is delayed using oaa DelaySolution(), incoming context
       parameters from the original request can not be automatically
욹
       concatenated to outgoing oaa_Solve requests -- since an agent can
z
¥
       manage multiple delayed goals at the same time, liboaa doesn't
       know the correct context for the outgoing oaa_Solve without explicit
¥
       direction from the programmer. Hence, an agent programmer who
¥
₽
       wants to call oaa_Solve during a delayed goal is expected to
       use this function to add the saved contexts for the delayed goal to
s.
```

```
₽
       his/her outgoing oaa Solve parameters.
옿
  inputs:
€
   - Id: an Id which will be used to later match solutions to request
₽
   - Params: Parameters for solve goal
욯
   - NewParams: Params augmented by saved contexts.
€
  example:
₽
     oaa AppDoEvent(goal(X), Params) :- oaa DelayEvent(a goal).
     oaa AppDoEvent(temp event(Y), Params) :-
€
          oaa AddDelayedContextParams(a goal, [], P),
¥
₽
          oaa Solve(sub goal(Y), P).
¥
     oaa AppDoEvent(final event(S), Params) :-
₽
          oaa ReturnDelayedSolutions(a goal, [goal(S)]).
oaa AddDelayedContextParams(Id, Params, NewParams) :-
     retract(oaa_delay_table(_GoalId, Id, _Goal, _SolveParams, AllParams)),
     findall(context(C), member(context(C), AllParams), Contexts),
     append(Contexts, Params, NewParams).
% Agent-Facilitator communication
% name:
        oaa PostEvent
% purpose: Sends a low-level event to another agent
% remarks:
₽
    Should NOT be used before there's a connection established for
웅
     the destination (such as when a client sends ev connect to its
¥
     facilitator). In such unusual cases, use com_SendData directly.
₽
     For application developers, this just means don't call
₽
     oaa PostEvent until after you've called oaa Register.
욯
    Parameters may include:
¥
     - priority(P):
€
     - address(A): specify address of specific server or client agent
ફ
       A must be an agent ID, not a name. If caller is a client agent,
       the only meaningful address is that of the client's facilitator.
¥
¥
     - from(KS): where the event originally originated
€
    IMPORTANT: there may be a different address INSIDE the event;
     these should not be confused!
₽
oaa PostEvent (Contents, Params) :-
     % see if any params of interest
      (memberchk(priority( P), Params);
     memberchk(from( Agent), Params) ->
        SendEvent = event(Contents, Params)
        SendEvent = event(Contents, [])
    ),
     % find destination: if none, dest = server
     (memberchk(address(Dest), Params) ->
       true
```

```
Dest = parent
     ),
     icl true id (Dest, DestId),
       oaa translate outgoing event (SendEvent, DestId, TransEvent),
     oaa_ComTraceMsg('~n[COM send to ~q]:~n ~q~n', [Dest, TransEvent]),
     oaa_convert_id_to_comm_id(DestId, CommId),
     % send event to destination
     com:com SendData(CommId, TransEvent),
     % Use SendEvent here, becuase triggers always contain event/2
     % to unify with.
       oaa_CheckTriggers(comm, SendEvent, send).
oaa convert id to comm id(Id, CId) :-
     com:com_GetInfo(CId, fac_id(Id)), !.
oaa convert id to comm id(Id, CId) :-
     com:com GetInfo(CId, oaa id(Id)), !.
*****
          oaa_translate_outgoing_event(+Event, +DestId, -NewEvent).
∛ name:
% purpose: Provides backwards compatibility by calling a hook
    (user:oaa event translation/7) that translates outgoing events to agents of
¥
    other versions. Also allows for event differences based on language.
욯
% remarks: user:oaa event translation/7 can be hard-coded, loaded at runtime,
    or whatever. If it's not present, we return the same event.
s.
¥
    See also comments for oaa translate incoming event.
% Special cases. There's no need to translate these. And, it could be
% problematical, because we don't yet know the language and version of
% the receiver. See comments for oaa unwrap event.
oaa translate outgoing event (event (Contents, Params), DestId,
                     event(Contents, Params)) :-
     ( Contents = ev_connect(_) ;
       Contents = ev_connected(_) ),
    1.
oaa translate outgoing event (event (Content, Params), DestId, TransEvent) :-
   current predicate (oaa event translation,
                user:oaa_event_translation(_,_,_,_,_,_)),
       % These assumptions may not always be right, but will
     % nearly always get the desired results:
   com:com GetInfo(Connection, oaa id(DestId)),
    ( com:com GetInfo(Connection, agent version(DestVersion)) ->
       true
   | otherwise ->
       DestVersion = 2.1
   ),
    ( com:com GetInfo(Connection, agent language(DestLanguage)) ->
       true
   | otherwise ->
       DestLanguage = c
```

```
),
   oaa LibraryVersion(MyVersion),
   user:oaa event translation(MyVersion, prolog, DestVersion, DestLanguage,
                     Connection, event (Content, Params), TransEvent),
   1.
oaa translate outgoing event (Event, , Event).
% name:
         oaa Version
% purpose: Lookup the language and library version number for an agent
% remarks: The default version (if unspecified) is 1.0
oaa Version(AgentId, Language, Version) :-
  icl_true id(AgentId, TrueId),
  % Asking for my version:
  oaa Id(TrueId),
  Language = prolog,
  oaa_LibraryVersion(Version),
oaa Version (AgentId, Language, Version) :-
  icl true id (AgentId, TrueId),
  ( com:com GetInfo(CommId, oaa id(TrueId)) ;
    com:com GetInfo(CommId, fac id(TrueId)) ),
  ( com:com GetInfo(CommId, agent language(Language)) ->
     true
  | otherwise ->
     Language = unknown
  ),
  ( com:com GetInfo(CommId, agent version(Version)) ->
     true
  | otherwise ->
     Version = 1.0
  ),
  1.
oaa_Version(AgentId, Language, Version) :-
   (oaa_class(leaf) ; oaa_class(node)),
   icl_true id(AgentId, TrueId),
     * The use of caching here could be dangerous - unless we install a
      % mechanism for automatic updating of the cache.
   oaa_Solve(agent_version(TrueId, Language, Version),
           [address(parent)]),
oaa Version(, prolog, 1.0).
% name:
        oaa CanSolve
% purpose: Asks the Facilitator for a list of agents which could solve a Goal
oaa CanSolve (Goal, KSList) :-
   oaa_Solve(can solve(Goal, KSList), [address(parent)]).
```

```
% purpose: Tests whether a given agent is currently responding to requests.
% inputs:
¥
   AgentAddr: address of agent to test
٩.
   TimeLimit: Time limit (in seconds) for how long to wait for a response
% outputs:
Ŷ.
   TotalResponseTime for round trip (in seconds)
% remarks: Fails if a ping is not returned in TimeLimit amount of time
oaa_Ping(AgentAddr, TimeLimit, TotalResponseTime) :-
   ground (AgentAddr),
   number (TimeLimit),
   TimeLimit >= 0,
   tcp now (Before),
   oaa Solve(true, [address(AgentAddr), time limit(TimeLimit)]),
   tcp now(After),
   tcp_time plus (Before, TotalResponseTimeMs, After),
   TotalResponseTime is TotalResponseTimeMs / 1000.
% Declaring Solvables
% name:
         oaa Declare (+Solvables, +CommonPermissions, +CommonParams, +Params,
₽
                    -DeclaredSolvables)
% purpose: Declare solvables for a client or facilitator, and inform the
₽
         parent if appropriate.
% arguments:
ક
   Solvables: A single solvable or a list of solvables, in shorthand or
욹
         standard form.
₽
   CommonPermissions: Permissions to be distributed to each solvable in
₽
         Solvables. This is purely for programming convenience. See
ę
         comments for icl_ConvertSolvables for possible values, and
욯
         solvables documentation for their meanings.
용
   CommonParams: Params to be distributed to each solvable in Solvables.
ક્ષ
         This is purely for programming convenience. See comments for
ક
         icl ConvertSolvables for possible values, and solvables
€
         documentation for their meanings.
₽
   Params:
€
      address(X): Where the solvable will exist. X may be either 'self'
옿
         or 'parent' (or the appropriate local ids). Default: 'self'.
¥
      if exists (OverwriteOrAppend): What to do when declaring solvables
₽
         for self, and some already exist. Default: append.
€
   DeclaredSolvables: Returns a list, in standard form, of all solvables
ⴻ
      successfully declared.
% remarks:
욯
    - Any agent can declare solvables for itself. In addition, a client can
욹
      ask its facilitator to declare solvables. Client-requested facilitator
¥
      solvables will automatically acquire permission write(true), and params
¥
      type(data), rules_ok(false), private(false), and bookkeeping(true).
욯
    - If called by a leaf or node agent, assumes agent is already registered
      with a parent facilitator.
8
    - Predicates can only be declared once. Changing an existing
€
      predicate definition should be done with oaa_Redeclare. However,
¥
```

```
a request to declare a predicate, which is already declared in
€
€
      precisely the same way, succeeds transparently.
€
    - @@Future params may include 'num context args(N)'.
f
    - @@Future solvable params may include 'shared'.
ક્ષ
    - synonym predicates can have their own triggers, but share the clause
₽
      database with their master table.
₽
    - views and filters, as provided by the OAA V1 DB agent, are not
¥
      supported as separate params, but the same functionality is available
¥
      using other params.
    - @@Do we want client agents to request declarations on other client
₽
¥
      agents?
oaa Declare (Solvable, InitialCommonPerms, InitialCommonParams,
         InitialParams, DeclaredSolvables) :-
    ( is list(Solvable) ->
     SolvableList = Solvable
   | otherwise ->
     SolvableList = [Solvable]
   .),
   icl_ConvertSolvables(SolvableList, Solvables),
   icl standardize perms(InitialCommonPerms, false, CommonPerms),
   icl standardize params(InitialCommonParams, false, CommonParams),
   icl standardize params (InitialParams, false, Params),
   oaa distribute perms (Solvables, CommonPerms, Solvables1),
   oaa distribute params(Solvables1, CommonParams, NewSolvables),
   oaa declare aux(add, NewSolvables, Params, DeclaredSolvables).
% name:
         oaa_DeclareData(+Solvables, +Params, -DeclaredSolvables)
% purpose: Declare data solvables for an agent.
oaa DeclareData(Solv, Params, DeclaredSolvs) :-
   \+ is_list(Solv),
   !,
   oaa_DeclareData([Solv], Params, DeclaredSolvs).
oaa DeclareData(Solvs, Params, DeclaredSolvs) :-
   % It's only necessary to specify the non-default perms and params.
   CommonPerms = [write(true)],
   CommonParams = [type(data)],
   oaa Declare (Solvs, CommonPerms, CommonParams, Params, DeclaredSolvs).
oaa Undeclare(+Solvables, +Params, -UndeclaredSolvables)
% name:
$ purpose: Remove solvables from a client or facilitator, and inform the
         parent if appropriate.
Я
% arguments:
€
   Solvables: A single solvable or a list of solvables, in shorthand or
      standard form. If a solvable is in standard form, however, ONLY
욹
      the goal is considered in selecting the solvables to be removed
¥
¥
      (permissions and parameters are ignored).
₽
   Params:
옿
      address(X): Where the solvable exists. X may be either 'self'
         or 'parent' (or the appropriate local ids). Default: 'self'.
€
   DeclaredSolvables: Returns a list, in standard form, of all solvables
€
      successfully removed.
÷
```

```
% remarks:
    - If called by a leaf or node agent, assumes agent is already registered
돵
      with a parent facilitator.
8
oaa Undeclare(Solvable, InitialParams, UndeclaredSolvables) :-
   ( is list(Solvable) ->
     SolvableList = Solvable
   otherwise ->
     SolvableList = [Solvable]
   ),
   icl_minimally_instantiate_solvables(SolvableList, Solvables),
   icl standardize params (InitialParams, false, Params),
   oaa_declare_aux(remove, Solvables, Params, UndeclaredSolvables).
oaa_Redeclare(+Solvable, +NewSolvable, +Params)
% name∶
% purpose: Replace a solvable on a client or facilitator, and inform the
         parent if appropriate.
¥
% arguments:
   Solvable: A single solvable, in shorthand or standard form. If in
f
웋
      standard form, however, ONLY the goal is considered in selecting
ક
      the solvable to be replaced (permissions and parameters are ignored).
₽
   NewSolvable: A single solvable, in shorthand or standard form.
∛
   Params:
      address(X): Where the solvable exists. X may be either 'self'
ક્ર
         or 'parent' (or the appropriate local ids). Default: 'self'.
ક્ર
% remarks:
    - If called by a leaf or node agent, assumes agent is already registered
¥
옿
      with a parent facilitator.
    - FAILS if the operation cannot be completed.
8
oaa Redeclare(InitialSolvable, InitialNewSolvable, InitialParams) :-
   icl_minimally_instantiate_solvables([InitialSolvable], [Solvable]),
   icl ConvertSolvables([InitialNewSolvable], [NewSolvable]),
   icl_standardize_params(InitialParams, false, Params),
   oaa declare aux(replace, Solvable, [with(NewSolvable) | Params],
              RedeclaredSolvables),
   RedeclaredSolvables = [].
% name:
         oaa_declare_aux(+Mode, +Solvables, +Params, -DeclaredSolvables)
% purpose: Common code for oaa_Declare, oaa_Undeclare, oaa_Redeclare.
% Mode: add, remove, or replace.
Solvables: for Mode = add, a list of Solvables in standard form.
           for Mode = remove, a list of Solvables in "minimally instantiated"
₽
f
               form.
           for Mode = replace, a list containing a single Solvable, in
¥
               "minimally instantiated" form.
₽
% Params: whatever is appropriate for oaa Declare, Undeclare, Redeclare.
           Must already be in standard form.
욹
% DeclaredSolvables: A list of all solvables successfully added (or removed
$
           or replaced), in standard form.
% remarks:
¥
   A number of params and perms are required when requesting that a
   parent declare solvables (see comments for oaa_Declare). We could ensure
*
```

```
their presence here, but it's not essential, because the facilitator will
8
2
   enforce this.
*************************
% Here, a client is asking the facilitator to add, remove, or replace
% solvables.
oaa declare aux(Mode, Solvables, Params, DeclaredSolvables) :-
   com:com GetInfo(parent, fac id(ParentId)),
   memberchk(address([ParentId]), Params),
    1,
    % Send the request to the Facilitator
   oaa PostEvent(ev post declare(Mode, Solvables, Params), []),
   oaa poll until event(
       ev reply declared (Mode, Solvables, Params, Declared Solvables)).
% Leaf, node or root adding, removing or replacing its own solvables:
oaa declare aux(Mode, Solvables, Params, DeclaredSolvables) :-
   oaa Id(Me),
    ( memberchk(address(Addr), Params) ->
       Addr = [Me]
    true),
    1,
   oaa declare local (Mode, Solvables, Params, DeclaredSolvables),
   % If I'm a facilitator, I must also "register" my Solvables with myself.
    % (If I'm a node, this will also register them with my parent.)
    ( (\+ oaa class(leaf), DeclaredSolvables \== []) ->
       oaa Name (MyName),
         user:oaa AppDoEvent(
           ev register solvables(Mode, DeclaredSolvables, MyName, Params),
         [from(Me)])
    | true
   ),
   % If I'm a leaf, post public solvables to parent facilitator:
   select elements (DeclaredSolvables, oaa public solvable, PublicSolvables),
    ( (oaa_class(leaf), PublicSolvables \== []) ->
     com:com_GetInfo(parent, oaa_name(MyNameC)),
       oaa PostEvent(
         ev_register_solvables(Mode, PublicSolvables, MyNameC, Params),
         []]
    | true ).
   % Solvable must be in standard form.
oaa public solvable(solvable(Solvable, Params, Perms)) :-
   icl GetParamValue(private(false), Params).
   % Solvable must be in standard form.
oaa data solvable(solvable(_Solvable, Params, _Perms)) :-
   icl GetParamValue(type(data), Params).
% name:
            oaa declare local(+Mode, +Solvables, +Params, -DeclaredSolvables)
% purpose:
            Declare solvables for an agent.
% Mode:
            add, remove, or replace.
% Solvables: The form they're in depends on the mode. See oaa_declare_aux.
```

```
% DeclaredSolvables: Returns those members of Solvables for which
      the operation was successful (more specifically, those that should
¥
      be passed up to the parent in ev register solvables). Always returned
*
      in STANDARD FORM.
% Also see: comments for oaa Declare, oaa Undeclare, oaa Redeclare.
% remarks:
    - This performs the local processing needed by calls to oaa Declare,
s,
      and by ev declare events.
₽
    - Solvables and Params must already be in standard form.
₽
¥
¥
    @@DLM: Could do more careful testing to be sure the solvables are
£
    all valid for the requested operation.
oaa_declare local(Mode, Solvable, Params, DeclaredSolvables) :-
    \+ is_list(Solvable),
    !,
    oaa_declare local(Mode, [Solvable], Params, DeclaredSolvables).
oaa declare local(add, InitialSolvables, Params, DeclaredSolvables) :-
    ( icl_GetParamValue(if exists(overwrite), Params) ->
      CurrentSolvables = []
    oaa solvables(CurrentSolvables) ->
      true
    CurrentSolvables = []
    ),
    % This will eliminate those that unify with an already declared solvable.
    % @@DLM: Should do more, though: warnings.
    solvables to be added (Initial Solvables, Current Solvables,
                               DeclaredSolvables),
    % Make sure Quintus has the correct properties for each DB solvable.
    select elements (DeclaredSolvables, oaa data solvable, DBSolvables),
    oaa declare for prolog(DBSolvables),
    append (CurrentSolvables, DeclaredSolvables, AllSolvables),
    retractall(oaa solvables( )),
    assert (oaa solvables (AllSolvables)).
oaa_declare_local(remove, Solvables, _Params, RemovedSolvables) :-
    % See which ones are really declared:
    ( oaa_solvables(Current) -> true | Current = [] ),
    solvables to be removed (Solvables, Current, RemovedSolvables),
    % Retract all clauses from data solvables:
    select elements (RemovedSolvables, oaa data solvable, DBSolvables),
   oaa remove solvables data(DBSolvables),
    % Assert the new solvables list:
   retractall(oaa solvables()),
   subtract(Current, RemovedSolvables, New),
   assert(oaa solvables(New)).
oaa_declare_local(replace, [Solvable], Params, [Solvable]) :-
   memberchk(with(NewSolvable), Params),
   % Make sure Solvable is really declared:
    ( oaa solvables(Current) -> true | otherwise -> Current = []),
   memberchk(Solvable, Current),
    !,
    % If a data solvable, maybe retract all its clauses:
    ( oaa_data_solvable(Solvable) ->
```

```
oaa remove solvables data([Solvable])
   true
   ),
   % Assert the new solvables list:
   retractall(oaa solvables(_)),
   replace element (Solvable, Current, NewSolvable, New),
   assert(oaa solvables(New)).
oaa declare local(replace, [Solvable], Params, []) :-
   Solvable = solvable(Goal, _, _),
   format('-w: Ignoring attempt to replace a non-existent solvable:~n -w~n',
        ['WARNING', Goal]).
% name: oaa distribute params(+Solvables, +CommonParams, -NewSolvables).
       oaa_distribute_perms(+Solvables, +CommonPerms, -NewSolvables).
% purpose: Add CommonParams (CommonPerms) to the Params (Permissions) list of
       each solvable in Solvables.
ę.
% Solvables: a solvables list, in standard form.
% remarks: @@Should warn when a solvables has a param that conflicts with
         CommonParams. Also, should have an arg that says which version of
s.
         of the conflicting param to keep.
oaa distribute params([], _CommonParams, []).
oaa distribute params([Solvable | Solvables], CommonParams,
                [NewSolvable | NewSolvables]) :-
   Solvable = solvable(Goal, Params, Perms),
   union(Params, CommonParams, NewParams),
   NewSolvable = solvable(Goal, NewParams, Perms),
   oaa distribute params(Solvables, CommonParams, NewSolvables).
oaa distribute perms([], CommonPerms, []).
oaa distribute perms([Solvable | Solvables], CommonPerms,
                [NewSolvable | NewSolvables]) :-
   Solvable = solvable(Goal, Params, Perms),
   union(Perms, CommonPerms, NewPerms),
   NewSolvable = solvable(Goal, Params, NewPerms),
   oaa_distribute_perms(Solvables, CommonPerms, NewSolvables).
% name: solvables to be added(+ProposedSolvs, +CurrentSolvs, -SolvsToBeAdded).
% purpose: Checks a list of solvables, to make sure they can legally be
         declared.
% ProposedSolvs: Must be in STANDARD FORM.
% CurrentSolvs: This agent's current solvables.
% SolvsToBeAdded: A subset of ProposedSolvs.
solvables_to_be_added([], _Current, []).
solvables_to_be_added([Solvable | Solvables], Current, OKSolvables) :-
   Solvable = solvable (Goal, _, _),
   memberchk(solvable(Goal, _, _), Current),
   !,
   format('-w: Ignoring attempt to declare an already existing solvable:-n
~w~n',
        ['WARNING', Goal]),
   solvables_to_be_added(Solvables, Current, OKSolvables).
```

```
solvables to be added([Solvable | Solvables], Current,
                   [Solvable | OKSolvables]) :-
   solvables to be added(Solvables, Current, OKSolvables).
% name: solvables to be removed(+ProposedSolvs, +CurrentSolvs,
                           -SolvsToBeRemoved).
% purpose: Checks a list of solvables, to make sure they can legally be
         UNdeclared.
٩.
% ProposedSolvs: Must be in MINIMALLY INSTANTIATED FORM.
% CurrentSolvs: This agent's current solvables.
% SolvsToBeRemoved: A subset of ProposedSolvs, but returned in standard form,
   fully instantiated.
₽.
solvables_to_be_removed([], _Current, []).
solvables to be removed ([Solvable | Solvables], Current,
               [Solvable | OKSolvables]) :-
   memberchk(Solvable, Current),
   1.
   solvables to be removed (Solvables, Current, OKSolvables).
solvables_to_be_removed([Solvable | Solvables], Current, OKSolvables) :-
   Solvable = solvable(Goal, _, _),
   format('-w: Ignoring attempt to remove a non-existent solvable:~n -w~n',
        ['WARNING', Goal]),
   solvables to be removed (Solvables, Current, OKSolvables).
% Updating Data Solvables
ቄ name:
         oaa AddData(+Clause, +Params).
% purpose: Add a new clause for a DATA solvable (locally and/or remotely)
% Params:
    address(X): a list including 'self', 'parent', and/or the
$
     addresses of other client agents. The default (no address)
¥
¥
     behavior is the same as with oaa Solve.
웅
    reflexive(T_F): Save as with oaa_Solve. Default: true.
¥
    at beginning(T F): if true, uses asserta instead of assertz.
8
     Default: false.
ક્ર
    single_value(T_F): if true, ALL clauses for this predicate are removed
€
     before adding the new clause.
€
     Default: false.
¥
    unique values (T F): if true, at most one copy of each value is stored.
₽
     Default: false.
₽
    owner(LocalId): if bookkeeping(true) for this solvable, record
¥
     LocalId as the owner.
÷
     Default: the agent from which the request originated.
₽
    get address(X): Returns a list of addresses (ids) of agents that
Ł
     were sent the request.
£
    get satisfiers(X): Returns a list of addresses (ids) of agents that
     successfully completed the request.
₽
```

```
reply({true, none}): When data is being added on
₽
      a remote agent or agents, this tells whether reply message(s) are
8
욯
      desired.
욯
     block(Mode) : true: Block until the reply arrives.
€
                : false: Don't block. In
₽
                       this case, the reply events (ev reply updated)
₽
                       can be handled by the user's app do event callback
₽
                Default: true. Note that reply(none) overrides
$
                       block(true).
% remarks:
    - Clause is normally a fact (no body), but with Prolog agents, and
₽
      with rules ok(true), it's possible for it to have a body.
*
    - Triggers will be examined with the on(add) operation mask
oaa AddData(Clause, Params) :-
   oaa update(add, Clause, Params).
oaa RemoveData(+Clause, +Params).
% name:
% purpose: Remove a clause from a DATA solvable (locally and/or remotely)
% Params:
    address(X): a list including 'self', 'parent', and/or the
₽
      addresses of other client agents. The default (no address)
₽
욹
      behavior is the same as with oaa Solve and oaa AddData.
₽
    reflexive(T F): Save as with oaa Solve. Default: true.
₽
    do all(T F): If true, removes all predicate values that match the Clause
욯
      Default: false (removes only the first)
f
    qet address(X): Returns a list of addresses (ids) of agents that
£
      were sent the request.
    get_satisfiers(X): Returns a list of addresses (ids) of agents that
₽
¥
      successfully completed the request.
¥
    owner(LocalId): if bookkeeping(true) for this solvable, remove only
¥
      data owned by LocalId.
₽
      Default: ignore owner in removing data.
€
    reply({true,none}): When data is being removed on
욯
      a remote agent or agents, this tells whether reply message(s) are
₽
      desired.
욯
     block(Mode) : true: Block until the reply arrives.
ક્ર
                : false: Don't block. In
웅
                       this case, the reply events (ev_reply_updated)
욯
                       can be handled by the user's app do event callback
ક્ર
                Default: true. Note that reply(none) overrides
÷
                       block(true).
% remarks:
    - Clause is normally a fact (no body), but with Prolog agents, and
*
      with rules ok(true), it's possible for it to have a body.
¥
    - Triggers will be examined with the 'on Retract' operation mask.
₽
    - Not for backtracking.
¥
oaa_RemoveData(Clause, Params) :-
   oaa update (remove, Clause, Params).
8-----
                  _____
% name:
         oaa ReplaceData(+Clause1, +Clause2, +Params).
% purpose: Change a predicate value to a new one
```

```
% Clause1: Must be a clause of a writable data solvable.
% Clause2: Must be a clause of a writable data solvable.
% Params:
    address(X): a list including 'self', 'parent', and/or the
¥
      addresses of other client agents. The default (no address)
¥
¥
      behavior is the same as with oaa Solve and oaa AddData.
€
    reflexive(T F): Save as with oaa Solve. Default: true.
₽
    do all (T F): If, true, changes all predicate values that match the
¥
            Clausel specification
₽
            default is 'false': changes only the first
₽
    at_beginning(T_F): If true, uses asserta instead of assertz
¥
            default is 'false'
¥
    owner(LocalId): if bookkeeping(true) for this solvable, record
8
      LocalId as the owner of each new data item. Note: It is not possible
옿
      to specify the owner of the data to be replaced, just that of the
₽
      NEW data.
¥
      Default: the agent from which the request originated.
€
    get_address(X): Returns a list of addresses (ids) of agents that
₽
      were sent the request.
₽
    get_satisfiers(X): Returns a list of addresses (ids) of agents that
ક્ર
      successfully completed the request.
¥
    reply({true, none}): When data is being replaced on
욯
      a remote agent or agents, this tells whether reply message(s) are
¥
      desired.
₽
    block(Mode) : true: Block until the reply arrives.
₽
                 : false: Don't block. In
₽
                        this case, the reply events (ev reply updated)
ક્ર
                        can be handled by the user's app do event callback
ક્ર
                Default: true. Note that reply(none) overrides
¥
                        block(true).
% remarks:
÷
    - Clause1 and/or Clause2 may be synonym predicates.
€
    - Clause1 and Clause2 are not required to have the same functor.
€
    - Clause1 and Clause2 may share variables.
f
    - Triggers will be examined with the 'remove' operation mask with Clausel,
      and the 'add' operation mask with Clause2.
ક્ષ
¥
    - db_replace triggers on the Pred2 argument, not on the Pred1 arg
    - at beginning param only used if do all is false
8
8-----
oaa_ReplaceData(Clause1, Clause2, Params) :-
   oaa update(replace, Clause1, [with(Clause2) | Params]).
% name:
         oaa update(+Mode, +Clause, +Params).
% purpose: Common code for oaa AddData, oaaRemoveData, and oaa ReplaceData.
% Mode:
          add, remove, or replace.
% Clause, Params: May include whatever is appropriate for oaa AddData,
                oaaRemoveData, or oaa ReplaceData.
oaa_update(Mode, Clause, InitialParams) :-
  icl standardize params (InitialParams, false, Params),
  % Is there a specified address?
   ( memberchk(address(Addr), Params) ->
      true
  | otherwise ->
      Addr = []
```

```
% Decide whether or not to update locally:
oaa Id(Me),
( memberchk (Me, Addr) ->
    delete(Addr, Me, NewAddr),
    replace element (address (Addr), Params, address (NewAddr), Params1),
    Self = true
| otherwise ->
   NewAddr = Addr,
    Params1 = Params
),
( Addr = [], icl GetParamValue(reflexive(true), Params1) ->
    % do NOT use remove element here:
    delete(Params1, reflexive(true), Params2),
    ( caa solvables(Solvables) -> true | otherwise -> Solvables = [] ),
    ( oaa data matches_solvables(Clause, Solvables, write, _, _) ->
        Self = true
    | otherwise ->
        true
   )
| otherwise ->
   Params2 = Params1
),
% Update locally if appropriate:
( Self == true ->
   Requestees1 = [Me],
    (Mode == add ->
        Functor = oaa_add_data_local
    Mode == replace ->
       Functor = oaa replace data local
    Mode == remove ->
       Functor = oaa_remove_data_local
    ),
   LocalCall = .. [Functor, Clause, Params2],
    ( call(LocalCall) ->
       Updaters1 = [Me]
       Updaters1 = [])
    | otherwise ->
   Requestees1 = [],
   Updaters1 = []
),
% Update remotely if appropriate:
( oaa_class(leaf), (Addr == [] ; NewAddr \== []) ->
    % Send the ev post update event to the Facilitator
   oaa PostEvent(ev post update(Mode, Clause, Params2), []),
   % In the return event, Requestee2s lists all agents to whom
   % the update request was sent; Updaters2 lists those who succeeded.
    ( (icl_GetParamValue(reply(asynchronous), Params) ;
       icl_GetParamValue(reply(none), Params)) ->
       Requestees2 = [],
       Updaters2 = []
    | otherwise ->
       oaa_poll_until_event(
          ev_reply_updated(Mode, Clause, Params2, Requestees2, Updaters2))
```

),

```
)
   | otherwise ->
      Requestees2 = [],
      Updaters2 = []
  ).
  append(Updaters1, Updaters2, Updaters),
  % Return Updaters if requested:
   ( memberchk(get satisfiers(Updaters), Params) -> true | true ),
  append (Requestees1, Requestees2, Requestees),
  % Return Requestees if requested:
   ( memberchk(get address(Requestees), Params) -> true | true ).
oaa add data local(+Clause, +Params)
% name:
% purpose:
           Assert a clause for an agent's solvable.
% arguments: See comments for oaa AddData.
% remarks:
웊
   This performs the local processing needed for calls to oaa AddData, and
÷
   ev update(add, ...) requests.
   Application code should not call oaa_add_data_local directly, but rather
윻
¥
   oaa AddData with address(self).
oaa add data local(Clause1, Params) :-
   ( oaa_solvables(Solvables) -> true | otherwise -> Solvables = []),
   oaa data matches solvables (Clause1, Solvables, write, Clause, Matched),
   Matched = solvable(Pred, DeclParams, Perms),
   (Clause = (Head :- Body) ->
       true
   | otherwise ->
       Head = Clause,
       Body = true
   ),
   append (Params, DeclParams, AllParams),
   % If there's no callback, leave Callback a var:
   ( memberchk(callback(Callback), AllParams) -> true | true ),
   % if single value, erase all old values
   (icl GetParamValue(single value(true), AllParams) ->
       ( \+ icl_GetParamValue(bookkeeping(false), DeclParams) ->
         oaa_retractall((Pred :- _), _OldOwner, Callback)
     | otherwise ->
         retract_all((Pred :- ))
     )
   true),
   % if unique values(true), make sure fact not already in database
   ( clause (Head, Body), icl GetParamValue (unique values (true), AllParams) ->
       true
   | otherwise ->
       ( \+ icl GetParamValue(bookkeeping(false), DeclParams) ->
         oaa data owner (Params, Owner),
           ( icl GetParamValue(at beginning(true), AllParams) ->
              oaa asserta(Clause, Owner, Callback)
           oaa_assertz(Clause, Owner, Callback)
```

```
)
     | otherwise ->
          ( icl GetParamValue(at beginning(true), AllParams) ->
              asserta (Clause)
              assertz (Clause)
          )
       )
   ),
   oaa_CheckTriggers(data, Head, add),
  !.
oaa remove data local(+Clause, +Params)
% name:
           Retract a clause (or all clauses) from an agent's solvable.
% purpose:
% arguments: See comments for oaaRemoveData.
% remarks:
¥
   This performs the local processing needed for calls to oaaRemoveData, and
   ev update(remove, ...) requests.
8
oaa_remove_data_local(Clause1, Params) :-
   ( oaa_solvables(Solvables) -> true | otherwise -> Solvables = []),
   oaa data matches solvables (Clause1, Solvables, write, Clause, Matched),
   Matched = solvable( Pred, DeclParams, Perms),
   ( Clause = (Head :- Body) ->
       true
   | otherwise ->
      Head = Clause,
      Body = true
   ),
   append(Params, DeclParams, AllParams),
   ( memberchk(callback(Callback), AllParams) -> true | true ),
   ( \+ icl GetParamValue(bookkeeping(false), DeclParams) ->
     ( icl_GetParamValue(owner(Owner), Params) -> true | true ),
       ( icl GetParamValue(do all(true), Params) ->
          oaa retractall(Clause, Owner, Callback)
     | otherwise ->
        oaa_retract(Clause, Owner, Callback)
     )
   otherwise ->
       ( icl_GetParamValue(do_all(true), Params) ->
          retract all(Clause)
     | otherwise ->
          retract (Clause)
     )
   ),
   oaa CheckTriggers (data, Head, remove),
   1.
% name:
           oaa_replace_data_local(+Clause1, +Params)
% purpose:
           Replace one or more clauses from an agent's solvable.
% arguments: See comments for oaa_ReplaceData.
```

```
% remarks:
   This performs the local processing needed for calls to oaa ReplaceData, and
욯
€
   ev_update(replace, ...) requests.
융
   Clausel is the thing to be replaced. The thing to replace it with must
   be present in Params, as with (Clause2).
¥.
oaa_replace_data_local(ClauselIn, Params) :-
   memberchk(with(Clause2In), Params),
   ( oaa_solvables(Solvables) -> true | otherwise -> Solvables = []),
   oaa_data_matches_solvables(Clause1In, Solvables, write, Clause1, Matched),
   oaa data matches solvables (Clause2In, Solvables, write, Clause2, _Matched2),
   Matched = solvable( Pred, DeclParams, Perms),
    ( Clause1 = (Head :- Body) ->
       true
   | otherwise ->
       Head = Clause1,
       Body = true
   ),
   append(Params, DeclParams, AllParams),
   ( memberchk(callback(Callback), AllParams) -> true | true ),
   % do replace of either one or all occurrences
    ( \+ icl_GetParamValue(bookkeeping(false), DeclParams) ->
       oaa data owner (Params, Owner),
       ( icl_GetParamValue(do_all(true), Params) ->
          oaa_replace_all(Clause1, Clause2, Owner, Callback)
       | otherwise ->
          oaa_retract(Clause1, _OldOwner, Callback),
           (icl_GetParamValue(at_beginning(true), AllParams) ->
             oaa asserta(Clause2, Owner, Callback)
           oaa assertz(Clause2, Owner, Callback)
     )
    | otherwise ->
       ( icl_GetParamValue(do_all(true), Params) ->
          replace_all(Clause1, Clause2)
     | otherwise ->
          retract(Clause1),
           (icl GetParamValue(at beginning(true), AllParams) ->
             asserta(Clause2)
           assertz (Clause2)
         )
     )
   ),
   oaa CheckTriggers(data, Clausel, remove),
   oaa CheckTriggers(data, Clause2, add),
   1.
% name:
         retract all
% purpose: Remove all clauses matching Clause1
% remarks: Always succeeds. Needed because retractall((func(X) :- Y)) doesn't
s.
         work.
**********************
retract all(Clause1) :-
  retract (Clause1),
```

```
fail.
retract_all(_Clause1).
```

```
% name:
      replace all
% purpose: Replace all clauses matching Clause1 by Clause2
% remarks: Always succeeds
replace all(Clause1, Clause2) :-
  retract(Clause1),
  assert (Clause2),
  fail
replace_all(_Clause1, _Clause2).
% name: oaa data owner(+Params, -Owner)
% purpose: Determine data ownership from the available params
oaa data owner(Params, Owner) :-
  ( memberchk(owner(Owner), Params) ->
     true
  memberchk(from(Owner), Params) ->
   true
  | oaa Id(Owner) ->
   true
  otherwise ->
   Owner = unknown
  ).
% name: oaa Id(MyId)
% purpose: Return the Id of the current agent
% if connected to a Facilitator, use this Id
oaa Id(MyId) :-
   com.com_GetInfo(parent, oaa id(MyId)), !.
% For root, get any id
oaa Id(MyId) :-
   com:com GetInfo(ConnectionId, type(server)),
   com:com GetInfo(ConnectionId, oaa id(MyId)), !.
% name: oaa Name(MyName)
% purpose: Return the name of the current agent
% if connected to a Facilitator, use this Id
oaa Name (MyName) :-
   com:com_GetInfo(parent, oaa name(MyName)), !.
% For root, get any id
oaa Name (MyName) :-
   com:com_GetInfo(ConnectionId, type(server)),
   com.com_GetInfo(ConnectionId, oaa_name(MyName)), !.
% name: oaa class(MyClass)
```

```
% purpose: Return the class (leaf, node, root) of the current agent
% if connected to a Facilitator, use this Id
oaa class(leaf) :-
     com:com GetInfo( , type(client)),
     \+ com:com_GetInfo(_, type(server)), !.
oaa_class(node) :-
     com:com_GetInfo(_, type(client)),
     com:com GetInfo(_, type(server)), !.
oaa class(root) :-
     com:com GetInfo( , type(server)),
     \+ com:com_GetInfo(_, type(client)), !.
% name: oaa_asserta(Clause, Owner, SpecifiedCallback)
¥
       oaa_assertz(Clause, Owner, SpecifiedCallback)
₽
       oaa retract(Clause, Owner, SpecifiedCallback)
₽
       oaa retractall(Clause, Owner, SpecifiedCallback)
<u>۹</u>
       oaa_replace_all(Clause1, Clause2, Owner, SpecifiedCallback)
% purpose: Perform data updates with bookkeeping info (in oaa data ref/3)
% remarks: These should only be used with data solvables having param
         bookkeeping(true).
욹
ક્ર
         There are still a couple limitations related to data callbacks.
웅
          First, callbacks don't work when bookkeeping(false).
          Second, oaa replace all assumes the same callback is appropriate
Ж
          for both the old and new facts.
₽
oaa_asserta(Clause, Owner, Callback) :-
   asserta(Clause, Ref),
   now(Time),
   assert (oaa data ref (Ref, Owner, Time)),
   oaa_call_callback(app_on_data_change, Callback, [add(Clause)]).
oaa assertz(Clause, Owner, Callback) :-
   assertz(Clause, Ref),
   now(Time),
   assert (oaa data ref (Ref, Owner, Time)),
   oaa_call_callback(app_on_data_change, Callback, [add(Clause)]).
oaa retract(Clause, Owner, Callback) :-
   ( Clause = (Head :- Body) ->
       true
   | otherwise ->
       Head = Clause,
       Body = true
   ),
   clause(Head, Body, Ref),
   ( retract(oaa_data_ref(Ref, Owner, _)) ->
       erase(Ref),
     oaa call callback(app on data change, Callback, [remove(Clause)])
   ).
oaa_retractall(Clause, Owner, Callback) :-
   ( Clause = (Head :- Body) ->
       true
   | otherwise ->
```

```
Head = Clause,
      Body = true
   ),
   clause(Head, Body, Ref),
   ( retract(oaa data ref(Ref, Owner, )) ->
      erase(Ref),
     oaa call callback(app on data change, Callback, [remove(Clause)])
   ),
   fail.
oaa retractall( Clause, Owner, Callback).
oaa_replace_all(Clause1, Clause2, Owner, Callback) :-
  oaa_retract(Clause1, _OldOwner, Callback),
oaa_assertz(Clause2, Owner, Callback),
  % This would be redundant:
  % oaa call callback(app on data change, Callback, [replace(Clause1,
Clause2)]),
  fail.
oaa_replace all( Clause1, _Clause2, Owner, _Callback).
% Trigger Handling
% name:
        oaa_CheckTriggers
% purpose: Given a trigger type, a mask and an Op (e.g. [send, receive],
   [add, remove], etc), see if any triggers fire.
oaa_CheckTriggers(Type, Condition, Op) :-
     % for each matching trigger
     oaa_solve_local(
         oaa_trigger(TriggerId, Type, Condition, Action, Params),
        []),
     ( (Type == task, \+ var(Condition)) ->
       % We don't want this to succeed more than once, so use ->
       ( oaa Interpret(Condition, [from(self)]) -> true )
     | otherwise ->
        true
    ),
    % see if on(Op) has been specified
     (memberchk(on(OpSpecified), Params) ->
       OpMask = OpSpecified
     OpMask = ),
    % see if Op is OK
     ( (ground(OpMask), OpMask = [ ]) ->
        memberchk(Op, OpMask)
     | otherwise ->
         Op = OpMask
    ),
    % test additional conditions
```

```
(memberchk(test(Test), Params) ->
         % We don't want this to succeed more than once, so use ->
         ( oaa Interpret(Test, [from(self)]) -> true )
         Test = 'true'),
      % check recurrence: remove trigger?
      (remove_element(recurrence(R), Params, NewParams) ->
         (R = whenever ->
                        % don't remove trigger if 'whenever'
            true
         integer(R), R > 1 ->
            R2 is R - 1,
            % decrement recurrence count
            oaa remove data local(
                oaa_trigger(TriggerId, Type, Condition, Action, Params),
              []),
            oaa add data local(
                  oaa trigger(TriggerId, Type, Condition, Action,
                           [recurrence(R2) | NewParams]),
                (1)
           oaa_remove_local_trigger_by_id(TriggerId)
      R = when,
         oaa_remove_local_trigger_by_id(TriggerId)
      ),
      oaa_TraceMsg(
       '-n-q trigger fired (-q): -q AND -q,-n Action: -q-n',
         [Type, Op, Cond, Test, Action]),
      (Type \== comm ->
         oaa Inform(trigger,
            'trigger_fired(~q,~q,~q,~q,~q)~n',
             [Type, Cond, Action, Params])
      true),
      % FIRE!!!!
        oaa_fire_trigger(Action),
      % loop back for more triggers
      fail.
oaa_CheckTriggers(_Type, _Cond, _Op).
oaa_fire_trigger(oaa_Solve(Goal, Params)) :-
    1,
    ( memberchk(block( ), Params) ->
     NewParams = Params
    | otherwise ->
     append([block(false)], Params, NewParams)
    ),
    oaa_Solve(Goal, NewParams).
oaa_fire_trigger(oaa_Solve(Goal)) :-
    !,
    oaa Solve(Goal, [block(false)]).
oaa_fire_trigger(oaa_Interpret(Goal, Params)) :-
    !,
```

```
( memberchk(from(_), Params) ->
    NewParams = Params
    otherwise ->
        oaa_Id(Me),
        append([from(Me)], Params, NewParams)
    ),
        oaa_Interpret(Goal, NewParams).
oaa_fire_trigger(oaa_Interpret(Goal)) :-
    !,
        oaa_Id(Me),
        oaa_Interpret(Goal, [from(Me)]).
oaa_fire_trigger(Goal) :-
        oaa_Id(Me),
        oaa_Id(Me),
        oaa_Id(Me),
        oaa_Iterpret(Goal, [from(Me)]).
```

```
% name:
         oaa AddTrigger
% purpose: Adds a trigger according to parameters
         = comm, data, task, time
% Type
% Condition= comm:event to match, data:data to match, task:solvable to call
           time:@@
% Action = Can be any of these:
₽
             oaa Solve(Goal, Params)
¥
             oaa Interpret (Goal, Params)
₽
             Goal [passed to oaa Interpret with default params]
% Params
   address(X): a list including 'self', 'parent', and/or the
¥
     addresses of other client agents. Default: see below.
욯
¥
   test(T): additional tests before trigger will fire [@@needs work?]
₽
   on(OP) : operation check: on(add), on(remove), on(receive), etc.
옿
   recurrence(R): when, whenever, or integer (# of times to execute)
₽
   reply({true,none}): When a trigger is being added on
₽
     a remote agent or agents, this tells whether reply message(s) are
ક્ર
     desired.
¥
   block(Mode) : true: Block until the reply arrives.
ક્ષ
              : false: Don't block. In
ક
                     this case, the reply events
뫙
                      can be handled by the user's app_do_event callback
₽
              Default: true. Note that reply(none) overrides
₽
                      block(true).
₿
   get address(X): Returns a list of addresses (ids) of agents that
∛
     were sent the request.
ક્ર
   get satisfiers(X): Returns a list of addresses (ids) of agents that
ક્ષ
     successfully completed the request.
8
% Default destination for triggers:
€
    Data triggers: all agents with solvables matching the Condition
ક્ર
       field.
    All other types: the local agent
¥
oaa AddTrigger(Type, Condition, Action, InitialParams) :-
  oaa_update_trigger(add, Type, Condition, Action, InitialParams).
% name:
         oaa_RemoveTrigger
```

```
% purpose: Removes a trigger from a local or remote agent
oaa RemoveTrigger(Type, Condition, Action, Params) :-
   oaa update trigger (remove, Type, Condition, Action, Params).
oaa update trigger (Mode, Type, InCondition, Action, InParams) :-
   ( (Type == comm, \+ InCondition = event(_,_)) ->
      Condition = event (InCondition, )
   | otherwise ->
      Condition = InCondition
   ),
   icl standardize params (InParams, false, Params),
   % Is there a specified address?
   ( memberchk(address(Addr), Params) ->
      true
   | otherwise ->
      Addr = []
   ).
   % Decide whether or not to update locally:
   oaa Id(Me),
   ( Addr \== [], memberchk(Me, Addr) ->
      delete(Addr, Me, NewAddr),
      replace_element(address(Addr), Params, address(NewAddr), Params1),
      Self = true
   Addr = [], Type == data, icl_GetParamValue(reflexive(true), Params) ->
      % Do NOT use remove element here:
      delete(Params, reflexive(true), Params1),
      NewAddr = Addr,
      Self = true
   Addr = [], Type = data ->
      NewAddr = Addr,
      Params1 = Params,
      Self = true
   | otherwise ->
      NewAddr = Addr,
      Params1 = Params
  ),
   % Update locally if appropriate:
   ( Self == true ->
      Requestees1 = [Me],
      ( Type == add ->
          Functor = oaa add_trigger_local
      | otherwise ->
          Functor = oaa remove trigger local
      ),
      LocalCall = .. [Functor, Type, Condition, Action, Params1],
      ( call(LocalCall) ->
          Updaters1 = [Me]
          Updaters1 = [])
   otherwise ->
      Requestees1 = [],
      Updaters1 = []
  ),
  % Update remotely if appropriate:
```

```
( oaa_class(leaf), ((Addr == [], Type = data) ; NewAddr \== []) ->
     % Send the request event to the Facilitator
     oaa PostEvent(
       ev post trigger update (Mode, Type, Condition, Action, Params1), []),
      ( (icl GetParamValue(reply(asynchronous), Params) ;
        icl GetParamValue(reply(none), Params)) ->
         Requestees2 = [],
         Updaters2 = []
      | otherwise ->
         % In the return event, Requestees lists all agents to whom
         % the update request was sent; Updaters2 lists those who succeeded.
         oaa poll until event(
          ev reply trigger_updated (Mode, Type, Condition, Action, Params1,
                          Requestees2, Updaters2))
     )
  | otherwise ->
     Requestees2 = [],
     Updaters2 = []
  ),
  append(Updaters1, Updaters2, Updaters),
  % Return Updaters if requested:
  ( memberchk(get satisfiers(Updaters), Params) -> true | true ),
  append (Requestees1, Requestees2, Requestees),
  % Return Requestees if requested:
  ( memberchk(get address(Requestees), Params) -> true | true ).
oaa add trigger local (Type, Condition, Action, Params) :-
   gensym(trg, TriggerId),
   oaa add data local(
      oaa trigger(TriggerId, Type, Condition, Action, Params),
     []).
oaa_remove_trigger_local(Type, Condition, Action, Params) :-
   oaa remove data local(
      oaa trigger( TriggerId, Type, Condition, Action, Params),
     []).
***********************
         oaa_remove_local_trigger_by_id
% name:
% purpose: Removes a local trigger given its unique identifier
oaa_remove local trigger by_id(TriggerId) :-
    oaa_remove data local(oaa trigger(TriggerId, , , , ), []),
     1.
% Requesting Services
% name:
        oaa Solve
% purpose: Sends work or information requests to distributed agents, brokered
       by the Facilitator agent
```

```
ⴻ
옿
    The default behavior (paramlist = []) is to act like the Prolog primitive
    call(Goal), blocking until Goal is finished, and unifying and backtracking
욹
₽
    over solutions for Goal.
₽
ક્ષ
    This behavior may be modified by a parameter list, which may contain:
€
ł
        cache(T F)
                           : cache all solutions locally, and if good solutions
¥
                        already exist in the cache, use the local values
욹
                        instead of making a distributed request.
<del>۶</del>
                              Default: false.
옿
        level limit(N)
                         : highest number of hierarchical levels to climb for
₽
                              solutions.
        address(AgentId): send request to specific agent, given its name or Addr
¥
8
                     If AgentID is 'self', solves the goal locally
옿
        reply(Mode)
                         : true: Reply desired.
¥
                         : none: No reply desired.
g
                         Default: true, except when the call to oaa Solve
뭉
                           is a trigger action, in which case it is
₽
                           none. 'none' is used here instead of false,
ક્ષ
                           because we anticipate some additional values.
옿
        block(Mode)
                         : true: Block until the reply arrives.
ક્ર
                         : false: Don't block. In
ક્ર
                           this case, the reply events (ev reply solved)
ક્ર
                           can be handled by the user's app do event callback
옿
                         Default: true, except when the call to oaa Solve
₽
                           is a trigger action, in which case it is
ⴻ
                           false. Note that reply(none) overrides
₿
                           block(true).
₽
        solution limit(N)
¥
                  : limits the maximum number of solutions found to N
ક્ષ
        time_limit(N)
                         : Waits a maximum of N seconds before returning
₽
                        (failure if no solution found in time).
₽
        context(C)
                         : Passes a context value through any subsequent
움
                    solves.
웅
        parallel_ok(T_F): if T_F is 'true' (default), multiple agents
₽
                    that can solve the Goal will attempt to work on it
ક્ષ
                    in parallel. If 'false', one agent will be selected
₽
                    at a time to solve the goal, until the maximum
₽
                    number of requested solutions (see solution_limit) is
₽
                    found.
뭉
      reflexive(T F)
€
                  : If T F is `true', the Facilitator will consider the
ક્ર
                       originating agent when choosing agents to solve a
8
                       request. Default: true.
욯
      priority(P) : P ranges from 1 (low priority) to 10 (high priority)
ક્ર
                              with a default of 5.
₽
        flush events (T F)
욯
                         : Will flush (dispose of) all events of lower priority
욹
                                                                  These
                    currently queued at the destination agent.
₽
                    events are lost, and will not be executed.
₽
                    This parameter should be used with caution !!!
욯
                           Default: false.
욯
        get_address(X)
                         : Returns a list of addresses (ids) of agents that
*
                           were asked to solve the goal, or one of its subgoals
¥
        get_satisfiers(X)
Ŷ.
                         : Returns a list of addresses (ids) of agents that
```

```
¥
                         succeeded in solving the goal, or one of its
¥
                         subgoals.
윻
욯
        strategy(S)
                       : Shorthand for certain combinations of the above
ક્ર
                         parameters. S is one of
₽
                           query = [parallel ok(true)]
욯
                           action = [parallel ok(false), solution limit(1)]
₽
                           inform = [parallel ok(true), reply(none)]
욹
Ł
    Remarks: Note that certain combinations of parameters are inconsistent,
ક્ષ
    and are handled as follows:
€
        reply(none) overrides block(true)
옿
        reply(none) overrides parallel ok(false)
₽
ક્ર
    All of the above parameters may be used in the "global" parameter
₽
    list (the second argument to oaa_Solve), when Goal is non-compound.
¥
   Most can be used in the global list with compound goals also.
¥
    Some of these parameters can also be used in the NESTED parameter
¥
   lists of compound goals. Uses of these parameters with compound
₽
   goals are documented elsewhere. When that documentation exists,
   this will go there:
₽
   With many compound goals, however, the get satisfier/1 parameter isn't
Å
   really meaningful. Thus, with compound goals, it is often best to use
ક્ર
₽
    this parameter in a nested parameter list.
oaa Solve(Goal, InitialParams) :-
      % Trace message
      oaa TraceMsg('~n~nStarting oaa Solve request:~n ~q [~q]...~n',
         [Goal, Params]),
      icl standardize params (Initial Params, false, Params),
      % Check for inappropriate params
        ( icl GetParamValue(cache(true), Params), icl compound goal(Goal) ->
          format('~w: ~w (~w)~n Goal: ~w~n',
               ['WARNING', 'Ignoring ''cache'' parameter',
                'cannot be used with compound goal', Goal]),
           Compound = true
      | otherwise ->
         Compound = false
     ),
      % Add context to params
      ( oaa_current_contexts(_, Contexts) ->
         append (Contexts, Params, NewParams)
      | otherwise ->
         NewParams = Params
     ),
      % check cache
      (icl GetParamValue(cache(true), NewParams), \+ Compound,
      on_exception(_, oaa_InCache(Goal, Solutions), fail) ->
          oaa TraceMsg('~n~nSolutions found in cache:~n ~q.~n',
             [Solutions])
      % Should I solve this only locally?
        (oaa_Id(Me),
```

```
memberchk(address(Me), Params) ->
            findall(Goal, oaa solve local(Goal, NewParams), Solutions)
          % send request to Facilitator
          oaa cont solve (Goal, NewParams, Solutions),
          % print appropriate trace message
          (icl GetParamValue(reply(none), NewParams) ->
             oaa TraceMsg('~n~nMessage broadcast.~n', [])
          oaa TraceMsg('~n~nSolutions returned:~n ~q.~n',
               [Solutions])
          ),
          % cache returned solutions if necessary
          ((icl GetParamValue(cache(true), NewParams), Solutions \== []) ->
             oaa AddToCache (Goal, Solutions),
             oaa_TraceMsg('Solutions cached.~n',[])
          | true)
        )
      ),!,
      % backtrack over all solutions
      member(Goal, Solutions).
oaa solve local(FullGoal, Params) :-
    % Validate the qoal:
    icl_GoalComponents(FullGoal, _, Goal1, GoalParams),
    ( oaa solvables (Solvables) -> true | otherwise -> Solvables = []),
    ( icl compound goal(Goal1) ;
      icl BuiltIn(Goal1) ;
      oaa goal matches solvables (Goal1, Solvables, Goal, Matched) ),
    1,
    % More "local" params take precedence, so they go to the
    % beginning of the list:
   append([GoalParams, Params], AllParams),
   % We don't want tests to be performed repeatedly with compound goals,
   % so we remove them after testing.
    ( passes tests(AllParams) ->
       delete(AllParams, test(_), NewParams),
      ( ( \+ var(Matched), Matched = solvable( , SolvParams, ),
          icl GetParamValue(type(data), SolvParams) ) ->
            ( memberchk(solution limit(N), AllParams) ->
                call n(N, Goal)
            | otherwise ->
                call(Goal)
            )
      otherwise ->
          ( memberchk(solution limit(N), AllParams) ->
              call n(N, oaa_Interpret(Goal, NewParams))
          | otherwise ->
              oaa Interpret (Goal, NewParams)
          )
```

```
)
   | otherwise ->
      oaa TraceMsg('~nDoesn''t pass test in: ~q~n', [AllParams]),
     fail
   ).
oaa solve local(FullGoal, Params) :-
      format('~nError: do not know how to solve: ~q~n', [FullGoal]), fail.
% name:
        oaa cont solve
% purpose: Post request for solutions, and if appropriate, poll until
8
       results are returned.
oaa_cont_solve(Goal, GlobalParams, Solutions) :-
     % Send the ev_post_solve event to the Facilitator
     oaa PostEvent(ev post_solve(Goal, GlobalParams),[]),
     % Compound goals may also contain relevant params
       icl GoalComponents(Goal, _, _, Params),
     append (Params, Global Params, All Params),
     % If delayed reply or no reply OK, succeed immediately
     ( ( icl GetParamValue(reply(false), AllParams) ;
        icl GetParamValue(reply(none), AllParams) ;
        icl GetParamValue(block(false), AllParams) ) ->
       Solutions = [Goal],
       Requestees = [],
       Solvers = []
     % otherwise wait for solutions to return
       icl GetParamValue(priority(P), AllParams),
       oaa poll until event (ev reply solved (Requestees, Solvers, Goal,
SolvedParams, Solutions),
                       P),
      % The facilitator is responsible for making SolvedParams
      % unifiable with GlobalParams. This msg is to keep facilitator
      % writers honest.
       ( GlobalParams = SolvedParams ->
          true
      | otherwise ->
          format('-w: -w -w-n -w: -w-n',
              ['WARNING:', 'Params in solved event don''t unify',
               'with original params', 'SolvedParams', SolvedParams])
      )
     ),
      % Return Solvers if requested:
     ( memberchk(get_satisfiers(Solvers), GlobalParams) -> true | true ),
      % Return Requestees if requested:
     ( memberchk(get address(Requestees), GlobalParams) -> true | true ).
% name:
         oaa Solve/1
% purpose: Convenience function: oaa_Solve with default parameters
```

```
oaa_Solve(Goal) :- oaa_Solve(Goal, []).
% name: oaa InCache
% purpose: Retrieve solutions from the cache if the goal we are
      asking for is properly contained in the cache (check subsumption)
oaa InCache (Goal, Solutions) :-
  oaa cache(SomeGoal, ),
  subsumes chk(SomeGoal, Goal),
  1.
  findall(Solution, oaa cache(Goal, Solution), Solutions).
% name:
      oaa AddToCache
% purpose: Add each solution to goal one at a time
     so we can retrieve solutions later using findall
oaa AddToCache (Goal, Solutions) :-
    member(Solution, Solutions),
     \+ oaa cache(Goal, Solution),
    assert (oaa cache (Goal, Solution)),
    fail.
oaa AddToCache ( Goal, Solutions).
oaa ClearCache
% name:
% purpose: Clear the cache
oaa ClearCache :-
  retractall(oaa cache( , )).
% name:
      oaa poll until event
% purpose: Block until requested event arrives in oaa GetEvent
oaa poll until event(Event) :-
  icl param default(priority(P)),
  oaa poll until event(Event, P).
oaa poll until event (Event, Priority) :-
   oaa poll until all events([Event], Priority).
oaa poll until all events
% name:
% purpose: Block until all requested events arrive
% no more events: we're done!
```

```
oaa poll until all events([], Priority) :- !.
%% @@Adam - you were apparently working on this; I corrected a syntax
%% error or two, but otherwise left it alone. - Dave
oaa poll until all events(EventList, Priority) :-
     % If we have a waiting event, grab it
        see problem description in (oaa is waiting for)
     *
     (oaa grab waiting event(EventList, Event) ;
     oaa_GetEvent(Event, Params, 0)),
     % if timeout returned, check triggers and call user:oaa AppIdle
         then fail (continue with next clause)
     (Event = timeout ->
       oaa_CheckTriggers(task, _, _),
       oaa call_callback(app_idle, _, []),
       fail
     oaa cont poll until all events (EventList, Event, Params, Priority)
     ), !.
% if oaa GetEvent fails (e.g. timeout), just continue waiting
oaa poll until all events (EventList, Priority) :-
     oaa poll_until_all_events(EventList, Priority).
oaa cont poll until all events (EventList, Event, Params, Priority) :-
     remove element (Event, EventList, NewEventList), !,
     oaa poll until all events (NewEventList, Priority).
oaa cont poll until all events (EventList, Event, Params, Priority) :-
     % if the new event is a ev_reply_solved() message for which we
     % are waiting at a higher recursive level, save this for
     % a later time, until we pop back out to the correct level.
     (oaa is waiting for (Event) ->
       assert (oaa waiting event (Event))
       % record what events we are waiting for on this processing level
       gensym(wait, WaitId),
       assert(oaa_waiting_for(WaitId, EventList)),
        (oaa ProcessEvent(Event, Params) | true), !,
       % level over, remove waiting statement
       retract(oaa waiting for(WaitId, EventList))
     ),
     oaa poll until all events (EventList, Priority).
% Callbacks
% name:
         oaa RegisterCallback
% purpose: Declare what procedures should be used for callbacks. These
s.
         are application-defined procedures called by library code.
oaa_RegisterCallback(CallbackID, CallbackProc) :-
```

```
( CallbackProc = Module:Proc ->
    true
   | otherwise ->
    Module = user,
    Proc = CallbackProc
  ),
  retractall( oaa callback(CallbackID, ) ),
  assert ( oaa callback (Callback ID, Module: Proc) ).
oaa call callback(CallbackID, SpecifiedCB, Args) :-
   ( ground(SpecifiedCB) ->
    SpecifiedCB = Module:Functor
   | otherwise ->
    oaa callback(CallbackID, Module:Functor)
  ),
   !,
  Call = .. [Functor | Args],
  on exception(E,
         Module:Call,
         ( oaa TraceMsg('WARNING (oaa.pl): Exception raised thru callback
handler (-w):-n -q-n',
                   [Module:Functor, E]),
          fail )
        ).
oaa call callback( CallbackID, SpecifiedCB, Args).
************
% Debugging
************************
% name:
       oaa TraceMsg
% purpose: If trace mode is on, display message and arguments
oaa TraceMsg(FormatString, Args) :-
    (oaa_trace(on) ->
       format(FormatString, Args)
$
       oaa_Inform(trace_info, FormatString, Args)
       ;
       true).
oaa ComTraceMsg
% name:
% purpose: If com trace mode is on, display message and arguments
*********************
oaa ComTraceMsg(FormatString, Args) :-
    (oaa com trace(on) ->
       format(FormatString, Args)
¥
       oaa Inform(trace info, FormatString, Args)
       true).
% name:
       oaa turn on debug
% purpose: start debugging if debug mode is on
% remarks:
```

```
₽
   Use predicate property and call so as to avoid errors in
   building and running a Quintus runtime system.
oaa turn on debug :-
    (oaa debug(on) ->
      ( predicate property(user:trace, built in) ->
         call(user:trace)
      | true )
     | true).
% name:
       oaa turn off debug
% purpose: stop debugging if debug mode is on
% remarks:
   Use predicate property and call so as to avoid errors in
9
   building and running a Quintus runtime system.
8
oaa turn off debug :-
    (oaa debug(on) ->
      ( predicate property(user:nodebug, built in) ->
         call(user:nodebug)
      | true )
     | true).
% User Interface
% name:
       oaa Inform
% purpose: sends a typed message to interested agents
oaa_Inform(TypeInfo, FormatString, Args) :-
      oaa_TraceMsg(FormatString, Args),
      (oaa class(leaf) ->
        sprintf(Result, FormatString, Args),
        oaa Solve(inform(TypeInfo, Result), [strategy(inform)])
        true
      ), !.
% Connection primitives
%%% BUG/HACK!!!!!
% tcp send/1 is not currently defined (new version of quintus)
% so these predicates should fail. This means we can't have
% multilevel facilitators.
% However, if we fix it by the tcp send/2 version (commented out),
% killing the agent doesn't shut down both connections and the
% facilitator server doesn't register the agent as disconnected.
```

% This must be fixed, but I don't have time now... % Ask the root agent for the address of facilitator FacName. % Either FacId or FacName may be bound. % IMPORTANT: This assumes the root agent is the only connection when % this is called. % @@Not happy with the use of a Connection number in the address param here. % Can an address be a connection number as well as an id or name??? [No.] % get address(FacId, FacName, Port, Host):-8 tcp connected (RootConnection), 8 oaa_Solve(agent_location(FacId, FacName, Port, Host), Å [address(RootConnection)]). %% succeed if FacName has not been registered with the root agent. otherwise, ask user to enter a different name for FacName 응용 % check_name duplication(MyName, NewMyName) :tcp send(ev check_agent name(MyName)), ¥ ₽ oaa select event(0, X), oaa_extract_event(X, Result, _), %% 'UNIQUE' ₽ (Result == 'UNIQUE' -> NewMyName = MyName ₽ ₽ ₽ format('Name is duplicated~n',[]), format('The following are registered ~n ~q ~n', [Result]), z ¥ format('Input agent name again:',[]), 8 read(NewMyName)). % report address to root(MyName, NewAddress):-¥ tcp send(register port number(MyName, NewAddress)). % routines to fix bug: ¥ blocking solve1 R incoming event generates blocking solve2 ₽ solution to solve1 thrown away!!! € solutions to solve2 stuck waiting for solvel forever * oaa is waiting for ¥ name: % purpose: Check to see if the current event is something we are waiting for on a higher recursive level ***************** oaa is waiting for (Event) :oaa_waiting_for(_Id, EventList), memberchk(Event, EventList). ********************** oaa grab waiting event % name: % purpose: If one of the delayed events is in the EventList that we are waiting for, return this event and remove from delayed list ********************** oaa grab waiting event (EventList, Event) :-

```
oaa waiting event(Event),
       memberchk(Event, EventList),
       1,
       retract (oaa waiting event (Event)).
% OAA Utilities
% name:
         oaa remove solvables data(Solvables).
% purpose: For each data solvable, remove all clauses belonging to it.
% remarks: - Solvables must be in standard form, and should include only
÷
           data solvables.
         - Permissions are ignored.
oaa remove solvables data([]).
oaa_remove_solvables_data([Solvable | Solvables]) :-
   Solvable = solvable(Goal, Params, Perms),
   icl GetParamValue(type(data), Params),
   \+ memberchk(synonym( ,  ), Params),
   1,
   % This should have already been done, but to be safe:
   (clause(Goal, _, _) -> true | true),
   predicate skeleton(Goal, Skeleton),
   ( oaa remove data local(Skeleton, [do all(true)]) ->
       true
   | otherwise ->
      format('~w: Problem in removing all data for solvable: ~w~n',
           ['! ERROR', Goal])
   ),
   oaa_remove_solvables_data(Solvables).
oaa_remove solvables data([_Solvable | Solvables]) :-
   oaa_remove_solvables_data(Solvables).
oaa remove data owned by(Id) :-
   ( oaa_solvables(Solvables) -> true | otherwise -> Solvables = []),
   oaa built in solvables (BuiltIns),
   append (BuiltIns, Solvables, AllSolvables),
   oaa remove data owned by (AllSolvables, Id).
oaa remove data owned by([], Id).
oaa remove data owned by ([Solvable | Solvables], Id) :-
   Solvable = solvable(Goal, Params, Perms),
   icl GetParamValue(type(data), Params),
   \+ icl GetParamValue(persistent(true), Params),
   \+ icl_GetParamValue(synonym(_, _), Params),
   1.
   % This should have already been done, but to be safe:
   (clause(Goal, , ) -> true | true),
   predicate skeleton(Goal, Skeleton),
   ( oaa_remove_data_local(Skeleton, [owner(Id), do_all(true)]) ->
      true
   | otherwise ->
      format('~w: Problem in removing data owned by ~w for solvable:~n ~w~n',
           ['! ERROR', Id, Goal])
```

```
),
  oaa remove data owned by (Solvables, Id).
oaa remove data owned by ([ Solvable | Solvables], Id) :-
  oaa remove data owned by (Solvables, Id).
% General Utilities
************************
      oaa consult(+FilePath, -AbsFileName).
% name:
% purpose:
% remarks: We don't use Quintus' builtin consult, because it's too picky
      about associating predicates with files.
¥
******
oaa consult(FilePath, AbsFileName) :-
  absolute file name (FilePath, AbsFileName),
  can open file (AbsFileName, read, fail),
  open(AbsFileName, read, Stream),
  load clauses(Stream),
  close(Stream).
% name:
      load clauses(+Stream).
% purpose:
load_clauses(Stream) :-
  repeat,
  read term(Stream, [], Term),
  ( Term = ':-'( Body) ->
   true
  Term = end of file ->
   true
  otherwise ->
    load_clause(Term)
  ),
  ( at end of file(Stream) ->
   1
  | otherwise ->
   fail
  ).
**********************
% name:
      load clause (+Term).
% purpose:
load clause(Term) :-
  assert ( Term ).
% name:
      oaa declare for prolog(Solvables).
% purpose: For each solvable, make sure it's known to Prolog as a dynamic
```

```
% predicate. This will prevent exceptions and warnings from
```

```
욹
      calls and retracts before there have been any asserts.
% remarks: Solvables must be in standard form, and should include only
₽
      data solvables.
₽
      This is probably Quintus-specific.
*
      We are assuming that none of these predicates are known to
÷.
      Prolog as compiled predicates. Would be better to check for this.
oaa declare for prolog([]).
oaa declare for prolog([solvable(Pred, , ) | Rest]) :-
  copy_term(Pred, PredCopy),
  ( clause(PredCopy, _Body) -> true | true ),
  oaa declare for prolog(Rest).
predicate skeleton(+Goal, +Skeleton).
% name:
predicate skeleton(Goal, Skeleton) :-
  functor (Goal, Functor, Arity),
  functor (Skeleton, Functor, Arity).
% name:
      sprintf
% purpose: C-like command formats a string + args into an atom
sprintf(AtomResult, FormatStr, Args) :-
 with output to chars (format (FormatStr, Args), Chars),
 name (AtomResult, Chars).
% name:
      memberchk nobind
% purpose: like memberchk, but doesn't bind variables in Elt when doing test.
memberchk nobind(Elt, [H] ]) :-
   would_unify(Elt, H), !.
memberchk_nobind(Elt, [_|T]) :-
   memberchk_nobind(Elt, T).
% name:
      would unify
% purpose: succeeds if X and Y WOULD unify, but doesn't actually do the
      unification (no variables are bound by test)
would_unify(X,Y) :- + + X = Y.
% name:
      remove element
% purpose: Removes the element X from a list
% remarks: Fails if X is not an element in the list
remove_element(X, [X | Rest], Rest) :- !.
```

```
remove_element(X, [Y|Rest], [Y|Rest2]) :- remove_element(X, Rest, Rest2).
```

```
replace element (Elt, List, New, NewList)
% name:
% purpose: Replaces the element Elt, if present in List, with the element New
% remarks: If there are multiple occurrences of Elt, only replaces the first
replace element(Elt, [Elt|Rest], New, [New|Rest]) :- !.
replace element(Elt, [Y Rest], New, [Y Rest2]) :-
   replace element (Elt, Rest, New, Rest2).
% name:
        select elements (List, Selector, NewList)
% purpose: Selects all List elements for which Selector(element) succeeds.
% remarks: If there are multiple occurrences of Elt, only replaces the first
select_elements([], _Selector, []).
select_elements([Element | Elements], Selector, [Element | Selected]) :-
   Test =.. [Selector, Element],
   call( Test ),
   1,
   select elements (Elements, Selector, Selected).
select elements ([ Element | Elements], Selector, Selected) :-
   select elements (Elements, Selector, Selected).
% name:
        call n(+N, +Goal)
% purpose: Call Goal with a limit on the number of solutions generated.
call n(1, Goal) :-
   call(Goal),
   1.
call n(N, Goal) :-
   % Remember the counter's value in case anyone else is using it.
   ctr_is(12, CtrOrig),
   call n aux(N, Goal, CtrOrig).
call_n_aux(N, Goal, CtrOrig) :-
   N > 1,
   ctr set(12, 1),
   call(Goal),
   ctr inc(12, 1, M),
   ( M =< N ->
     true
   | otherwise ->
     ctr set(12, CtrOrig),
    !,
    fail
  ).
   % This clause is for when the Goal fails before M > N:
call_n_aux(_N, _Goal, CtrOrig) :-
   ctr set(12, CtrOrig),
   1,
   fail.
```

```
% findall with a limit on the number of solutions generated.
findNSolutions(0, _Var, _Predicate, []).
findNSolutions(1, Var, Predicate, [Var]) :-
        call(Predicate), !.
findNSolutions(1, _Var, _Predicate, []).
findNSolutions(N, Var, Predicate, Solutions) :-
   N > 1,
    % Save the counter's value in case anyone else is using it.
   ctr_is(12, CtrOrig),
   ctr set(12, 1),
    findall(Var,
            (Predicate, ctr inc(12, 1, M),
            (M \ge N -> ! | otherwise -> true)),
          Solutions),
    ctr_set(12, CtrOrig).
$ _____
% No longer used: replaced or obsolete
% initialize all data flags
% oaa init flags :-
     % set appropriate prolog flags
웅
욯
     prolog flag(fileerrors, ,on),
€
     prolog flag(syntax_errors, _, error),
¥
     % Let's use retractall so as to avoid unknown exceptions when tracing:
     retractall(oaa_cache(_,_)),
retractall(oaa_already_loaded(_)),
₽
8
£
     assert(oaa_trace(off)),
¥
     assert(oaa_debug(off)),
옿
     assert(oaa com trace(off)),
₽
     tcp_trace(_,off).
```



APPENDIX A.V

Source code file named translations.pl.

욹 File : translations.pl ¥ Primary Authors : David Martin, Adam Cheyer ₽ Purpose : Provides translations for backward compatibility with OAA 1.0 ¥ 욯 ¥ Unpublished-rights reserved under the copyright laws of the United States. ¥ Ł ¥ Unpublished Copyright (c) 1998, SRI International. ¥ "Open Agent Architecture" and "OAA" are Trademarks of SRI International. 9 % This file is loaded by facilitator code, and thus no % module imports are needed here. % Currently, we support a 3.0 facilitator with a mix of 3.0 and/or pre-3.0 % clients. % A pre-3.0 facilitator with a 3.0 client is NOT supported, and probably % never will be. :- multifile oaa AppDoEvent/2. % At present we only support the case where the facilitator is 3.0, and % the client is pre-3.0. % Here we can ignore the languages. oaa_event_translation(2.0, L1, 3.0, L2, Connection, Event1, Event2) :oaa event translation(2.1, L1, 3.0, L2, Connection, Event1, Event2). oaa_event_translation(2.1, _L1, 3.0, _L2, _Connection, Event1, Event2) :-(Event1 = event(From, Contents1, Priority) -> Params2 = [from(From), priority(Priority)] Event1 = event(From, Contents1) -> Params2 = [from(From)] Event1 = Contents1 -> Params2 = []), (ev_trans_21_30(Contents1, Contents2) -> true | otherwise -> Contents2 = Contents1), Event2 = event(Contents2, Params2). % Here we can ignore the languages. oaa_event_translation(3.0, L1, 2.0, L2, Connection, Event1, Event2) :oaa_event_translation(3.0, L1, 2.1, L2, Connection, Event1, Event2). oaa_event_translation(3.0, _L1, 2.1, _L2, _Connection, Event1, Event2) :-Event1 = event(Contents1, Params1), (ev trans 30 21(Contents1, Params1, Contents2) -> true | otherwise -> Contents1 = Contents2), (memberchk(from(KS), Params1) ->

```
Event2 = event(KS, Contents2)
   otherwise ->
     Event2 = Contents2
   ),
   !.
   % Anything not specified explicitly stays the same:
oaa_event_translation(3.0, _L1, 2.1, _L2, _Connection, E1, E1).
******
% The following could go to or from the facilitator.
ev trans 21 30(trace on, ev_trace_on).
ev trans 21 30(trace_off, ev_trace_off).
ev_trans_21_30(tcp_trace_on, ev_com_trace_on).
ev_trans_21_30(tcp_trace_off, ev_com_trace_off).
ev trans 21 30 (debug on, ev debug on).
ev trans 21 30 (debug off, ev debug off).
ev_trans_21_30(set_timeout(N), ev_set_timeout(N)).
ev trans 21 30(halt, ev_halt).
*******
% The following are sent only from (pre-3.0) client to facilitator.
*****
ev_trans_21_30(post_event(Event), ev_post_event(NewEvent)) :-
   ev_trans_21_30(Event, NewEvent).
ev_trans_21_30(post_event(To, Event), ev_post_event(To, NewEvent)) :-
   ev trans 21 30 (Event, NewEvent).
ev trans 21 30 (post query (Goal, Params),
           ev post solve(Goal, [reflexive(false) | NewParams])) :-
   params trans 21 30 (Params, NewParams).
% This is the message from a facilitator to its parent facilitator;
% will probably evolve:
% ev trans 21 30(register solvable goals(AGL), register_solvable_goals(AGL)).
% NO, we don't want to translate this. The old form is still handled
% by the new facilitator:
% ev trans 21 30(register solvable goals(GoalList, KSName),
*
                       ev register solvables (add, GoalList, KSName,
                                [if exists(overwrite)])).
₽
ev_trans 21 30(solved(GoalId, FromKS, Goal, SolveParams, Solutions),
      ev solved(GoalId, FromKS, Goal, SolveParams, Solutions)).
/* post trigger/4: retained for backwards compatibility */
ev_trans 21_30(post_trigger(test, Type, Cond, Action), NewEvent) :-
   ev_trans_21_30(post_trigger(test, Type, unused, unused, Cond, Action),
             NewEvent).
/* post trigger/4: retained for backwards compatibility */
ev trans 21 30 (post trigger (data, Type, Cond, Action), NewEvent) :-
   ev_trans_21_30(post_trigger(data, Type,
                     [on_write, on_write_replace, on_replace],
                     Cond, true, Action), NewEvent).
```

•

```
/* post_trigger/4: retained for backwards compatibility */
ev trans 21 30 (post trigger (event, Type, Cond, Action), NewEvent) :-
    ev trans 21 30 (post trigger (event, Type, [on receive], Cond, true, Action),
               NewEvent).
ev trans 21 30 (post trigger (Kind, Recur, OpMask, Template, Test, Action),
             ev post trigger update(add,Mode,Condition,NewAction,Params)) :-
    (Kind == test -> Mode = task
      Kind == event -> Mode = comm
     Kind == alarm -> Mode = time
    otherwise -> Mode = Kind ),
    ( Recur == whenever ->
      Recurrence = [recurrence(whenever)]
    | otherwise ->
      Recurrence = [recurrence(when)]
    ),
    template_trans_21_30(Kind, Template, Condition),
    ( var(Test) -> TestParam = [] | otherwise -> TestParam = [test(Test)] ),
    ( Mode == data, ev trans 21 30 (Action, NewAction) -> true
    otherwise -> NewAction = Action ),
    opmask trans 21 30 (OpMask, OpParam),
    ( Mode == data ->
      oaa Id(FacId),
      Addr = [address(FacId)]
    otherwise ->
      Addr = []
    ),
    append([Addr, [reply(none), reflexive(false)],
          Recurrence, TestParam, OpParam], Params).
ev_trans_21_30 (post_trigger(KS, Kind, Recur, OpMask, Template, Test, Action),
             ev post trigger update(add, Type, Condition, NewAction, Params)) :-
    ( Kind == test -> Type = task
    | Kind == event -> Type = comm
    | Kind == alarm -> Type = time
    otherwise -> Type = Kind),
    ( Recur == whenever ->
      Recurrence = recurrence (whenever)
    | otherwise ->
      Recurrence = recurrence (when)
    ),
    template trans 21 30 (Kind, Template, Condition),
    ( var(Test) -> TestParam = [] | otherwise -> TestParam = [test(Test)] ),
    oaa Id(FacId),
    ( KS == FacId, ev trans 21 30 (Action, NewAction) -> true
    otherwise -> NewAction = Action ),
    opmask trans 21 30 (OpMask, OpParam),
    append([[address(KS), reply(none), reflexive(false)],
          Recurrence, TestParam, OpParam],
         Params).
params trans 21 30([], []).
params_trans_21_30([Param | Params], [NewParam | NewParams]) :-
    ( param trans 21 30 (Param, NewParam) ->
      true
    | otherwise ->
     NewParam = Param
    ),
```

params trans 21 30 (Params, NewParams).

•

```
param_trans_21_30(cache, cache(true)).
param_trans_21_30(solution_limit(N), solution_limit(N)).
param_trans_21_30(reflexive, reflexive(true)).
param_trans_21_30(address(A), address(NewA)) :-
    ( is_list(A) -> NewA = A | otherwise -> NewA = [A] ).
param_trans_21_30(broadcast, reply(none)).
param_trans_21_30(asynchronous, reply(asynchronous)).
% @@DLM: is this handled?:
param_trans_21_30(test(T), test(T)).
param_trans_21_30(level_limit(N), level_limit(N)).
% @@DLM: NOT HANDLED!:
param_trans_21_30(and_parallel, and_parallel).
param_trans_21_30(or_parallel, or_parallel).
```



```
ev_trans_30_21(ev_trace_on, _EvParams, trace_on).
ev_trans_30_21(ev_trace_off, _EvParams, trace_off).
ev_trans_30_21(ev_com_trace_on, _EvParams, tcp_trace_on).
ev_trans_30_21(ev_com_trace_off, _EvParams, tcp_trace_off).
ev_trans_30_21(ev_debug_on, _EvParams, debug_on).
ev_trans_30_21(ev_debug_off, _EvParams, debug_off).
ev_trans_30_21(ev_set_timeout(N), _EvParams, set_timeout(N)).
ev_trans_30_21(ev_halt, _EvParams, halt).
```



```
ev_trans_30_21(
             ev solve(ID, Goal, NewParams),
            EventParams,
             solve(ID, Goal, Params)) :-
    params trans 30 21 (Params, NewParams).
ev trans 30 21(ev reply solved(, Solved, Goal, SolveParams, Solutions),
             _EventParams,
             solved (FromKS, Goal, SolveParams, Solutions)) :-
    ( Solved = [FromKS] ->
      true
    | otherwise ->
      FromKS = Solved
    ).
    % OBSOLETE: forget these:
% ev_trans 30 21(add trigger(data, Type, Cond, Action),
% ev_trans 30 21(add trigger(event, Type, Cond, Action)
% ev_trans_30_21(add_trigger(test, Type, Cond, Action)
% @@DLM: Don't think this is needed:
% ev_trans 30 21(inform_ui(TypeInfo, Result), ))
ev_trans_30_21(
```

```
_EventParams,
   add_trigger(Kind, Recur, OpMask, Template, Test, Action) ) :-
    ( Type = task -> Kind == test
    Type = comm-> Kind == event
    Type = time-> Kind == alarm
     otherwise -> Type = Kind ),
    ( memberchk(recurrence(whenever), TrigParams) ->
     Recur = whenever
    otherwise ->
     Recur = when
   ),
   Template = Condition,
    ( memberchk(test(Test), TrigParams) -> true | otherwise -> Test = _ ),
    ( memberchk(on(OpParam), TrigParams) ->
     true
    | otherwise ->
     OpParam = _
   ),
   opmask trans 30 21(OpParam, OpMask),
    ( memberchk(test(Test), TrigParams) -> true | true ).
params trans 30 21([], []).
params trans 30 21([Param | Params], [NewParam | NewParams]) :-
    ( param trans 30 21(Param, NewParam) ->
     true
    | otherwise ->
     NewParam = Param
   ),
   params_trans_30_21(Params, NewParams).
param trans 30 21(cache(true), cache).
param trans 30 21(solution limit(N), solution limit(N)).
param trans 30 21(reflexive(true), reflexive).
% @@DLM: double-check this:
param_trans_30_21(address(A), address(A)).
param trans 30 21(reply(none), broadcast).
param trans 30 21(reply(asynchronous), asynchronous).
% @@DLM: is this handled?:
param_trans_30_21(test(T), test(T)).
param_trans_30_21(level_limit(N), level_limit(N)).
param_trans_30_21(time_limit(N), time_limit(N)).
% @@DLM: NOT HANDLED!:
param_trans_30_21(and_parallel, and_parallel).
param_trans_30_21(or_parallel, or_parallel).
% The following are sent only from a pre-3.0 facilitator to a client.
% Backwards compatibility not currently supported.
% ev_trans_21_30(solved(FromKS, Goal, SolveParams, Solutions),
¥
        ev reply solved([FromKS], Solvers, Goal, SolveParams, Solutions)) :-
₽
     ( Solutions == [] ->
£
     Solvers = []
₽
     | otherwise ->
```

ev update trigger(ID, add, Type, Condition, Action, TrigParams),

```
ⴻ
     Solvers = [FromKS]
₽
     ),
융
      ( memberchk(get address(FromKS), SolveParams) ->
¥
     true
€
     | otherwise ->
ⴻ
     FromKS = unknown
맟
     ).
% Auxiliary procedures.
% Returns either a Singleton list or an empty list.
opmask_trans 21 30(OpMask, []) :-
   var(OpMask),
    1.
opmask_trans 21 30(OpMask, OpParam) :-
    \+ is list(OpMask),
    1,
   opmask_trans_21_30([OpMask], OpParam).
opmask trans 21 30([], []).
opmask trans 21 30([Elt | Rest], [EltTrans | RestTrans]) :-
   opmask elt trans 21 30(Elt, EltTrans),
    1,
   opmask trans 21 30 (Rest, RestTrans).
opmask trans 21 30([ Elt | Rest], RestTrans) :-
    1.
   opmask trans 21 30 (Rest, RestTrans).
opmask_elt_trans_21_30(on_send, on(send)).
opmask_elt_trans_21_30(on_receive, on(receive)).
opmask_elt trans 21 30(on write, on(add)).
opmask elt trans 21 30(on retract, on(remove)).
opmask_elt_trans_21_30(on_replace, on(replace)).
% This one probably doesn't have a precise translation:
opmask_elt trans 21_30 (on_write replace, on (replace)).
opmask_trans_30_21(OpMask, OpMask) :-
   var(OpMask),
   1.
opmask_trans_30_21(OpMask, OpParam) :-
   \+ is list(OpMask),
   1,
   opmask trans 30 21([OpMask], OpParam).
opmask trans 30 21([], []).
opmask_trans_30_21([Elt | Rest], [EltTrans | RestTrans]) :-
   opmask_elt_trans_30_21(Elt, EltTrans),
   1,
   opmask trans_30_21(Rest, RestTrans).
opmask_trans_30_21([_Elt | Rest], RestTrans) :-
   1,
   opmask trans 30 21(Rest, RestTrans).
opmask elt trans 30 21(on(send), on send).
opmask_elt_trans_30_21(on(receive), on receive).
opmask_elt trans_30_21(on(add), on write).
opmask_elt_trans_30_21(on(remove), on_retract).
opmask_elt_trans_30_21(on(replace), on_replace).
% This one probably doesn't have a precise translation:
```

```
opmask_elt_trans_30_21(on(replace), on_write_replace).
template trans 21 30(data,
               data(ksdata, [AgentId, Status, Solvables, Name]),
               agent data(AgentId, Status, Solvables, Name)) :-
   !.
template_trans_21_30(data, Template, Template) :-
template trans 21 30 (event, Template, Condition) :-
   1.
   ev trans 21 30 (Template, Condition).
template_trans_21_30(_, Template, Template).
******
% Event handlers for selected pre-3.0 events.
$
% In these cases, this approach is easier than providing an event
% translation.
oaa AppDoEvent(register_solvable_goals(GoalList), Params) :-
       memberchk( connection id(Connection), Params),
     % This hack inherited from b.pl:
     oaa AppDoEvent (register solvable goals (GoalList, Connection),
                 Params).
oaa_AppDoEvent(register_solvable_goals(GoalList, Name), Params) :-
       memberchk( connection_id(Connection), Params),
     update_connected(Connection, [oaa_name(Name)]),
     icl ConvertSolvables (GoalList, Solvables),
     oaa AppDoEvent (ev register solvables (add, Solvables, Name, [if exists (overwri
te)]),
                 Params).
oaa_AppDoEvent(can_solve(Goal), EvParams) :-
   memberchk(from(KS), EvParams),
   findall(SomeKS, choose_ks_for_goal(KS, Goal, _, [], SomeKS, _), AgentList),
   oaa_PostEvent(return_can_solve(Goal, AgentList), [address(KS)]).
% BB events
oaa AppDoEvent(write bb(ksdata, [Id,Status,Solvables,Name]),
           EvParams) :-
   1,
   ( var(Solvables) ->
     % (Surely this never happens.)
       oaa:oaa add data local(agent data(Id,Status,Solvables,Name), [from(Id)])
   | otherwise ->
       icl ConvertSolvables (Solvables, FormalSolvables),
       oaa_AppDoEvent(ev_register_solvables(add,FormalSolvables,Name,
                                       [if exists(overwrite)]),
                     [from(Id) | EvParams])
   ).
oaa AppDoEvent(write_bb(oaa_version, V), EvParams) :-
```

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1,
    memberchk(from(Id), EvParams),
    % oaa:oaa add data local(data(oaa Version, V), [from(Id)]),
    com_GetInfo(ConnectionId, oaa id(Id)),
    com AddInfo(ConnectionId, agent version(V)).
oaa AppDoEvent(write_bb(language, Language), EvParams) :-
    1,
    memberchk(from(Id), EvParams),
    com GetInfo(ConnectionId, oaa id(Id)),
    com_AddInfo(ConnectionId, agent language(Language)).
oaa_AppDoEvent(write_bb(kshost, Host), EvParams) :-
    !,
    memberchk(from(Id), EvParams),
    oaa:oaa_solve_local(agent_data(Id, _, _, Name), []),
oaa:oaa_add_data_local(agent_host(Id, Name, Host),
                        [from(Id) | EvParams]).
oaa AppDoEvent(write bb(Item, Data), EvParams) :-
    !,
    memberchk(from(Id), EvParams),
    oaa:oaa_add_data_local(data(Item, Data), [from(Id)]).
oaa AppDoEvent(write once bb(Item, Data), EvParams) :-
    (Item = ksdata ; Item = oaa version ; Item = language ; Item = kshost),
    !,
    oaa AppDoEvent(write bb(Item, Data), [single value(true) | EvParams]).
oaa AppDoEvent(write once bb(Item, Data), EvParams) :-
    1.
    memberchk(from(Id), EvParams),
    oaa:oaa add data_local(data(Item, Data), [from(Id), single_value(true)]).
oaa_AppDoEvent(write_replace_bb(Item, Data), EvParams) :-
    (Item = ksdata ; Item = oaa version ; Item = language ; Item = kshost),
    1.
    oaa_AppDoEvent(write_bb(Item, Data), [unique_values(true) | EvParams]).
oaa_AppDoEvent(write_replace_bb(Item, Data), EvParams) :-
    1.
    memberchk(from(Id), EvParams),
    oaa:oaa add data local(data(Item, Data), [from(Id), unique values(true)]).
oaa_AppDoEvent(replace_bb(ksdata, [A,open,C,Name], [A,ready,C,Name]),
             EvParams) :-
    !,
    oaa_AppDoEvent(ev_ready(Name), EvParams).
oaa AppDoEvent (replace bb (ksdata, [Id, Status, Solvables, Name],
                             [NewId, NewStatus, NewSolvables, NewName]),
             EvParams) :-
    !,
    ( var(NewSolvables) ->
        oaa:oaa replace data local(agent_data(Id,Status,Solvables,Name),
            [from(Id), with(agent_data(NewId,NewStatus,NewSolvables,NewName))])
    otherwise ->
        icl ConvertSolvables (NewSolvables, FormalSolvables),
        oaa AppDoEvent (ev register solvables (add, FormalSolvables, NewName,
                                             [if exists(overwrite)]),
                        [from(NewId) | EvParams])
    ).
oaa_AppDoEvent(replace bb(Item, OldData, NewData), EvParams) :-
```

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```
1,
    memberchk(from(Id), EvParams),
    oaa:oaa replace data local(data(Item, OldData),
                      [from(Id), with(data(Item, NewData))]).
% @@DLM: May need more special-purpose clauses starting here:
oaa AppDoEvent(retract bb(Item, Data), EvParams) :-
    1,
    memberchk(from(Id), EvParams),
    oaa:oaa remove data local(data(Item, Data), [from(Id)]).
oaa AppDoEvent (read bb (ksdata, [AgentId, Status, Solvables, Name]), EvParams) :-
    1,
    memberchk(from(Id), EvParams),
    findall(read bb(ksdata, [AgentId, Status, Solvables, Name]),
          oaa:oaa_solve_local(agent_data(AgentId,Status,Solvables,Name), []),
          Solutions),
    oaa simplify ksdata (Solutions, Simplified),
    oaa PostEvent(return read bb(Simplified), [address(Id)]).
oaa_AppDoEvent(read_bb(KS,kshost,Host), EvParams) :-
    1,
    memberchk(from(Id), EvParams),
    findall(read bb(KS, kshost, Host),
          oaa:oaa solve local(agent host(KS, ,Host), []),
          Solutions),
    oaa_PostEvent(return_read_bb(Solutions), [address(Id)]).
oaa_AppDoEvent(read_bb(oaa_version,V), EvParams) :-
    1,
    memberchk(from(Id), EvParams),
    % Not sure if this works (but this clause is probably never called):
    findall(read bb(oaa version, V),
            ( com GetInfo(ConnectionId, oaa id( )),
            com_GetInfo(ConnectionId, agent_version(V)) ),
          Solutions),
    oaa_PostEvent(return read bb(Solutions), [address(Id)]).
oaa_AppDoEvent(read_bb(KS,oaa_version,V), EvParams) :-
    1.
    memberchk(from(Id), EvParams),
    findall(read_bb(KS, oaa_version, V),
            ( com GetInfo(ConnectionId, oaa id(KS)),
            com_GetInfo(ConnectionId, agent_version(V)) ),
          Solutions),
    oaa PostEvent(return read bb(Solutions), [address(Id)]).
oaa_AppDoEvent(read_bb(Item,Data), EvParams) :-
    !,
    memberchk(from(Id), EvParams),
    findall(read_bb(Item, Data),
          oaa:oaa_solve_local(data(Item, Data), []),
          Solutions),
    oaa PostEvent(return read bb(Solutions), [address(Id)]).
    % @@The owner parameter isn't implemented yet for solve!
oaa_AppDoEvent(read_bb(_KS, Item, Data), EvParams) :-
    1,
   memberchk(from(Id), EvParams),
    findall(read_bb(Item, Data),
          oaa:oaa_solve_local(data(Item, Data), []),
```

Solutions), oaa_PostEvent(return_read_bb(Solutions), [address(Id)]).

oaa_simplify_ksdata([], []).

. .

oaa_simplify_ksdata([KSData | Rest], [Simplified | RestSimp]) :-KSData = read_bb(ksdata, [A, B, Solvables, D]), icl_ConvertSolvables(SimplifiedSolvables, Solvables), Simplified = read_bb(ksdata, [A, B, SimplifiedSolvables, D]), oaa_simplify_ksdata(Rest, RestSimp).

| | | IN THE CLAIMS: |
|----------------|---------|---|
| | | 1. A computer-implemented method for communication and cooperative task |
| S. | a^{1} | completion among a plurality of distributed electronic agents, comprising the |
|)- | 3 | acts of: |
| | . 4 | registering a description of each active client agent's functional capabilities, using an |
| | 5 | expandable, platform-independent, inter-agent language; |
| | 6 | receiving a request for service as a base goal in the inter-agent language, in the form |
| | 7 | of an arbitrarily complex goal expression; and |
| | 8 | dynamically interpreting the goal expression, said act of interpreting further |
| | 9 | comprising: |
| | 10 | generating one or more sub-goals using the inter-agent language; and |
| | 11 | dispatching each of the sub-goals to a selected client agent for performance, |
| | 12 | based on a match between the sub-goal being dispatched and the |
| | 13 | registered functional capabilities of the selected client agent. |
| [][Jummin][][] | 1 | 2. A computer-implemented method as recited in claim 1, further including the |
| | 2 | following acts of: |
| 년 i [44 | 3 | receiving a new request for service as a base goal using the inter-agent language, in |
| ين س | 4 | the form of another arbitrarily complex goal expression, from at least one of |
| | 5 | the selected client agents in response to the sub-goal dispatched to said agent; |
| ļ | 6 | and |
| | 7 | recursively applying the last step of claim 1 in order to perform the new request for |
| | 8 | service. |
| ų, | 1 | 3. A computer implemented method as recited in claim 2 wherein the act |
| | 2 | of registering a specific agent further includes: |
| | 3 | invoking the specific agent in order to activate the specific agent; |
| 1 | 4 | instantiating an instance of the specific agent; and |
| 20] |) 5 | > transmitting the new agent profile from the specific agent to the facilitator |
| B) | 6 | agent in response to the instantiation of the specific agent. |
| | 1 | 4. A computer implemented method as recited in claim 1 further |
| | 2 | including the act of deactivating a specific client agent no longer available to provide |
| | 3 | services by deleting the registration of the specific client agent. |
| | 1 | 5. A computer implemented method as recited in claim 1 further |
| | 2 | comprising the act of providing an agent registry data structure. |
| | | / |
| | | |

A computer implemented method as recited in claim 5 wherein the
 agent registry data structure includes at least one symbolic name for each active agent.
 7. A computer implemented method as recited in claim 5 wherein the
 agent registry data structure includes at least one data declaration for each active
 agent.

8. A computer implemented method as recited in claim 5 wherein the
 agent registry data structure includes at least one trigger declaration for one active
 agent.

9. A computer implemented method as recited in claim 5 wherein the agent registry data structure includes at least one task declaration, and process characteristics for each active agent.

1 10. A computer implemented method as recited in claim 5 wherein the 2 agent registry data structure includes at least one process characteristic for each active 3 agent.

1 11. A computer implemented method as recited in claim 1 further 2 comprising the act of establishing communication between the plurality of distributed 3 agents.

1 12. A computer implemented method as recited in claim 1 further 2 comprising the acts of:

receiving a request for service in a second language differing from the interagent language;

selecting a registered agent capable of converting the second language into the
inter-agent language and

forwarding the request for service in a second language to the registered agent
capable of converting the second language into the inter-agent language, implicitly
requesting that such a conversion be performed and the results returned.

1 13. A computer implemented method as recited in claim 12 wherein the 2 request includes a natural language query, and the registered agent capable of 3 converting the second language into the inter-agent language service is a natural 4 language agent.

1 14. A computer implemented method as recited in claim 13 wherein the 2 natural language query was generated by a user interface agent.

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1 15. A compater implemented method as recited in charm 1, wherein the 2 base goal requires setting a trigger having conditional functionality and consequential 3 functionality.

1 16. A computer implemented method as recited in claim 15 wherein the 2 trigger is an outgoing communications trigger, the computer implemented method 3 further including the acts of:

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5

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monitoring all outgoing communication events in order to determine whether a specific outgoing communication event has occurred; and

in response to the occurrence of the specific outgoing communication event,
performing the particular action defined by the trigger.

1 17. A computer implemented method as recited in claim 15 wherein the 2 trigger is an incoming communications trigger, the computer implemented method 3 further including the acts of:

4 monitoring all incoming communication events in order to determine whether
5 a specific incoming communication event has occurred; and

6 in response to the occurrence of a specific incoming communication event 7 satisfying the trigger conditional functionality, performing the particular 8 consequential functionality defined by the trigger.

1 18. A computer implemented method as recited in claim 15 wherein the 2 trigger is a data trigger, the computer implemented method further including the acts 3 of:

monitoring a state ϕ f a data repository; and

in response to a particular state event satisfying the trigger conditional

functionality, performing the particular consequential functionality defined by the
trigger.

1 19. A computer implemented method as recited in claim 15 wherein the 2 trigger is a time trigger, the computer implemented method further including the acts 3 of:

monitoring for the occurrence of a particular time condition; and

5 in response to the occurrence of a particular time condition satisfying the 6 trigger conditional functionality, performing the particular consequential functionality 7 defined by the rigger.

1 20. A computer implemented method as recited in claim 15 wherein the 2 trigger is installed and executed within the facilitator agent.

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1 21. A computer implemented method as recited in claim 15 wherein the 2 trigger is installed and executed within a first service-providing agent.

1 22. A computer implemented method as recited in claim 15 wherein the 2 conditional functionality of the trigger is installed on a facilitator agent.

1 23. A computer implemented method as recited in claim 22 wherein the 2 consequential functionality is installed on a specific service-providing agent other 3 than a facilitator agent.

1 24. A computer implemented method as recited in claim 15 wherein the 2 conditional functionality of the trigger is installed on a specific service-providing 3 agent other than a facilitator agent.

1 25. A computer implemented method as recited in claim 15 wherein the 2 consequential functionality of the trigger is installed on a facilitator agent.

1 26. A computer implemented method as recited in claim 1 wherein the 2 base goal is a compound goal having sub-goals separated by operators.

1 27. A computer implemented method as recited in claim 26 wherein the 2 type of available operators includes a conjunction operator, a disjunction operator, 3 and a conditional execution operator.

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1 28. A computer implemented method as recited in claim 27 wherein the type 2 of available operators further includes a parallel disjunction operator that indicates that 3 disjunct goals are to be performed by different agents.

Attorney Docket No: SRI1P016(3477)/BRC/EWJ

Page 287 of 778

A computer program stored on a computer readable medium, the computer program executable to facilitate cooperative task completion within a distributed computing environment, the distributed computing environment including a plurality of autonomous electronic agents, the distributed computing environment supporting an Interagent Communication Language, the computer program comprising computer executable instructions for:

providing an agent registry that declares capabilities of service-providing
electronic agents currently active within the distributed computing environment;

9 interpreting a service request in order to determine a base goal that may be a 10 compound, arbitrarily complex base goal, the service request adhering to an 11 Interagent Communication Language (ICL), the act of interpreting including the sub-12 acts of:

13determining any task completion advice provided by the base goal, and14determining any task completion constraints provided by the base goal;

constructing a base goal satisfaction plan including the sub-acts of:

determining whether the requested service is available,

determining sub-goals required in completing the base goal,

selecting service-providing electronic agents from the agent registry
suitable for performing the determined sub-goals, and

20 ordering a delegation of sub-goal requests to best complete the 21 requested service; and

implementing the base goal satisfaction plan.

1 30. A computer program as recited in claim 29 wherein the computer 2 executable instruction for providing an agent registry includes the following computer 3 executable instructions for registering a specific service-providing electronic agent 4 into the agent registry:

establishing a bi-directional communications link between the specific agent
and a facilitator agent controlling the agent registry;

providing a new agent profile to the facilitator agent, the new agent profile
defining publicly available capabilities of the specific agent; and

9 registering the specific agent together with the new agent profile within the 10 agent registry, thereby making available to the facilitator agent the capabilities of the 11 specific agent.

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1 31. A computer program as recited in claim 30 wherein the computer 2 executable instruction for registering a specific agent further includes:

invoking the specific agent in order to activate the specific agent;

4 instantiating an instance of the specific agent; and

5 transmitting the new agent profile from the specific agent to the facilitator 6 agent in response to the instantiation of the specific agent.

1 32. A computer program as recited in claim 29 wherein the computer 2 executable instruction for providing an agent registry includes a computer executable 3 instruction for removing a specific service-providing electronic agent from the 4 registry upon determining that the specific agent is no longer available to provide 5 services.

1 33. A computer program as recited in claim 29 wherein the provided agent 2 registry includes a symbolic name, a unique address, data declarations, trigger 3 declarations, task declarations, and process characteristics for each active agent.

1 34. A computer program as recited in claim 29 further including computer 2 executable instructions for receiving the service request via a communications link 3 established with a client.

35. A computer program as recited in claim 29 wherein the computer executable instruction for providing a service request includes instructions for:

receiving a non-ICL format service request;

selecting an active agent capable of converting the non-ICL formal service
request into an ICL format service request;

6 forwarding the non-ICL format service request to the active agent capable of 7 converting the non-ICL format service request, together with a request that such 8 conversion be performed; and

9 receiving an ICL/format service request corresponding to the non-ICL format
10 service request.

1 36. A computer program as recited in claim 35 wherein the non-ICL 2 format service request includes a natural language query, and the active agent capable 3 of converting the non-ICL formal service request into an ICL format service request is 4 a natural language agent.

1 37. A computer program as recited in claim 36 wherein the natural 2 language query is generated by a user interface agent.

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requires setting a trigger having conditional and consequential functionality. 3 39. A computer program as fecited in claim 38 wherein the trigger is an 1 2 outgoing communications trigger, the/computer program further including computer 3 executable instructions for: monitoring all outgoing communication events in order to determine whether a 4 specific outgoing communication event has occurred; and 5 in response to the occurrence of the specific outgoing communication event, 6 performing the particular action/defined by the trigger. 7 40. A computer program as recited in claim 38 wherein the trigger is an 1 incoming communications trigger, the computer program further including computer 2 executable instructions for: 3 monitoring all incoming communication events in order to determine whether 4 a specific incoming communication event has occurred; and 5 in response to the occurrence of the specific incoming communication event, 6 performing the particular action defined by the trigger. 7 41. A computer/program as recited in claim 38 wherein the trigger is a data 1 trigger, the computer program further including computer executable instructions for: 2 monitoring a state of a data repository; and 3 4 in response to a particular state event, performing the particular action defined 5 by the trigger. 42. A computer program as recited in claim 38 wherein the trigger is a 1 time trigger, the computer program further including computer executable instructions 2 3 for: monitoring for the occurrence of a particular time condition; and 4 in response to the occurrence of the particular time condition, performing the 5 6 particular action defined by the trigger. A computer program as recited in claim 38 further including computer 43. 1 executable instructions for installing and executing the trigger within the facilitator 2 3 agent. 1 44 A computer program as recited in claim 38 further including computer executable instructions for installing and executing the trigger within a first service-2 providing agent. 3 Page 290 of trong / Docket No: SRI1P016(3477)/BRC/EWJ

A computer program as recited in claim 29, the computer program

further including computer executable instructions for implementing a base goal that

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Page 53 of 59

45. A computer program as recited in claim 29 further including computer
 executable instructions for interpreting compound goals having sub-goals separated
 by operators.

1 46. A computer program as recited in claim 45 wherein the type of 2 available operators includes a conjunction operator, a disjunction operator, and a 3 conditional execution operator.

1 47. A computer program as recited in claim 46 wherein the type of 2 available operators further includes a parallel disjunction operator that indicates that 3 disjunct goals are to be performed by different agents.

48. An Interagent Communication Language (ICL) providing a basis for facilitated cooperative task completion within a distributed computing environment having a facilitator agent and a plurality of autonomous service-providing electronic agents, the ICL enabling agents to perform queries of other agents, exchange information with other agents, set triggers within other agents, an ICL syntax supporting compound goal expressions such that goals within a single request provided according to the ICL syntax may be coupled by a conjunctive operator, a disjunctive operator, a conditional execution operator, and a parallel disjunctive operator parallel disjunctive operator that indicates that disjunct goals are to be performed by different agents.

49. An ICL as recited in claim 48, wherein the ICL is computer platform independent.

1 50. An ICL as recited in claim 48 wherein the ICL is independent of 2 computer programming languages which the plurality of agents are programmed in.

1 51. An ICL as recited in claim 48 wherein the ICL syntax supports explicit 2 task completion constraints within goal expressions.

1 52. An ICL as recited in claim 51 wherein possible types of task 2 completion constraints include use of specific agent constraints and response time 3 constraints.

1 53. An ICL as recited in claim 51 wherein the ICL syntax supports explicit 2 task completion advisory suggestions within goal expressions.

54. An ICL as recited in claim 48 wherein the ICL syntax supports explicit
 task completion advisory suggestions within goal expressions.

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1 55. An ICE as recited in claim 48 wherein each autonomous service-2 providing electronic agent defines and publishes a set of capability declarations or 3 solvables, expressed in ICL, that describes services provided by such electronic agent.

56. An ICL as recited in claim \$5 wherein an electronic agent's solvables
 define an interface for the electronic agent.

1 57. An ICL as recited in claim 56 wherein the facilitator agent maintains 2 an agent registry making available a plurality of electronic agent interfaces.

1 58. An ICL as recited in claim 57 wherein the possible types of solvables 2 includes procedure solvables, a procedure solvable operable to implement a procedure 3 such as a test or an action.

1 59. An ICL as recited in claim 58 wherein the possible types of solvables 2 further includes data solvables, a data solvable operable to provide access to a 3 collection of data.

1 60. An ICL as recited in claim 58 wherein the possible types of solvables 2 includes data solvables, a data solvable operable to provide access to a collection of 3 data.

A facilitator agent arranged to coordinate cooperative task completion within a distributed computing environment having a plurality of autonomous serviceproviding electronic agents, the facilitator agent comprising:

an agent registry/that declares capabilities of service-providing electronic agents currently active within the distributed computing environment; and

a facilitating engine operable to parse a service request in order to interpret a
compound goal set forth therein, the compound goal including both local and global
constraints and control parameters, the service request formed according to an
Interagent Communication Language (ICL), the facilitating engine further operable to
construct a goal satisfaction plan specifying the coordination of a suitable delegation
of sub-goal requests to complete the requested service satisfying both the local and
global constraints and control parameters.

1 62. A facilitator agent as recited in claim 61, wherein the facilitating 2 engine is capable of modifying the goal satisfaction plan during execution, the 3 modifying initiated by events such as new agent declarations within the agent registry, 4 decisions made by remote agents, and information provided to the facilitating engine 5 by remote agents. 1 63. A factmator agent as recited in claim 61 wherein the agent registry 2 includes a symbolic name, a unique address, data declarations, trigger declarations, 3 task declarations, and process characteristics for each active agent.

1 64. A facilitator agent as recited in claim 61 wherein the facilitating engine 2 is operable to install a trigger mechanism requesting that a certain action be taken 3 when a certain set of conditions are met.

1 65. A facilitator agent as recited in claim 64 wherein the trigger 2 mechanism is a communication trigger that monitors communication events and 3 performs the certain action when a certain communication event occurs.

1 66. A facilitator agent as recited in claim 64 wherein the trigger 2 mechanism is a data trigger that monitors a state of a data repository and performs the 3 certain action when a certain data state is obtained.

67. A facilitator agent as recited in claim 66 wherein the data repository is
 local to the facilitator agent.

1 68. A facilitator agent as recited in claim 66 wherein the data repository is 2 remote from the facilitator agent

1 69. A facilitator agent as recited in claim 64 wherein the trigger 2 mechanism is a task trigger having a set of conditions.

1 70. A facilitator agent as recited in claim 61, the facilitator agent further 2 including a global database accessible to at least one of the service-providing 3 electronic agents.

1 *W*. A software-based, flexible computer architecture for communication 2 and cooperation among distributed electronic agents, the architecture contemplating a 3 distributed computing system comprising:

4 a plurality of service/providing electronic agents; and

5 a facilitator agent in bi-directional communications with the plurality of 6 service-providing electronic agents, the facilitator agent including:

an agent registry that declares capabilities of service-providing
electronic agents currently active within the distributed computing
environment;

10a facilitating engine operable to parse a service request in order11to interpret an arbitrarily complex goal set forth therein, the facilitating12engine further operable to construct a goal satisfaction plan including

the coordination of a suitable delegation of sub-goal requests to best complete the requested service.

A computer architecture as recited in claim 71, wherein the basis for 72. ł the computer architect is an Interagent Communication Language (ICL) enabling 2 agents to perform queries of other agents, exchange information with other agents, 3 4 and set triggers within other agents, the ICL further defined by an ICL syntax supporting compound goal expressions such that goals within a single request 5 provided according to the ICL syntax may be coupled by a conjunctive operator, a 6 disjunctive operator, a conditional execution operator, and a parallel disjunctive 7 8 operator parallel disjunctive operator that indicates that disjunct goals are to be performed by different agents. 9

1 73. A computer architecture as recited in claim 72, wherein the ICL is 2 computer platform independent.

1 74. A computer architecture as recited in claim 73 wherein the ICL is 2 independent of computer programming languages in which the plurality of agents are 3 programmed.

75. A computer architecture as recited in claim 73 wherein the ICL syntax
 supports explicit task completion constraints within goal expressions.

76. A computer architecture as recited in claim 75 wherein possible types
 of task completion constraints include use of specific agent constraints and response
 time constraints.

77. A computer architecture as recited in claim 75 wherein the ICL syntax
 supports explicit task completion advisory suggestions within goal expressions.

78. A computer architecture as recited in claim 73 wherein the ICL syntax
 supports explicit task completion advisory suggestions within goal expressions.

1 79. A computer architecture as recited in claim 73 wherein each 2 autonomous service-providing electronic agent defines and publishes a set of 3 capability declarations or solvables, expressed in ICL, that describes services 4 provided by such electronic agent.

1 80. A computer architecture as recited in claim 79 wherein an electronic 2 agent's solvables define an interface for the electronic agent.

1 81. A computer architecture as recited in claim 80 wherein the possible 2 types of solvables includes procedure solvables, a procedure solvable operable to 3 implement a procedure such as a test or an action.

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1 82. A computer architecture as recited in claim 81 wherein the possible 2 types of solvables further includes data solvables, a data solvable operable to provide 3 access to a collection of data.

- 83. A computer architecture as recited in claim 82 wherein the possible types of solvables includes a data solvable operable to provide access to modify a collection of data.
 - 84. A computer architecture as recited in claim 71 wherein the planning component of the facilitating engine are distributed across at least two computer processes.

85. A computer architecture as recited in claim 71 wherein the execution component of the facilitating engine is distributed across at least two computer processes.

86. A data wave carrier providing a transport mechanism for information communication in a distributed computing environment having at least one facilitator agent and at least one active client agent, the data wave carrier comprising a signal representation of an inter-agent language description of an active client agent's functional capabilities.

87. A data wave carrier as recited in claim 85, the data wave carrier further comprising a signal representation of a request for service in the inter-agent language from a first agent to a second agent.

88. A data wave carrier as recited in claim 85, the data wave carrier further
 comprising a signal representation of a goal dispatched to an agent for performance
 from a facilitator agent.

A data wave carrier as recited in claim 88 wherein a later state of the data wave carrier comprises a signal representation of a response to the dispatched goal including results and/or a status report from the agent for performance to the facilitator agent.

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Page 295 of 778 Docket No: SRI1P016(3477)/BRC/EWJ

Software-Based Architecture for Communication and Cooperation Among Distributed Electronic Agents

ABSTRACT

5 A highly flexible, software-based architecture is disclosed for constructing distributed systems. The architecture supports cooperative task completion by flexible, dynamic configurations of autonomous electronic agents. Communication and cooperation between agents are brokered by one or more facilitators, which are responsible for matching requests, from users and agents, with descriptions of the 10 capabilities of other agents. It is not generally required that a user or agent know the identities, locations, or number of other agents involved in satisfying a request, and relatively minimal effort is involved in incorporating new agents and "wrapping" legacy applications. Extreme flexibility is achieved through an architecture organized around the declaration of capabilities by service-providing agents, the construction of

- 15 arbitrarily complex goals by users and service-requesting agents, and the role of facilitators in delegating and coordinating the satisfaction of these goals, subject to advice and constraints that may accompany them. Additional mechanisms and features include facilities for creating and maintaining shared repositories of data; the use of triggers to instantiate commitments within and between agents; agent-based
- 20 provision of multi-modal user interfaces, including natural language; and built-in support for including the user as a privileged member of the agent community. Specialized embodiments providing enhanced scalability are also described.

TION AND POWER OF AT FOR ORIGINAL U.S. PATENT APPLICATION

> Attorney's Docket No. SRI1P016

As a below-named inventor, I hereby declare that:

My residence, post office address and citizenship are as stated below next to my name.

I believe that I am the original, first and sole inventor (if only one name is listed below) or an original, first and joint inventor (if plural names are listed below) of the subject matter which is claimed and for which a patent is sought on the invention entitled: SOFTWARE-BASED ARCHITECTURE FOR COMMUNICATION AND COOPERATION AMONG DISTRIBUTED ELECTRONIC AGENTS, the specification of which is attached hereto.

I hereby state that I have reviewed and understand the contents of the above-identified specification, including the claims, as amended by any amendment referred to above.

And I hereby appoint the law firm of Hickman & Marting, including Paul L. Hickman (Reg. No. 28, 516); L. Keith Stephens (Reg. No. 32,632); Brian R. Coleman (Reg. No. 39,145); Dawn L. Palmer (Reg. No. 41,238); Jerray Wei (Reg. No. 43,247); and Ian L. Cartier (Reg. No. 38,406) as my principal attorneys to prosecute this application and to transact all business in the Patent and Trademark Office connected therewith:

Send Correspondence To:

Brian R. Coleman **HICKMAN STEPHENS & COLEMAN, LLP** P.O. BOX 52037 Palo Alto, California 94303-0746

Direct Telephone Calls To:

Brian R. Coleman at telephone number (650) 470-7430

I hereby declare that all statements made herein of my own knowledge are true and that all statements made on information and belief are believed to be true; and further that these statements were made with the knowledge that willful false statements and the like so made are punishable by fine or imprisonment, or both, under section 1001 of Title 18 of the United States Code, and that such willful false statements may jeopardize the validity of the application or any patent issuing thereon.

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| | PATENT APPLICATION FEE DETERMINATION RECORD Application or Docket Number Effective November 10, 1998 09/225/198 | | | | | | | | | | | |
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PATENT APPLICATION SERIAL NO.

U.S. DEPARTMENT OF COMMERCE PATENT AND TRADEMARK OFFICE FEE RECORD SHEET

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01 FC:101 760.00 CH 02 FC:102 234.00 CH 03 FC:103 1242.00 CH

> PTO-1556 (5/87) Page 299 of 778

ARTIFACT SHEET

Enter artifact number below. Artifact number is application number + artifact type code (see list below) + sequential letter (A, B, C ...). The first artifact folder for an artifact type receives the letter A, the second B, etc.. Examples: 59123456PA, 59123456PB, 59123456ZA, 59123456ZB 092251999Pt

Indicate quantity of a single type of artifact received but not scanned. Create individual artifact folder/box and artifact number for each Artifact Type.

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| CD(s) containing: |
| Stapled Set(s) Color Documents or B/W Photographs Doc Code: Artifact Artifact Type Code: C |
| Microfilm(s) Doc Code: Artifact Artifact Type Code: F |
| Video tape(s) Doc Code: Artifact Artifact Type Code: V |
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March 8, 2004

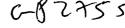
ARTIFACT SHEET

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| | CD(s) containing: |
| | Stapled Set(s) Color Documents or B/W Photographs Doc Code: Artifact Artifact Type Code: C |
| | Microfilm(s) Doc Code: Artifact Artifact Type Code: F |
| | Video tape(s) Doc Code: Artifact Artifact Type Code: V |
| | Model(s) Doc Code: Artifact Artifact Type Code: M |
| | Bound Document(s) Doc Code: Artifact Artifact Type Code: B |
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| | Other, description: Doc Code: Artifact Artifact Type Code: Z |

March 8, 2004



PATENT

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

In re the application of:

Cheyer et al.

Application No.: 09/225,198

Filed: January 5, 1999

For: SOFTWARE-BASED ARCHITECTURE FOR COMMUNICATION AND COOPERATION AMONG DISTRIBUTED ELECTRONIC AGENTS Group: 2755

Examiner: Unassigned

Atty. Docket No.: SRI1P016

Date: May 11, 1999 RECEIVED

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Group 2700

CERTIFICATE OF MAILING

I hereby certify that this correspondence is being deposited with the United States Postal Service as First Class Mail in an envelope addressed to: Assistant Commissioner for Patents, Washington, DC 20231 on May 11, 1999

Signed: Vasudevan

INFORMATION DISCLOSURE STATEMENT UNDER 37 CFR §§1.56 AND 1.97(c)

Assistant Commissioner for Patents Washington, DC 20231

Dear Sir:

The references listed in the attached PTO Form 1449, copies of which are attached, may be material to examination of the above-identified patent application. Applicants submit these references in compliance with their duty of disclosure pursuant to 37 CFR §§1.56 and 1.97. The Examiner is requested to make these references of official record in this application.

Reference No. R on Page 4 of PTO form 1449 contains documents downloaded from a web site owned by Dejima, Inc. at http://www.dejima.com on April 29, 1999 and March 18, 1999. The applicant makes no representation that this web site has not changed between the dates of downloading or that this web site will not change in the future.

This Information Disclosure Statement is not to be construed as a representation that a search has been made, that additional information material to the examination of this application does not exist, or that these references indeed constitute prior art.

Attny Dkt No. SRI1P016

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This Information Disclosure Statement is believed to be filed before the mailing date of a first Office Action on the merits. Accordingly, it is believed that no fees are due in connection with the filing of this Information Disclosure Statement. However, if it is determined that any fees are due, the Commissioner is hereby authorized to charge such fees to Deposit Account 50-0384 (Order No.<u>SRI1P016</u>).

Respectfully submitted, HICKMAN STEPHENS & COLEMAN, LLP

Brian R. Coleman Reg. No. 39,145

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| | | | UNITED STATES DEPARTM United States Patent and T Address: COMMISSIONER OF P. Washington, D.C. 20231 www.uspto.gov | rademark Office ATENTS AND TRADEMARI |
|--------------------------------|----------------------------------|----------------------|---|---|
| APPLICATION NO. | FILING DATE | FIRST NAMED INVENTOR | ATTORNEY DOCKET NO. | CONFIRMATION NO. |
| 09/225,198 | 01/05/1999 | ADAM J. CHEYER | SRI1P016 | 2756 |
| 25696 75 OPPENHEIM | 90 07/17/2002 ER WOLFF & DONI | NELLY | EXAM | NFR |
| P. O. BOX 1035 PALO ALTO, C | | | BULLOCK JR, LEV | |
| | | | ART UNIT | PAPER NUMBER |
| | | | 2151 | |
| | | | DATE MAILED: 07/17/2002 | |

Please find below and/or attached an Office communication concerning this application or proceeding.

PTO-90C (Rev. 07-01)

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| | Application No. | Applicant(s) | | | | |
| | 09/225,198 | CHEYER ET AL. | | | | |
| Office Action Summary | Examiner | Art Unit | | | | |
| | Lewis A. Bullock, Jr. | 2151 | | | | |
| The MAILING DATE of this communication Period for Reply | n appears on the cover sheet wi | th the correspondence address | | | | |
| A SHORTENED STATUTORY PERIOD FOR R THE MAILING DATE OF THIS COMMUNICATION - Extensions of time may be available under the provisions of 37 Cl after SIX (6) MONTHS from the mailing date of this communication - If the period for reply specified above is less than thirty (30) days, - If NO period for reply is specified above, the maximum statutory p - Failure to reply within the set or extended period for reply will, by s - Any reply received by the Office later than three months after the the earned patent term adjustment. See 37 CFR 1.704(b). Status | ON. FR 1.136(a). In no event, however, may a ro- nn. a reply within the statutory minimum of thirt eriod will apply and will expire SIX (6) MON statute, cause the application to become AB | epty be timely filed y (30) days will be considered timely. THS from the mailing date of this communication. ANDONED (35 U.S.C. § 133). | | | | |
| 1) Responsive to communication(s) filed on | · | | | | | |
| 2a) This action is FINAL . 2b)⊠ | This action is non-final. | | | | | |
| 3) Since this application is in condition for a closed in accordance with the practice un | | | | | | |
| Disposition of Claims | | | | | | |
| 4) Claim(s) <u>1-89</u> is/are pending in the applic | | | | | | |
| 4a) Of the above claim(s) is/are with | ndrawn from consideration. | | | | | |
| 5) Claim(s) is/are allowed. | | | | | | |
| 6)⊠ Claim(s) <u>1-89</u> is/are rejected. | | | | | | |
| 7) Claim(s) is/are objected to. | | | | | | |
| 8) Claim(s) are subject to restriction a Application Papers | nd/or election requirement. | | | | | |
| 9) The specification is objected to by the Exar | niner. | | | | | |
| 10) The drawing(s) filed on is/are: a) | accepted or b) objected to by th | ne Examiner. | | | | |
| Applicant may not request that any objection | to the drawing(s) be held in abeya | nce. See 37 CFR 1.85(a). | | | | |
| 11) The proposed drawing correction filed on _ | is: a) approved b) di | sapproved by the Examiner. | | | | |
| If approved, corrected drawings are required | in reply to this Office action. | | | | | |
| 12) The oath or declaration is objected to by the | e Examiner. | | | | | |
| Priority under 35 U.S.C. §§ 119 and 120 | | | | | | |
| 13) Acknowledgment is made of a claim for for | reign priority under 35 U.S.C. § | 119(a)-(d) or (f). | | | | |
| a) All b) Some * c) None of: | | | | | | |
| 1. Certified copies of the priority docum | nents have been received. | | | | | |
| 2. Certified copies of the priority docum | nents have been received in Ap | oplication No | | | | |
| 3. Copies of the certified copies of the priority documents have been received in this National Stage application from the International Bureau (PCT Rule 17.2(a)). * See the attached detailed Office action for a list of the certified copies not received. | | | | | | |
| 14) Acknowledgment is made of a claim for dom | | | | | | |
| a) The translation of the foreign language provisional application has been received. 15) Acknowledgment is made of a claim for domestic priority under 35 U.S.C. §§ 120 and/or 121, | | | | | | |
| Attachment(s) | | | | | | |
| Notice of References Cited (PTO-892) Notice of Draftsperson's Patent Drawing Review (PTO-948 Information Disclosure Statement(s) (PTO-1449) Paper No |) 5) 🚺 Notice of In | ummary (PTO-413) Paper No(s) formal Patent Application (PTO-152) | | | | |
| I.S. Patent and Trademark Office PTO-326 (Rev_04-01) Page 305 01 778 Office | ce Action Summary | Part of Paper No. 3 | | | | |

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Page 2

. Application/Control Number: 09/225,198 Art Unit: 2151

DETAILED ACTION

Claim Rejections - 35 USC § 112

 Claim 2 is rejected under 35 U.S.C. 112, second paragraph, as being indefinite for failing to particularly point out and distinctly claim the subject matter which applicant regards as the invention. Applicant claims the recursively applying the last step of claim 1, however the Examiner cannot determine which step applicant is referring to.
 Applicant is either referring to the dynamically interpreting step and its substep or the dispatching step of the dynamically interpreting step. Clarification is requested.

2. Claim 3 recites the limitation "from the specific agent to the facilitator agent" in lines 5-6. There is insufficient antecedent basis for this limitation in the claim. There is no mention of the facilitator agent anywhere in the parent claims. In review of the specification the examiner finds the facilitator agent performs the steps of claim 1, however, claim 1 does not detail the facilitator agent as performing the steps. The examiner request Applicant to amend claim 1 to detail that the facilitator agent performs the facilitator agent performs the facilitator agent performs the facilitator agent performs the steps.

3. Claims 84 and 85 are rejected under 35 U.S.C. 112, second paragraph, as being indefinite for failing to particularly point out and distinctly claim the subject matter which applicant regards as the invention. Claims 84 and 85 recite the planning and execution components, however neither component has antecedent basis in the parent claim 71. Correction is requested.

4. Claims 87 and 88 recite the limitation "A data wave carrier as recited in claim 85" in line 1. There is insufficient antecedent basis for this limitation in the claim. Claims 87 and 88 should be dependent on claim 86 not claim 85 and are further examined as such.

Claim Rejections - 35 USC § 102

5. The following is a quotation of the appropriate paragraphs of 35 U.S.C. 102 that form the basis for the rejections under this section made in this Office action:

A person shall be entitled to a patent unless -

(a) the invention was known or used by others in this country, or patented or described in a printed publication in this or a foreign country, before the invention thereof by the applicant for a patent.

(b) the invention was patented or described in a printed publication in this or a foreign country or in public use or on sale in this country, more than one year prior to the date of application for patent in the United States.

6. Claims 1, 2, 5-11, 15-28, 48-89 are rejected under 35 U.S.C. 102(a) as being

anticipated by "Building Distributed Software Systems with the Open Agent

Architecture" by MARTIN.

As to claim 1, MARTIN teaches a computer-implemented method for

communication and cooperative task completion among a plurality of distributed agents

(application agent / meta agent / user interface agent), comprising the acts of:

registering a description of each client agent's functional capabilities (capabilities

specifications), using a platform independent inter-agent language (ICL); receiving a

request for service as a base goal (goals created by requesters of service) in the inter-

agent language, in the form of an arbitrarily complex goal expression; and dynamically

interpreting the goal expression (goals) (via facilitator) comprising: generating one or

more sub-goals using the inter-agent language; and dispatching each of the sub-goals to a selected client agent (service providers) for performance, based on a match between the sub-goal being dispatched and the registered functional capabilities of the selected client agent (pg. 7, Mechanisms of Cooperation; pg. 12-14, Requesting Services; Refining Service Requests, and Facilitation).

As to claim 2, MARTIN teaches receiving a new request (subgoal) for service as a base goal from at least one of the selected client agents in response to the sub-goal and recursively applying the dynamically interpreting (pg. 13, Refining Service Requests).

As to claims 5-10, MARTIN teaches providing an agent registry data structure that can comprise of symbolic names, data declarations, trigger declarations, and task and process characteristics (pg. 13-14, Facilitation; pg. 7, "In processing a request...it can use ICL to request services of other agents, set triggers, and read or write shared data on the facilitator...").

As to claim 11, MARTIN teaches establishing communication between distributed agents (pg. 6, The facilitator is a specialized server agent that is responsible for coordinating agent communications and cooperative problem-solving.").

As to claims 15-25, MARTIN teaches the base goal requires setting a trigger having conditional functionality and consequential functionality which can be stored on the facilitator agent and/or the service providing agent (pgs. 16-17, Autonomous Monitoring Using Triggers).

As to claims 26-28, MARTIN teaches the base goal is a compound goal having sub-goals separated by operators, i.e. conjuction operator, disjunction operator, conditional operator, and a parallel operator (pg. 12-13, Compound goals).

As to claim 48, MARTIN teaches an Inter-agent Communication Language (ICL) providing a basis for facilitated cooperative task completion within a distributed computing environment having a facilitator agent (facilitator) and a plurality of electronic agents (service providing agents / service requesting agents), the ICL enabling agents to perform queries of other agents, exchange information with other agents, set triggers within other agents (pgs. 4-7, Overview of OAA System Structure, Mechanisms of Cooperation; pg. 8, "OAA agents employ ICL to perform queries, execute actions, exchange information, set triggers, and manipulate data in the agent community."), an ICL syntax supporting compound goal expressions such that goals within a single request provided according to the ICL syntax may be coupled by a conjunctive operator, a disjunctive operator, a conditional execution operator, and a parallel operator that indicates that goals are to be performed by different agents (pg. 12, Compound goals).

As to claim 49 and 50, MARTIN teaches the ICL is platform and language independent (pg. 8, "OAA's Inter-agent Communication Language (ICL) is the interface, communication, and task coordination language shared by all agents, regardless of what platform they run on or what computer language they are programmed in.").

As to claims 51-54, MARTIN teaches the ICL supports task completion constraints within goal expressions (pg. 9, "A number of important declarations...we consider each of these elements.").

As to claims 55-60, MARTIN teaches each electronic agent defines and publishes a set of capability declarations or solvables that describe services and an interface to the electronic agent (pg. 9, "A number of important declarations...we consider each of these elements.").

As to claims 61 and 62, reference is made to an agent that performs the method of claim 1 above and is therefore met by the rejection of claim 1 above. However, claim 61 further details an agent register and the construction of a goal satisfaction plan. MARTIN teaches an agent register (knowledge base) (pg. 13-14, Facilitation); and the construction of a goal satisfaction plan (pg. 13, "When a facilitator receives a compound goal, its job is to construct a goal satisfaction plan and oversee its satisfaction in the most appropriate, efficient manner that is consistent with the specified advice.").

As to claim 63, refer to claim 5 for rejection.

As to claim 64-69, refer to claims 15-25 for rejection.

As to claim 70, MARTIN teaches the agent registry (knowledge base) is a database accessible to all electronic agents (via the facilitator) (pg. 13-14, Facilitation).

As to claim 71, reference is made to an architecture that encompasses the agent of claim 61 above, and is therefore met by the rejection of claim 61 above. However claim 71, further details the facilitator agent in bi-directional communication with the electronic agents. MARTIN teaches the facilitator agent in bi-directional communication with the electronic agents (fig 1).

As to claim 72, refer to claim 48 for rejection.

As to claims 73 and 74, refer to claims 49 and 50 for rejection.

As to claims 75-78, refer to claims 51-54 for rejection.

As to claims 79-83, refer to claims 54-60 for rejection.

Page 7

As to claims 84 and 85, MARTIN teaches the facilitating engine is distributed across at least two processes (pg. 6, "Larger systems can be assembled from multiple facilitator/client groups...").

As to claim 86, MARTIN teaches a data wave carrier (system) providing a transport mechanism (layer of conversational protocol / communication functions) for information communication in a distributed computing environment having at least one facilitator agent (facilitator) and at least one client agent (application agent / user interface agent), the carrier comprising a signal representation of an inter-agent language description of a client agent's functional capabilities (registering by the service provider agents) (pg. 6-9).

As to claim 87, MARTIN teaches a signal representation of a request for service in the inter-agent language from a first agent to a second agent (request for service from an service requesting agent to the facilitator) (pg. 12, Requesting Services).

As to claim 88, MARTIN teaches a signal representation of a goal dispatched to an agent for performance from a facilitator agent (pg. 13-14, Facilitation).

As to claim 89, MARTIN teaches a signal representation of a response to the dispatched goal including results and/or a status report from the agent for performance to the facilitator agent (pg. 13-14, Facilitation).

Page 312 of 778

7. Claims 1, 2, 5-11, and 15-25 are rejected under 35 U.S.C. 102(b) as being anticipated by "Development Tools for the Open Agent Architecture" by MARTIN.

As to claim 1, MARTIN teaches a computer-implemented method for communication and cooperative task completion among a plurality of distributed agents (sub-agents / agents), comprising the acts of: registering a description of each client agent's functional capabilities, using a platform independent inter-agent language (pg. 5, Each facilator records the published capabilities of their subagents..."); receiving a request as a base goal in the inter-agent language (ICL form), in the form of an arbitrarily complex goal expression; and dynamically interpreting the goal expression comprising: generating one or more sub-goals using the inter-agent language; and dispatching each of the sub-goals to a selected client agent for performance ("pg. 5, "...and when requests arrive (expressed in the Inter-agent Communication Language, described below), the facilitator is responsible for breaking them down and for distributing sub-requests to the appropriate agents; "For example, every agent can...and request solutions for a set of goals,...").

As to claim 2, MARTIN teaches receiving a new request for service as a base goal from at least one of the selected client agents in response to the sub-goal and recursively applying the dynamically interpreting (pg. 5, "An agent satisfying a request may require supporting information, and the OAA provides numerous means of requesting data from other agents or from the user.").

As to claims 5-10, MARTIN teaches providing an agent registry data structure that can comprise of symbolic names, data declarations, trigger declarations, and task and process characteristics (pg. 5, "For example, every agent can install local or remote triggers on data..").

As to claim 11, MARTIN teaches establishing communication between distributed agents (pg. 5, ...the facilitator is responsible for breaking them down and for distributing sub-requests to the appropriate agent.").

As to claims 15-25, MARTIN teaches the base goal requires setting a trigger having conditional functionality and consequential functionality which can be stored on the facilitator agent and/or the service providing agent (pg. 5, "For example, every agent can install local or remote triggers on data..").

Claim Rejections - 35 USC § 103

8. The following is a quotation of 35 U.S.C. 103(a) which forms the basis for all obviousness rejections set forth in this Office action:

(a) A patent may not be obtained though the invention is not identically disclosed or described as set forth in section 102 of this title, if the differences between the subject matter sought to be patented and the prior art are such that the subject matter as a whole would have been obvious at the time the invention was made to a person having ordinary skill in the art to which said subject matter pertains. Patentability shall not be negatived by the manner in which the invention was made.

9. Claims 3, 29-34, and 38-47 are rejected under 35 U.S.C. 103(a) as being unpatentable over "Building Distributed Software Systems with the Open Agent Architecture" by MARTIN.

As to claim 3, MARTIN teaches the act of registering and transmitting the new agent profile from the specific agent to the facilitator agent (pg. 7, "When invoked, a client agent makes a connection to a facilitator...an agent informs its parent facilitator of the services it is capable of providing."). It would be obvious that an agent that is initially created is instantiated in memory before it is registered.

As to claim 29, MARTIN teaches a method to facilitate cooperative task completion within a distributed computing environment supporting an Inter-agent Communication Language among a plurality of electronic agents (fig 1) comprising: providing an agent registry (knowledge base) as disclosed (pg. 13-14, Facilitation); interpreting a service request in order to determine a base goal (compound goal) comprising: determining any task completion advice provided by the base goal, and determining any task completion constraints provided by the base goal (pg. 14, "It may also use strategies or advice specified by the requester.."); constructing a base goal satisfaction plan (pg. 13, "When a facilitator receives a compound goal, its job is to construct a goal satisfaction plan and oversee its satisfaction in the most appropriate, efficient manner that is consistent with the specified advice.") comprising: determining whether the requested service is available, determining sub-goals required in completing the base goal (delegation), selecting suitable service-providing electronic

agents for performing the sub-goals, and ordering a delegation of sub-goal requests to complete the requested service; and implementing the base goal satisfaction plan (pg. 13-14, Facilitation). However, MARTIN does not explicitly mention that the method is operable in a computer program product. It would be obvious to one skilled in the art to generate program code that would entail the method of Martin and thereby obvious that the method can be entailed in a computer program product.

As to claims 30 and 31, MARTIN teaches registering a specific agent (service provider agents) into the agent registry comprising: establishing a bi-directional communications link between the specific agent and a facilitator agent (facilitator) controlling the agent registry; providing a new agent profile to the facilitator agent; and registering the specific agent with the profile thereby making the capabilities available to the facilitator agent (pgs. 9-10, Providing Services; pg. 7, Mechanisms of Cooperation).

As to claim 32, refer to claim 3 for rejection.

As to claim 33, refer to claim 5 for rejection.

As to claim 34, refer to claim 11 for rejection.

As to claims 38-44, refer to claims 15-25 for rejection.

Page 12

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As to claims 45-47, refer to claims 26-28 for rejection.

10. Claims 4, 12-14 and 35-37 is rejected under 35 U.S.C. 103(a) as being unpatentable over "Building Distributed Software Systems with the Open Agent Architecture" by MARTIN1 in view of "Information Brokering in an Agent Architecture" by MARTIN2.

As to claim 4, MARTIN1 substantially discloses the invention above. However, MARTIN1 does not explicitly mention the cited limitation. MARTIN2 teaches deactivating a client agent no longer available to provide services by deleting the registration (pg. 9, Source agents that need to go offline...so that it can unregister the source and retract its schema mapping rules."). Therefore it would be obvious to combine the teachings of MARTIN1 with the teachings of MARTIN2 in order to provide transparent access to a plurality of independent agents (abstract).

As to claims 12-14, MARTIN1 substantially discloses the invention above. However, MARTIN1 does not explicitly mention the cited limitation. MARTIN2 teaches receiving a request for service in a second language (source shema); selecting a registered agent capable of converting the second language into the inter-agent language (broker schema); and forwarding the request for service in a second language to the registered agent for conversion to be performed and the results returned (pg. 12-13, Queries Expressed in a Source Schema). Refer to claim 4 for the motivation to combine.

As to claims 35-37, refer to claims 12-14 for rejection.

11. Claims 3, 29-34, 38-47, 61-71, and 84-89 are rejected under 35 U.S.C. 103(a) as being unpatentable over "Developing Tools for the Open Agent Architecture" by MARTIN.

As to claim 3, MARTIN teaches the act of registering and transmitting the new agent profile from the specific agent to the facilitator agent (pg. 5, "Every agent participating in an OAA-based system defines and publishes a set of capabilities specifications, expressed in the ICL, describing the services that it provides."). It would be obvious that an agent that is initially created is instantiated in memory before it is registered.

As to claim 29, MARTIN teaches a method to facilitate cooperative task completion within a distributed computing environment supporting an Inter-agent Communication Language among a plurality of electronic agents (sub-agents / agents) comprising: providing an agent registry as disclosed (facilitator storage of published sub-agents capabilities); interpreting a service request in order to determine a base goal (via facilitator) constructing a base goal satisfaction plan comprising: determining whether the requested service is available, determining sub-goals required in completing the base goal (determine solutions for a set of goals) selecting suitable service-providing electronic agents for performing the sub-goals, and ordering a

delegation of sub-goal requests to complete the requested service; and implementing the base goal satisfaction plan (pg. 5, "The facilitator is responsible for breaking them down and for distributing sub-requests to the appropriate agents."). However, MARTIN does not explicitly mention that the method is operable in a computer program product or the sending of advice or constraints. It would be obvious that since an agent can request solutions for a goal to be satisfied under a variety of different control strategies (pg. 5) that the control strategies are the advice and/or constraints. It would also be obvious to one skilled in the art to generate program code that would entail the method of Martin and thereby obvious that the method can be entailed in a computer program product.

As to claims 30 and 31, MARTIN teaches registering a specific agent (agent) into the agent registry (list of agents capabilities) comprising: establishing a bi-directional communications link between the specific agent and a facilitator agent controlling the agent registry; providing a new agent profile to the facilitator agent; and registering the specific agent with the profile thereby making the capabilities available to the facilitator agent (pg. 5, "Each facilitator records the published capabilities of their subagents..."; "Every agent participating in an OAA-based system...describing the services that it provides.").

As to claim 32, refer to claim 3 for rejection.

As to claim 34, refer to claim 11 for rejection.

As to claims 38-44, refer to claims 15-25 for rejection.

As to claims 45-47, refer to claims 26-28 for rejection.

As to claim 61 and 62, reference is made to an agent that performs the method of claim 1 above and is therefore met by the rejection of claim 1 above. However, claim 61 further details an agent register and the construction of a goal satisfaction plan. MARTIN teaches every agent participating in an OAA-based system defines and publishes a set of capabilities describing the services that it provides and that the facilitator records these published capabilities (pg. 5). Therefore, there is an agent register of the capabilities of each agent. MARTIN also teaches an agent can request solutions for a set of goals to be satisfied under a variety of different control strategies. It would be obvious that since solutions are determined based on the goals and control strategies that a goal satisfaction plan is created.

As to claim 63, refer to claim 5 for rejection.

As to claim 64-69, refer to claims 15-25 for rejection.

As to claim 70, MARTIN teaches the agent registry (agent library / list of agent capabilities) is a database accessible to all electronic agents (pg. 5, A collection of agents satisfies requests from users, or other agents...one or more facilitators."; "An agent satisfying a request may require supporting information...requesting data from other agents or from the user.").

As to claim 71, reference is made to an architecture that encompasses the agent of claim 61 above, and is therefore met by the rejection of claim 61 above. However claim 71, further details the facilitator agent in bi-directional communication with the electronic agents. MARTIN teaches the facilitator can distribute request to the agents and the agents can request information via the facilitator (pg. 5), therefore it would be obvious that the facilitator and agents are in bi-directional communication.

As to claims 84 and 85, MARTIN teaches the facilitating engine is distributed across at least two processes (pg. 5, "Facilitators can, in turn, be connected as clients of other facilitators.").

As to claim 86, MARTIN teaches system for information communication in a distributed computing environment having at least one facilitator agent (facilitator) and at least one client agent (sub-agent / agents), the carrier comprising a signal representation of an inter-agent language description (ICL registration of capabilities) of

a client agent's functional capabilities (pg. 5, "Each facilitator records the published capabilities of their subagents.."). It would be obvious that the system has a data wave carrier and a transport mechanism for network communication.

As to claim 87, MARTIN teaches a signal representation of a request for service in the inter-agent language from a first agent (client agent sending a query) to a second agent (facilitator) (pg. 5).

As to claim 88, MARTIN teaches a signal representation of a goal dispatched to an agent for performance from a facilitator agent (every agent can request solutions for a set of goals / facilitator is responsible for breaking them down and for distributing subrequests to the appropriate agent) (pg. 5).

As to claim 89, It is well known in the art to one skilled in the art that an agent can send back a response after processing the request.

12. Claims 4, 12-14, 26-28, 35-37, 48-60, 72-83 are rejected under 35 U.S.C. 103(a) as being unpatentable over "Development Tools for the Open Agent Architecture" by MARTIN1 in view of "Information Brokering in an Agent Architecture" by MARTIN2.

As to claim 4, MARTIN1 substantially discloses the invention above. However, MARTIN1 does not explicitly mention the cited limitation. MARTIN2 teaches deactivating a client agent no longer available to provide services by deleting the

registration (pg. 9, Source agents that need to go offline...so that it can unregister the source and retract its schema mapping rules."). Therefore it would be obvious to combine the teachings of MARTIN1 with the teachings of MARTIN2 in order to provide transparent access to a plurality of independent agents (abstract).

As to claims 12-14, MARTIN1 substantially discloses the invention above. However, MARTIN1 does not explicitly mention the cited limitation. MARTIN2 teaches receiving a request for service in a second language (source schema); selecting a registered agent capable of converting the second language into the inter-agent language (broker schema); and forwarding the request for service in a second language to the registered agent for conversion to be performed and the results returned (pg. 12-13, Queries Expressed in a Source Schema). Refer to claim 4 for the motivation to combine.

As to claims 26-28, MARTIN1 substantially discloses the invention above. However, MARTIN1 does not explicitly mention the cited limitation. MARTIN2 teaches the base goal is a compound goal having sub-goals (pg. 8, "Queries submitted to the Broker are expression...and backtracking in expressing and processing queries."). It would be obvious that since the base goal (query) is broken down and distributed to as sub-requests to the appropriate agents or solutions are requested for a set of goals as disclosed in MARTIN1 that the base goal as a compound goal is broken down based on

operators disclosing where it can be broken down. Refer to claim 4 for the motivation to combine.

As to claims 35-37, refer to claims 12-14 for rejection.

As to claim 48, MARTIN1 teaches an Inter-agent Communication Language (ICL) providing a basis for facilitated cooperative task completion within a distributed computing environment having a facilitator agent (facilitator) and a plurality of electronic agents (sub-agents / agents), the ICL enabling agents to perform queries of other agents, exchange information with other agents, set triggers within other agents (pg. 5, Agents share a common communication language...and may run on any network linked platform."). However, MARTIN1 does not teach the ICL supporting compound goal expressions. MARTIN2 teaches the query is a base goal stored in as a compound goal having sub-goals (pg. 8, "Queries submitted to the Broker are expression...and backtracking in expressing and processing queries."). It would be obvious that since the base goal (query) is broken down and distributed to as sub-requests to the appropriate agents or solutions are requested for a set of goals as disclosed in MARTIN1 that the base goal as a compound goal is broken down based on operators disclosing where it can be broken down. Refer to claim 4 for the motivation to combine.

Application/Control Number: 09/225,198
 Art Unit: 2151

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As to claim 49 and 50, MARTIN1 teaches the ICL is platform and language independent (pg. 5, "The OAA's Inter-agent Communication Language...they are programmed in.").

As to claims 51-54, MARTIN1 teaches the ICL supports task completion constraints (triggers) within goal expressions (pg. 5).

As to claims 54-60, MARTIN1 teaches each electronic agent defines and publishes a set of capability declarations or solvables that describe services and an interface to the electronic agent (pg. 5, "Every agent participating in an OAA-based system defines and publishes...we refer to these capabilities specifications as solvables.").

As to claim 72, refer to claim 48 for rejection.

As to claims 73 and 74, refer to claims 49 and 50 for rejection.

As to claims 75-78, refer to claims 51-54 for rejection.

As to claims 79-83, refer to claims 54-60 for rejection.

Application/Control Number: 09/225,198
 Art Unit: 2151

Conclusion

Any inquiry concerning this communication or earlier communications from the examiner should be directed to Lewis A. Bullock, Jr. whose telephone number is (703) 305-0439. The examiner can normally be reached on Monday-Friday, 8:30 am - 5:00 pm.

If attempts to reach the examiner by telephone are unsuccessful, the examiner's supervisor, Alvin E. Oberley can be reached on (703) 305-9716. The fax phone numbers for the organization where this application or proceeding is assigned are (703) 746-7239 for regular communications and (703) 746-7238 for After Final communications.

Any inquiry of a general nature or relating to the status of this application or proceeding should be directed to the receptionist whose telephone number is (703) 305-0286.

ST. JOHN COURTENAY II PRIMARY EXAMINER

July 11, 2002

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Applicant(s)/Patent Under Reexamination CHEYER ET AL. Art Unit 2151

Page 1 of 1

| Lewis A. | Bullock, | Jr. |
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A copy of this reference is not being furnished with this Office action. (See MPEP § 707.05(a).) Dates in MM-YYYY format are publication dates. Classifications may be US or foreign.

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| Form 1449 (Modified) | Atty Docket No. | Serial No.: |
| MALSOM | SRI1P016 | 09/225,198 |
| Information Disclosure | Applicant: | |
| Statement By Applicant | Cheyer et al. | |
| | Filing Date: | Group |
| (Use Several Sheets if Necessary) | January 5. 1999 | 2755 |

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Foreign Patent or Published Foreign Patent Application

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| Form 1449 (Modified) | Atty Docket No. | Serial No.: |
| & TRADEMANS | SRI1P016 | 09/225,198 |
| Information Disclosure | Applicant: | |
| Statement By Applicant | Cheyer et al. | |
| | Filing Date: | Group |
| (Use Several Sheets if Necessary) | January 5. 1999 | 2755 |

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| Form 1449 (Modified & TRADEMARY | Atty Docket No. SRI1P016 | Serial No.: 09/225,198 |
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| Information Disclosure Statement By Applicant | Applicant: Cheyer et al. | 07/225,170 |
| (Use Several Sheets if Necessary) | Filing Date: January 5. 1999 | Group 2755 |

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| Information Disclosure | Applicant: | |
| Statement By Applicant | Cheyer et al. | |
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| (Use Several Sheets if Necessary) | January 5. 1999 | 2755 |

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Examiner: Initial citation considered. Draw line through citation if not in conformance and not considered. Include copy of this form with next communication to applicant.

| | - | Attorney | Docket No. 5950 | 2755 4 11-8016.US01 |
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| | I hereby certify that this correspondence is being deposit First Class Mail in an envelope addressed to: Assistant C | ommissioner for Patent | | |
| () | Date: <u>August 6, 2002</u> | By: <u>ANNUL</u> | amie L. Hughes | |
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| | FOR: SOFTWARE-BASED ARCHITECTURE FOR | | RECE | IVED |
| | COMMUNICATION AND COOPERATION AMONG DISTRIBUTED ELECTRONIC | k Ni | AUG 1 | 5 2002 |
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Information Disclosure Statement After First Office Action but Before Final Action or Notice of Allowance – 37 CFR 1.97(c)

Assistant Commissioner for Patents Washington, D.C. 20231

Sir:

1. <u>Timing of Submission</u>

The information transmitted herewith is being filed *after* three months of the filing date of this application or after the mailing date of the first Office action on the merits, whichever occurred last, but *before* the mailing date of either a final action under 37 CFR 1.113 or a Notice of Allowance under 37 CFR 1.311, whichever occurs first. The references listed on the enclosed Form PTO/SB/08A may be material to the examination of this application; the Examiner is requested to make them of record in the application.

08/14/2002 CNEUYEN 00000007 502207 09225198 01 FC:126 160.00 CH

2. <u>Cited Information</u>

- Copies of the following references are enclosed:
 - All cited references

3. Effect of Information Disclosure Statement (37 CFR 1.97(h))

This Information Disclosure Statement is not to be construed as a representation that: (i) a search has been made; (ii) additional information material to the examination of this application does not exist; (iii) the information, protocols, results and the like reported by third parties are accurate or enabling; or (iv) the cited information is, or is considered to be, material to patentability. In addition, applicant does not admit that any enclosed item of information constitutes prior art to the subject invention and specifically reserves the right to demonstrate that any such reference is not prior art.

4. Fee Payment (37 CFR 1.97(c)) or Certification (37 CFR 1.97(e))

- Applicant elects to pay the fee under 37 CFR 1.17(p) \$180.00.
 - □ Check enclosed for \$
 - Please charge the above fee(s) to Deposit Account No. 50-2207 this paper is provided in triplicate.

Respectfully submitted, Perkins Coie LLP

Date: 6 Aug

Brian R. Coleman Registration No. 39,145

Correspondence Address:

Customer No. 22918 Perkins Coie LLP P.O. Box 2168 Menlo Park, California 94026 (650) 838-4300 AUG 13 ZUTZ - CIDA

Cited Information

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Copies of the following references are enclosed:

All cited references

Effect of Information Disclosure Statement (37 CFR 1.97(h))

This Information Disclosure Statement is not to be construed as a representation that: (i) a search has been made; (ii) additional information material to the examination of this application does not exist; (iii) the information, protocols, results and the like reported by third parties are accurate or enabling; or (iv) the cited information is, or is considered to be, material to patentability. In addition, applicant does not admit that any enclosed item of information constitutes prior art to the subject invention and specifically reserves the right to demonstrate that any such reference is not prior art.

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- Please charge the above fee(s) to Deposit Account No. 50-2207 this paper is provided in triplicate.

Respectfully submitted, Perkins Coie LLP

Attorney Docket No. 595078016.U

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Brian R. Coleman Registration No. 39,145

Date: 6 Aug 2002

Correspondence Address:

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INTERNATIONAL APPLICATION PUBLISHED UNDER THE PATENT COOPERATION TREATY (PCT)

| (51) | International Patent Classification: H04N 7/16 | A1 | | ational Publication Number: ational Publication Date: | WO 00/11869 02 March 2000 (02.03.2000) |
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| (21) | International Application Number: | PCT/ | US99/19051 | | |
| (22) | International Filing Date: 20 August | 1999 | (20.08.1999) | Published | ι. |
| (30) | Priority Data: 60/097,538 21 August 1998 (21.08 not furnished 30 July 1999 (30.07) | | • | | |
| (60) | Parent Application or Grant UNITED VIDEO PROPERTIES, INC. [/]; Michael, D. [/]; (). LEMMONS, Thomas, R William, L. [/]; (). TREYZ, G., Victor; (). | | | | |

(54) Title: CLIENT-SERVER ELECTRONIC PROGRAM GUIDE(54) Titre: GUIDE DE PROGRAMMES ELECTRONIQUE CLIENT-SERVEUR

(57) Abstract

A client-server interactive television program guide system is provided. An interactive television program guide client is implemented on user television equipment. The interactive television program guide provides users with an opportunity to define expressions that are processed by the program guide server. The program guide server may provide program guide data, schedules reminders, schedules program recordings, and parentally locks programs based on the expressions. Users' viewing histories may be tracked. The program guide server may analyze the viewing histories and generates viewing recommendations, targets advertising, and collects program ratings information based on the viewing histories.

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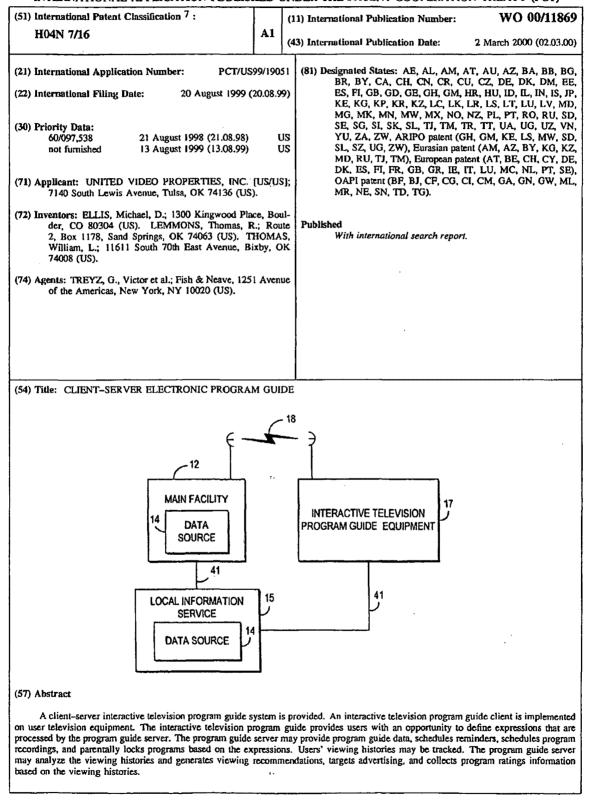
L'invention concerne un système de guide de programmes de télévision interactif entre un client et un serveur. Un client de guide de programmes de télévision interactif est mis en application sur l'installation télévisuelle d'un utilisateur. Ce guide de programmes permet aux utilisateurs de définir des expressions traitées par le serveur de guide de programmes. Ce serveur peut produire des données de guide de programmes, des rappels de programmation, des enregistrements de programmes et, de même, verrouille des programmes en fonction des expressions. Il est possible de rechercher l'historique de visualisation des utilisateurs. Le serveur de guide de programmes peut analyser les historiques de visualisation et générer des recommandations de visualisation, des publicités ciblées et recueillir des informations d'évaluation de programmes en fonction de ces historiques de visualisation.

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CLIENT-SERVER ELECTRONIC PROGRAM GUIDE

| 25 | | Background of the Invention |
|----|----|---|
| | | This invention relates to interactive |
| | | television program guide systems, and more |
| 30 | | particularly, to interactive television program guide |
| | 5 | systems based on client-server arrangements. |
| | | Cable, satellite, and broadcast television |
| | | systems provide viewers with a large number of |
| 35 | | television channels. Users have traditionally |
| | | consulted printed television program schedules to |
| | 10 | determine the programs being broadcast at a particular |
| | | time. More recently, interactive television program |
| 40 | | guides have been developed that allow television |
| | | program information to be displayed on a user's |
| | | television. Interactive television program guides, |
| | 15 | which are typically implemented on set-top boxes, allow |
| 45 | | users to navigate through television program listings |
| | | using a remote control. In a typical program guide, |
| | | various groups of television program listings are |
| | | displayed in predefined or user-selected categories. |
| 50 | 20 | Program listings are typically displayed in a grid or |
| | | |
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5 - 2 table. On-line program guides have been proposed that require users to navigate the Internet to access 10 program listings. Client-server based program guides have been 5 proposed in which program listings are stored on a 15 server at a cable system headend. The server provides the program listings to program guide clients implemented on the set-top boxes of a number of users associated with each headend. As users navigate within 20 10 a program listings grid, the server provides program listings to the client for display. Such systems, may be limited in their functionality due to their limited use of the resources of the server. 25 It is therefore an object of the present 15 invention to provide an interactive televison program quide system in which server resources are used to provide enhanced program guide features not provided by 30 conventional set-top-box-based or client-server-based program guides. 20 Summary of the Invention 35 This and other objects of the present invention are accomplished in accordance with the principles of the present invention by providing a client-server based interactive television program 40 25 guide system in which a main facility (e.g., a satellite uplink facility or a facility that feeds such an uplink facility) provides data from one or more data 45 sources to a number of television distribution facilities such as cable system headends, broadcast 30 distribution facilities, satellite television distribution facilities, or other suitable distribution 50 facilities. Some of the data sources may be located at 55

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different facilities and have their data provided to

5 television distribution facilities includes television

programming data (e.g., titles, channels, content information, rating information, program identifiers, series identifiers, or any other information associated with television programming), and other program guide

facilities directly. The data provided to the

10 data for additional services other than television

20 program guide server. If desired, program guide

distribution facilities or other distribution facilities. Each program guide server stores the

30 servers may also store user data, such as user

25 program guide data provided by the main facility and provides access to the program guide data to program guide clients implemented on the user television equipment of a number of users associated with each

television distribution facility. The program guide

preference profiles, parental control settings, record and reminder settings, viewing history, and other

servers may also be located at cable system network nodes or other facilities separate from the television

suitable communications link.

suitable data.

program listings (e.g., weather information, associated Internet web links, computer software, etc.). The main facility (and other sources) may provide the program

guide data to the television distribution facilities
15 via a satellite link, a telephone network link, a cable
or fiber optic link, a microwave link, an Internet
link, a combination of such links, or any other

Each television distribution facility has a

the main facility for localization and distribution or may provide their data to the television distribution

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Providing program guide data with a program 10 guide server and storing user data on the server may provide users with opportunities to perform various functions that may enhance the users' television 5 viewing experience. Users may, for example, set user 15 preference profiles or other favorites that are stored by the program guide server and used by the server to customize the program guide viewing experience for the user. The program guide server may filter program 10 guide data based on the user preference profiles. Only data that is of interest to the user may then be provided to the guide client, thereby tending to minimize the memory requirements of the user's television equipment and lessen the bandwidth 15 requirements of the local distribution network. A client-server based architecture may also provide users with the ability to search and sort through program related information in ways that might not otherwise be possible due to the limited processing 20 and storage capabilities of the users' television equipment. If desired, users may be provided with access to program guide data without requiring them to navigate the Internet. Users may, for example, define sophisticated boolean or natural language expressions 25 having one or more criteria for searching through and sorting program guide data, scheduling reminders, automatically recording programs and parentally controlling programs. The criteria may also be derived by the program guide server or program guide client 30 from user profiles or by monitoring usage of the program guide. The criteria may be stored on the program guide server. Users may be provided with an

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| 10 | | opportunity to access, modify, or delete the expressions. |
| | | The program guide server may also track the |
| | | users' viewing histories to provide a user-customized |
| 15 | 5 | program guide experience. Programs or series of |
| | | episodes users have watched may be identified and used |
| | | by the program guide, for example, to inform users when |
| | | there are showings in the series that the users have |
| 20 | | not watched. The program guide may, for example, |
| | 10 | provide viewing recommendations based on a user's |
| | | viewing history and, if appropriate, on user preference |
| | · - | profiles or other criteria stored by the program guide |
| 25 | | server. The program guide may also target |
| | | advertisements toward users based on the viewing |
| | 15 | |
| 20 | | programs to generate viewership ratings. |
| 30 | | Further features of the invention, its nature |
| | | and various advantages will be more apparent from the |
| | 20 | accompanying drawings and the following detailed |
| 35 | 20 | description of the preferred embodiments. |
| | | Brief Description of the Drawings |
| | | FIG. 1 is a schematic block diagram of an |
| | | illustrative system in accordance with the present |
| 40 | | invention. |
| | 25 | FIGS. 2a, 2b, and 2c show illustrative |
| | 20 | arrangements for the interactive program guide |
| | | equipment of FIG. 1 in accordance with the principles |
| 45 | | of the present invention. |
| | | FIG. 3 is an illustrative schematic block |
| | 30 | |
| 50 | , | 2b in accordance with the principles of the present |
| 50 | | invention. |
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| | | |
| 10 | | FIG. 4 is a generalized schematic block |
| 10 | | diagram of portions of the illustrative user television |
| | | equipment of FIG. 3 in accordance with the principles |
| | | of the present invention. |
| 15 | 5 | FIG. 5 is an illustrative main menu screen in |
| 15 | | accordance with the principles of the present |
| | | invention. |
| | | FIG. 6 is an illustrative program listings by |
| 20 | | time screen in accordance with the principles of the |
| | 10 | present invention. |
| | • | FIG. 7 is an illustrative program listings by |
| | | channel screen in accordance with the principles of the |
| 25 | | present invention. |
| | | FIGS. 8a-8c are illustrative program listings |
| | 15 | by category screens in accordance with the principles |
| | | of the present invention. |
| 30 | | FIG. 9a is an illustrative boolean type |
| | | criteria screen in accordance with the principles of |
| | | the present invention. |
| | 20 | FIG. 9b is an illustrative natural language |
| 35 | | criteria screen in accordance with the principles of |
| | | the present invention. |
| | | FIG. 10 shows an illustrative agents screen |
| | | in accordance with the principles of the present |
| 40 | 25 | invention. |
| | | FIG. 11 is an illustrative program listings |
| | | screen in which program listings found according to the |
| | | illustrative expressions of FIGS. 9a and 9b are |
| 45 | | displayed in accordance with the principles of the |
| | 30 | present invention. |
| 50 | | FIG. 12 shows an illustrative setup screen in |
| | | accordance with the principles of the present |
| | | invention. |
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- 7 -FIGS. 13a-13f show illustrative preference 10 profile screens in accordance with the principles of the present invention. FIG. 14 shows an illustrative profile 5 activation screen in accordance with the principles of 15 the present invention. FIG. 15 shows a table containing an illustrative list of programs that might be available to a user after defining the preference profiles of 20 10 FIGS. 13a-13f in accordance with the principles of the present invention. FIGS. 16a-16c are illustrative program listings screens that may be displayed according to the 25 preference profiles of FIGS. 13a-13f in accordance with 15 the principles of the present invention. FIGS. 17a and 17b show illustrative criteria 30 screens in accordance with the principles of the present invention. FIGS. 18 and 19 show illustrative program 20 reminder lists generated according to the expressions 35 of FIGS. 17a and 17b in accordance with the principles of the present invention. FIGS. 20a and 20b show an illustrative viewer recommendation overlay, in accordance with the 40 25 principles of the present invention. FIG. 20c shows an illustrative additional information screen in accordance with the principles of the present invention. 45 FIG. 21 is a flowchart of illustrative steps 30 involved in providing users with an opportunity to define preference profiles and access program guide data according to the preference profiles in accordance 50 with the principles of the present invention. 55

- 8 -FIG. 22 is a flowchart of illustrative steps 10 involved in providing users with an opportunity to search program guide data, other information, and videos in accordance with the principles of the present 5 invention. 15 FIG. 23 is a flowchart of illustrative steps involved in processing and using expressions in accordance with the principles of the present invention. 20 10 FIG. 24 is a flowchart of illustrative steps involved in tracking and using viewing histories in accordance with the principles of the present invention. 25 Detailed Description of the Preferred Embodiments 15 An illustrative system 10 in accordance with 30 the present invention is shown in FIG. 1. Main facility 12 may provide program guide data from data source 14 to interactive television program guide equipment 17 via communications link 18. There may be · 35 20 multiple program guide data sources in main facility 12 but only one has been shown to avoid over-complicating the drawing. If desired, program guide data sources may be located at facilities separate from main ΔN facility 12 such as at local information services 15, 25 and may have their data provided to main facility 12 for localization and distribution. Data sources 14 may be any suitable computer or computer-based system for 45 obtaining data (e.g., manually from an operator, electronically via a computer network or other 30 connection, or via storage media) and placing the data into electronic form for distribution by main facility 50 12. Link 18 may be a satellite link, a telephone

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network link, a cable or fiber optic link, a microwave link, an Internet link, a combination of such links, or any other suitable communications link. Video signals may also be transmitted over link 18 if desired.

- 9 -

Local information service 15 may be any suitable facility for obtaining data particular to a localized region and providing the data to main facility 12 or interactive television program guide equipment 17 over communications links 41. Local

10 information service 15 may be, for example, a local weather station that measures weather data, a local newspaper that obtains local high school and college sporting information, or any other suitable provider of information. Local information service 15 may be a

15 local business with a computer for providing main facility 12 with, for example, local ski reports, fishing conditions, menus, etc., or any other suitable provider of information. Link 41 may be a satellite link, a telephone network link, a cable or fiber optic

20 link, a microwave link, an Internet link, a combination of such links, or any other suitable communications link. Additional data sources 14 may be located at other facilities for providing main facility 12 with non-localized data (e.g., non-localized program guide 25 data) over link 41.

The program guide data transmitted by main facility 12 to interactive television program guide equipment 17 may include television programming data (e.g., program identifiers, times, channels, titles, 30 descriptions, series identifiers, etc.) and other data for services other than television program listings (e.g., help text, pay-per-view information, weather information, sports information, music channel

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- 10 information, associated Internet web links, associated 10 software, etc.). There are preferably numerous pieces or installations of interactive television program quide equipment 17, although only one is shown in 5 FIG. 1 to avoid over-complicating the drawing. 15 Program guide data may be transmitted by main facility 12 to interactive television program guide equipment 17 using any suitable approach. Data files may, for example, be encapsulated as objects and 20 10 transmitted using a suitable Internet based addressing scheme and protocol stack (e.g., a stack which uses the user datagram protocol (UDP) and Internet protocol (IP)). Systems in which program guide data is 25 transmitted from a main facility to television 15 distribution facilities are described, for example, in Gollahon et al. U.S. patent application Serial No. 09/332,624, filed June 11, 1999 (Attorney Docket No. 30 UV-106), which is hereby incorporated by reference herein in its entirety. 20 A client-server based interactive television program guide is implemented on interactive television 35 program guide equipment 17. Three illustrative arrangements for interactive television program guide equipment 17 are shown in FIGS. 2a-2c. FIG. 2a shows 40 25 an illustrative arrangement for interactive television program guide equipment 17 in which a program guide server obtains program guide data directly from main facility 12. FIG. 2b shows an illustrative arrangement 45 for interactive television program guide equipment 17 30 in which a program guide server obtains program guide data from main facility 12 or some other facility (e.g., local information service 15) via the Internet. 50 In either of these approaches, users may be provided

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PCT/US99/19051

- 11 -

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with opportunities to access program guide data without having to navigate the Internet, if desired. As shown in FIGS. 2a and 2b, interactive program guide television equipment 17 may include television 5 distribution facility 16 and user television

equipment 22.

facility.

Television distribution facility 16 may have program guide distribution equipment 21 and program guide server 25. Distribution equipment 21 is 10 equipment suitable for providing program guide data

from program guide server 25 to user television equipment 22 over communications path 20. Distribution equipment 21 may include, for example, suitable transmission hardware for distributing program guide

15 data on a television channel sideband, in the vertical blanking interval of a television channel, using an inband digital signal, using an out-of-band digital signal, over a dedicated computer network or Internet link, or by any other data transmission technique

20 suitable for the type of communications path 20. Analog or digital video signals (e.g., television programs) may also be distributed by distribution equipment 21 to user television equipment 22 over communications paths 20 on multiple analog or digital

25 television channels. Alternatively, videos may be distributed to user television equipment 22 from some other suitable distribution facility, such as a cable system headend, a broadcast distribution facility, a satellite television distribution facility, or any 30 other suitable type of television distribution

Communications paths 20 may be any communications paths suitable for distributing program

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PCT/US99/19051

- 12 -

guide data. Communications paths 20 may include, for

cable or fiber optic link, a microwave link, an Internet link, a data-over-cable service interface 5 specification (DOCSIS) link, a combination of such

links, or any other suitable communications link. Communications paths 20 preferably have sufficient bandwidth to allow television distribution facility 16

or another distribution facility to distribute

15 FIGS. 2a and 2b to avoid over-complicating the

communications paths.

10 television programming to user television equipment 22. There are typically multiple pieces of user television equipment 22 and multiple associated communications paths 20, although only one piece of user television

equipment 22 and communications path 20 are shown in

Program guide server 25 may be based on any

drawings. If desired, television programming and program guide data may be provided over separate

20 suitable combination of server software and hardware.

25 on user television equipment 22. As shown in FIGS. 2a and 2b, program guide server 25 may include processing

circuitry 54 may include any suitable processor, such

as a microprocessor or group of microprocessors, and 30 other processing circuitry such as caching circuitry, video decoding circuitry, direct memory access (DMA)

circuitry 54 and storage device 56. Processing

circuitry, input/output (I/O) circuitry, etc.

Program guide server 25 may retrieve program guide data or video files from storage device 56 in response to program guide data or video requests generated by an interactive television program guide client implemented

example, a satellite link, a telephone network link, a

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PCT/US99/19051

- 13 -

Storage device 56 may be a memory or other 10 storage device, such as random access memory (RAM), flash memory, a hard disk drive, etc., that is suitable for storing the program guide data transmitted to 5 television distribution facility 16 by main facility 15 12. User data, such as user preference profiles, preferences, parental control settings, record and reminder settings, viewing histories, and other suitable data may also be stored on storage device 56 20 10 by program guide server 25. Program guide data and user data may be stored on storage device 56 in any suitable format (e.g., a Structured Query Language (SQL) database). If desired, storage 56 may also store 25 video files for playing back on demand. 15 Processing circuitry 54 may process requests for program guide data by searching the program guide data stored on storage device 56 for the requested 30 data, retrieving the data, and providing the retrieved data to distribution equipment 21 for distribution to 20 user television equipment 22. Processing circuitry 54 35 may also process storage requests generated by the program guide client that direct program guide server 25 to store user data. Alternatively, program guide server 25 may distribute program guide data to 40 25 and receive user data from user television equipment 22 directly. If communications paths 20 include an Internet link, DOCSIS link, or other high speed computer network link (e.g., 10BaseT, 100BaseT, 45 10BaseF, T1, T3, etc.), for example, processing 30 circuitry 54 may include circuitry suitable for transmitting program guide and user data and receiving program guide data and storage requests over such a 50 link.

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Program guide server 25 may communicate with user television equipment 22 using any suitable 10 communications protocol. For example, program guide server 25 may use a communications protocol stack that 5 includes transmission control protocol (TCP) and 15 Internet protocol (IP) layers, sequenced packet exchange (SPX) and internetwork packet exchange (IPX) layers, Appletalk transaction protocol (ATP) and datagram delivery protocol (DDP) layers, DOCSIS, or any 20 10 other suitable protocol or combination of protocols. User television equipment 22 may also include suitable hardware for communicating with program guide server 25 over communications paths 20 (e.g., Ethernet cards, 25 modems (digital, analog, or cable), etc.) 15 The program guide client on user television equipment 22 may retrieve program guide data from and store user data on program guide server 25 using any 30 suitable client-server based approach. The program guide may, for example, pass SQL requests as messages 20 to program guide server 25. In another suitable approach, the program guide may invoke remote 35 procedures that reside on program guide server 25 using one or more remote procedure calls. Program guide server 25 may execute SQL statements for such invoked 25 remote procedures. In still another suitable approach, 40 client objects executed by the program guide may communicate with server objects executed by program guide server 25 using, for example, an object request broker (ORB). This may involve using, for example, 45 30 Microsoft's Distributed Component Object Model (DCOM) approach. As used herein, "record requests" and "storage requests" are intended to encompass any of 50 these types of inter-process or inter-object

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| 10 | communications, or any other suitable type of inter- process or inter-object communication. FIG. 2b shows an illustrative arrangement for |
| | interactive television program guide equipment 17 in 5 which program guide server 25 obtains program guide |
| 15 | data via the Internet. The program guide data obtained by program guide server 25 may be provided by main facility 12 or from some other source (e.g., local information service 15) and made available on the |
| 20 | 10 Internet. Internet service system 61 may use any suitable combination of hardware and software capable of providing program guide data from the Internet to |
| 25 | program guide server 25 using an Internet based approach (e.g., using the HyperText Transfer Protocol 15 (HTTP), File Transfer Protocol (FTP), etc.). FIG. 2b |
| 30 | shows Internet service system 61 as being encompassed by television distribution facility 16. If desired, Internet service system 61 may be located at a facility that is separate from television distribution |
| 35 | 20 facility 16. Internet service system 61 may, for example, be located at main facility 12 or at some other Internet node suitable for providing program guide data from the Internet to program guide server |
| 40 | 25. The functionality of Internet service system 61 25 and program guide server 25 may be integrated into one system if desired. |
| 45 | Another suitable arrangement for interactive television program guide equipment 17 is shown in FIG. 2c. Interactive television program guide equipment 17 30 may include, for example, television distribution |
| 50 | facility 16 having program guide server 25 and Internet service system 61. A program guide client application may run on personal computer 23. The client may access |
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PCT/US99/19051

5 - 16 program guide server 25 via Internet service system 61 and communications path 20. Personal computer 23 may 10 include processing circuitry 27, memory 29, storage device 31, communications device 35, and monitor 39. Processing circuitry 27 may include any 5 suitable processor, such as a microprocessor or group 15 of microprocessors, and other processing circuitry such as caching circuitry, direct memory access (DMA) circuitry, input/output (I/O) circuitry, etc. 20 10 Processing circuitry 27 may also include suitable circuitry for displaying television programming. Personal computer 23 may include, for example, a PC/TV card. Memory 29 may be any suitable memory, such as 25 random access memory (RAM) or read only memory (ROM), 15 that is suitable for storing the computer instructions and data. Storage device 31 may be any suitable storage device, such as a hard disk, floppy disk drive, 30 flash RAM card, recordable CD-ROM drive, or any other suitable storage device. Communications device 35 may 20 be any suitable communications device, such as a conventional analog modem or cable modem. 35 An illustrative arrangement for user television equipment 22 of FIGS. 2a and 2b is shown in FIG. 3. User television equipment 22 of FIG. 3 25 receives analog video or a digital video stream and 40 data, program guide data, or any suitable combination thereof, from television distribution facility 16 (FIG. 1) at input 26. During normal television viewing, a user tunes set-top box 28 to a desired television 45 30 channel. The signal for that television channel is then provided at video output 30. The signal supplied at output 30 is typically either a radio-frequency (RF) signal on a predefined channel (e.g., channel 3 or 4), 50 55

PCT/US99/19051

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or a analog demodulated video signal, but may also be a digital signal provided to television 36 on an appropriate digital bus (e.g., a bus using the Institute of Electrical and Electronics Engineers

5 (IEEE) 1394 standard, (not shown)). The video signal at output 30 is received by optional secondary storage device 32.

The interactive television program guide client may run on set-top box 28, on television 36 (if 10 television 36 has suitable processing circuitry and memory), on a suitable analog or digital receiver connected to television 36, or on digital storage device 31 if digital storage device 31 has suitable processing circuitry and memory. The interactive

15 television program guide client may also run cooperatively on a suitable combination of these devices. Interactive television application systems in which a cooperative interactive television program guide application runs on multiple devices are

20 described, for example, in Ellis U.S. patent application Serial No. 09/186,598, filed November 5, 1998, which is hereby incorporated by reference herein in its entirety.

Secondary storage device 32 can be any
25 suitable type of analog or digital program storage device or player (e.g., a videocassette recorder, a digital versatile disc (DVD) player, etc.). Program recording and other features may be controlled by set-top box 28 using control path 34. If secondary
30 storage device 32 is a videocassette recorder, for example, a typical control path 34 involves the use of an infrared transmitter coupled to the infrared receiver in the videocassette recorder that normally

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PCT/US99/19051

5 - 18 accepts commands from a remote control such as remote control 40. Remote control 40 may be used to control 10 set-top box 28, secondary storage device 32, and television 36. 5 If desired, a user may record programs, 15 program quide data, or a combination thereof in digital form on optional digital storage device 31. Digital storage device 31 may be a writeable optical storage device (such as a DVD player capable of handling 20 10 recordable DVD discs), a magnetic storage device (such as a disk drive or digital tape), or any other digital storage device. Interactive television program guide systems that have digital storage devices are 25 described, for example, in Hassell et al. U.S. patent 15 application Serial No. 09/157,256, filed September 17, 1998, which is hereby incorporated by reference herein in its entirety. 30 Digital storage device 31 can be contained in set-top box 28 or it can be an external device 20 connected to set-top box 28 via an output port and appropriate interface. Digital storage device 31 may, 35 for example, be contained in local media server 29. If necessary, processing circuitry in set-top box 28 formats the received video, audio and data signals into 25 a digital file format. Preferably, the file format is 40 an open file format such as the Moving Picture Experts Group (MPEG) MPEG-2 standard or the Moving Joint Photographic Experts Group (MJPEG) standard. The 45 resulting data is streamed to digital storage device 31 30 via an appropriate bus (e.g., a bus using the Institute Electrical and Electronics Engineers (IEEE) 1394 standard), and is stored on digital storage device 31. 50 In another suitable approach, an MPEG-2 data stream or

| series of files may be received from distri 10 equipment 21 and stored. | ibution |
|--|--------------|
| Television 36 receives video sign | hals from |
| secondary storage device 32 via communicati | - |
| 5 The video signals on communications path 38 | - |
| 15 be generated by secondary storage device 32 | |
| playing back a prerecorded storage medium (| - |
| videocassette or a recordable digital video digital storage device 31 when playing back | - |
| 20 10 recorded digital medium, may be passed thro | - |
| set-top box 28, may be provided directly to | |
| 36 from set-top box 28 if secondary storage | |
| is not included in user television equipmen | |
| 25 be received directly by television 36. Dur | - |
| 15 television viewing, the video signals provi | - |
| television 36 correspond to the desired cha | |
| which a user has tuned with set-top box 28. | Video |
| 30 signals may also be provided to television | 36 by set- |
| top box 28 when set-top box 28 is used to p | lay back |
| 20 information stored on digital storage devic | e 31. |
| 35 Set-top box 28 may have communica | tions |
| device 37 for communicating with program gu | ide server |
| 25 over communications path 20. Communicat | ions device |
| 37 may be a modem (e.g., any suitable analo | g or digital |
| 40 25 standard, cellular, or cable modem), networ | |
| card (e.g., an Ethernet card, Token ring ca | |
| combination of such devices, or any other s | |
| communications device. Television 36 may a | |
| 45 such a suitable communications device if de | |
| 30 Set-top box 28 may have memory 44 | - |
| may be any memory or other storage device, | |
| random access memory (RAM), read only memor | |
| 50 flash memory, a hard disk drive, a combinat. | ton of Such |
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5 - 20 devices, etc., that is suitable for storing program guide client instructions and program guide data for 10 use by the program guide client. A more generalized embodiment of user 5 television equipment 22 of FIG. 3 is shown in FIG. 4. As shown in FIG. 4, program guide data from television 15 distribution facility 16 (FIG. 1) and programming are received by control circuitry 42 of user television equipment 22. The functions of control circuitry 42 20 10 may be provided using the set-top box arrangement of FIGS. 2a and 2b. Alternatively, these functions may be integrated into an advanced television receiver, personal computer television (PC/TV) such as shown in 25 FIG. 2c, or any other suitable arrangement. If 15 desired, a combination of such arrangements may be used. User television equipment 22 may also have 30 secondary storage device 47 and digital storage device 49 for recording programming. Secondary storage device 20 47 can be any suitable type of analog or digital program storage device (e.g., a videocassette recorder, 35 a digital versatile disc (DVD), etc.). Program recording and other features may be controlled by control circuitry 42. Digital storage device 49 may 25 be, for example, a writeable optical storage device 40 (such as a DVD player capable of handling recordable DVD discs), a magnetic storage device (such as a disk drive or digital tape), or any other digital storage device. 45 30 User television equipment 22 may also have memory 63. Memory 63 may be any memory or other storage device, such as a random access memory (RAM), read only memory (ROM), flash memory, a hard disk 50

PCT/US99/19051

drive, a combination of such devices, etc., that is suitable for storing program guide client instructions and program guide data for use by control circuitry 42. User television equipment 22 of FIG. 4 may

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5 also have communications device 51 for supporting communications between the program guide client and program guide server 25 and via communications path 20. Communications device 51 may be a modem (e.g., any suitable analog or digital standard, cellular, or cable 10 modem), network interface card (e.g., an Ethernet card, Token ring card, etc.), a combination of such devices, or any other suitable communications device.

A user controls the operation of user television equipment 22 with user interface 46. User 15 interface 46 may be a pointing device, wireless remote control, keyboard, touch-pad, voice recognition system, or any other suitable user input device. To watch television, a user instructs control circuitry 42 to display a desired television channel on display

20 device 45. To access the functions of the program guide, a user instructs the program guide implemented on interactive television program guide equipment 17 to generate a main menu or other desired program guide display screen for display on display device 45. If

25 desired, the program guide client running on user television equipment 22 may provide users with access to program guide features without requiring them to navigate the Internet.

The program guide may provide users with an 30 opportunity to access program guide features through a main menu. A main menu screen, such as illustrative main menu screen 100 of FIG. 5, may include menu 102 of selectable program guide features 106. If desired,

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program guide features 106 may be organized according to feature type. In menu 102, for example, program guide features 106 have been organized into three columns. The column labeled "TV GUIDE" is for listings 5 related features, the column labeled "MSO SHOWCASE" is for multiple system operator (MSO) related features, and the column labeled "VIEWER SERVICES" is for viewer related features. The interactive television program guide may generate a display screen for a particular 10 program guide feature when a user selects that feature from menu 102.

Main menu screen 100 may include one or more selectable advertisements 108. Selectable advertisements 108 may, for example, include text and 15 graphics advertising pay-per-view programs or other programs or products. When a user selects a selectable advertisement 108, the program guide may display information (e.g., pay-per-view information) or take other actions related to the content of the

20 advertisement. Pure text advertisements may be presented, if desired, as illustrated by selectable advertisement banner 110.

Main menu screen 100 may also include other screen elements. The brand of the program guide

25 product may be indicated, for example, using a product brand logo graphic such as product brand logo graphic 112. The identity of the television service provider may be presented, for example, using a service provider logo graphic such as service provider logo

30 graphic 114. The current time may be displayed in clock display region 116. In addition, a suitable indicator such as indicator graphic 118 may be used to indicate to a user that mail from a cable operator is

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waiting for a user if the program guide supports

messaging functions. 10 The interactive television program guide may provide a user with an opportunity to view television 5 program listings. A user may indicate a desire to view program listings by, for example, positioning highlight 15 region 120 over a desired program guide feature 106. Alternatively, the program guide may present program listings when a user presses a suitable key (e.g., a 20 10 "guide" key) on remote control 40. When a user indicates a desire to view television program listings, the program quide client requests listings from program quide server 25 and generates an appropriate program 25 listings screen for display on display device 45 15 (FIG. 4). Program listings screens may be overlaid on a program being viewed by a user or overlaid on a portion of the program in a "browse" mode. Program 30 listings screens are described, for example, in Knudson et al. U.S. patent application Serial No. 09/357,941, 20 filed July 16, 1999 (Attorney Docket No. UV-114), which is hereby incorporated by reference herein in its 35 entirety. A program listings screen may contain one or more groups or lists of program listings organized 25 according to one or more organization criteria (e.g., 40 by time, by channel, by program category, etc.). The program guide may, for example, provide a user with an opportunity to view listings by time, by channel, according to a number of categories (e.g., movies, 45

30 sports, children, etc.), or may allow a user to search for a listing by title. Program listings may be displayed using any suitable list, table, grid, or other suitable display arrangement. If desired,

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- 24 program listings screens may include selectable advertisements, product brand logo graphics, service 10 provider brand graphics, clocks, or any other suitable indicator or graphic. 5 A user may indicate a desire to view program listings by time, channel, or category by, for example, 15 selecting a selectable feature 106 from menu 102. In response, the program guide client may issue one or more requests to program guide server 25 for listings 20 10 in the selected category if such listings are not already cached in memory 63 (FIG. 4). Program guide server 25 may retrieve program guide data stored on storage device 56, on another server, or from Internet 25 service system 61, and provide the data to the program 15 guide client via program guide distribution equipment 21. The program guide client may display program 30 listings in a suitable program listings screen on user television equipment 22. FIG. 6 illustrates the 20 display of program listings by time. Program listings screen 130 of FIG. 6 may include highlight region 151, 35 which highlights the current program listing 150. A user may position highlight region 151 by entering appropriate commands with user interface 46. For 25 example, if user interface 46 has a keypad, a user can 40 position highlight region 151 using "up" and "down" arrow keys on remote control 40. A user may select a listing by, for example, pressing on the "OK" or "info" key on remote control 40. Alternatively, a touch 45 30 sensitive screen, trackball, voice recognition device, or other suitable device may be used to move highlight region 151 or to select program listings without the use of highlight region 151. In still another 50

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PCT/US99/19051

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approach, a user may speak a television program listing into a voice request recognition system. These methods of selecting program listings are merely illustrative. Any other suitable approach for selecting program 5 listings may be used if desired.

A user may view additional listings for the time slot indicated in timebar 111 by, for example, pressing an "up" or "down" arrow, or a "page up" or "page down" key on remote control 40. The user may 10 also see listings for the next 24 hour period, or the last 24 hour period, by pressing a "day forward" or "day backward" key on remote control 40, respectively.

If there are no listings starting exactly 24 hours in the indicated direction, the program guide may pick 15 programs starting at either closer or further than 24 hours away. If desired, the program guide may require

a user to scroll through advertisement banner 110. A user may view program listings for other time slots by, for example, pressing "right" and "left" arrows on 20 remote control 40.

FIG. 7 illustrates the display of program listings by channel. A user may scroll up and down to view program listings for additional time slots, and may scroll left and right to view program listings for 25 other channels. If desired, the day for which program listings are displayed may be included in display

The program guide may provide users with an opportunity to view program listings sorted by 30 category. A user may, for example, press a special category key on remote control 40 (e.g., "movies", "sports", "children", etc.), select a selectable category feature from main menu screen 100 (FIG. 5), or

area 147 with the channel number as shown.

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may indicate a desire to view program listings by category using any other suitable approach. FIG. 8a is an illustrative program listings screen in which program listings for movies are displayed. FIG. 8b is

5 an illustrative program listings screen in which program listings for sports-related programming are displayed. FIG. 8c is an illustrative program listings screen in which program listings for children's programs are displayed.

In program listings display screens such as those shown in FIGS. 7a and 8a-8c for example, program listings within lists 129 may be divided into predefined time slots, such as into 30 minute time slots. Between each time slot, separator 128 may be

15 displayed to indicate to a user that a user has scrolled or paged program listings from one time slot to the next. In FIG. 7 for example, a user is scrolling from program listings in the 11:30 PM to the 12:00 AM time slot. This is indicated by the display of

20 the name of the next week day. In FIGS. 8a-8c, for example, a user is scrolling from program listings in the 12:30 PM time slot to program listings in the 1:00 PM time slot. If desired, separators 128 may be displayed only for those timeslots for which there are

25 listings. When the user scrolls within listings, highlight region 151 may skip separator 128. FIGS. 6, 7, and 8a-8c also illustrate how the program guide may display an advertisement banner so that a user is required to scroll past the banner to access additional 30 program listings.

The program listings screens of FIGS. 6, 7, 8a, 8b, and 8c have also been shown as including various other screen elements. Program listings

PCT/US99/19051

5 - 27 display screens may include, for example, selectable advertisements, advertisement banners, brand logos, 10 service provider logos, clocks, message indicators, or any other suitable screen element. The program guide 5 may provide users with access to selectable 15 advertisements in response to, for example, a user pressing left arrows to move highlight region 151 to highlight a selectable advertisement. In the illustrative program listings screens of FIGS. 6, 8a, 20 10 8b, and 8c, the program guide may also adjust the time displayed in timebar 123 as the user scrolls or pages through program listings to reflect the time of the program listing at the top of the list. 25 The program guide client may provide a user 15 with an opportunity to define sophisticated boolean or natural language expressions of one or more criteria. Such criteria may include, for example, attribute type 30 and attribute information that is provided by program quide server 25. The user defined expressions may be 20 stored by program guide server 25 for searching through and sorting program guide data, scheduling reminders, 35 automatically recording programs, and parentally controlling programs. Criteria may also be derived by the program guide server or program guide client from 25 user profiles or by monitoring usage of the program 40 guide or advertising. Program guide server 25 may also use expressions to obtain other types of information or programs. Program guide server 25 may obtain, for example, video-on-demand programs, web site links, 45 30 games, chat group links, merchandise information, or any other suitable information or programming from data sources 14 located at main facility 12 or other 50 facilities. The program guide client may provide users 55

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with an opportunity to access, modify, or delete the expressions if desired. 10 A user may indicate a desire to search program guide data by, for example, selecting 5 selectable Search feature 106 of main menu 102 (FIG. 5). In response, the program guide client may display 15 a criteria screen, such as illustrative criteria screen 141 and 149 of FIGS. 9a and 9b. The program guide client may display criteria screen 141 of FIG. 9a to 10 provide a user with an opportunity to define a boolean 20 expression. The user may construct a boolean expression by selecting criteria such as attribute types, attributes, logical operators, and sorting 25 criteria. User selectable criteria may also include 15 what program guide server 25 searches for such as, for example, program listings, program information, web sites, video-on-demand videos, software, or any other 30 suitable program guide data, other information, or videos. Users may define expressions by, for example, 20 arrowing up or down between criteria, arrowing left or 35 right to choose an attribute, attribute type or logical operator, and pressing a suitable key to indicate that the user is finished (e.g., an "OK" key). In the 25 example of FIG. 9a, the user has constructed a boolean 40 expression for all action programs that have the actor Bruce Willis, that start between 7:00P and 11:00P, and that end between 9:00P and 1:30A on the current day. FIG. 9a has not been shown as including criteria for 45 30 selecting what program guide server 25 searches for to avoid over-complicating the drawing. The program guide client may display criteria screen 149 of FIG. 9b to provide a user with an 50 55

opportunity to construct a natural language expression. The user may enter a natural language phrase, such as "List in alphabetical order all action programs starring Bruce Willis and that start today between 5 7:00P and 11:00P and that end between 9:00P and 1:30A"

- 29 -

using user interface 46 (FIG. 4).

The program guide client may submit the user defined boolean expression or the natural language expression to program guide server 25 for processing.

10 Program guide server 25 may process the expression, and provide the resulting program guide data (e.g., program listings, program information, software, Internet links, etc.) or video programs to the program guide client for display. FIG. 11 shows an illustrative 15 program listings screen that may be displayed by the

program guide client in response to the expressions defined in FIGS. 9a and 9b.

Users may also indicate a desire to have program guide server 25 automatically process

20 expressions by, for example, saving defined expressions as agents. A user may indicate a desire to save an expression as an agent by, for example, selecting Save As Agent selectable feature 147 of FIGS. 9a and 9b after defining a boolean or natural language

25 expression. The program guide client may automatically highlight Save As Agent selectable feature 147 when a user indicates that the user is finished defining an expression (e.g., by pressing an "OK" key). If desired the program guide client may provide the user with an 30 opportunity to name the agent.

Users may access saved expressions or agents by, for example, selecting selectable Agent feature 106 of main menu 102. In response, the program guide

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agents. An illustrative agents screen 1101 is shown in

client may display a list of saved expressions or

FIG. 10. A user may indicate a desire to view program listings by, for example, positioning highlight region 5 151 over the desired expression and pressing an "OK" key on remote control 40. In response to a user indicating a desire to access an expression, the program guide client may submit the user defined expression to program guide server 25 for processing. 10 Program guide server may process the expression, and provide program listings to the program guide client for display in a program listings screen. For example, if a user saved the boolean expression of FIG. 9a, named it "Bruce Willis", and then indicated a desire to 15 access listings for the expression the program guide client may display the listings screen of FIG. 10. In still another approach, the program quide client may provide the expression to program guide server 25 in response to the user saving the expression 20 as an agent. Program quide server 25 may store the expression and monitor the data stored on storage device 56 for program guide listings, program information, other information, software, videos, etc.,

that match the expression. Program guide server 25 may 25 also query other sources for program guide data and videos that match the expression via, for example, the Internet. Program guide server 25 may obtain the program guide data, other information or videos from storage device 56 or other sources and provide them to 30 the program guide client when the user indicates a desire to access the agent. Alternatively, program guide server 25 may provide the program guide data, other information, or videos to the program guide

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client automatically when the user accesses a feature of the program guide that would display such information. In still another suitable approach, program guide server 25 may provide, for example,

5 program identifiers and air times to the program guide client for use in generating program reminders that indicate found programs.

The program guide may also provide users with an opportunity to define user preferences that allow 10 users to customize their program guide experience. Systems in which interactive television program guides provide users with opportunities to define user preference profiles are described, for example, in Ellis et al. U.S. patent application Serial No.

15 09/034,934, filed March 4, 1998 (Attorney Docket No. UV-43), which is hereby incorporated by reference herein in its entirety. Users may indicate a desire to set up user preference profiles, for example, by selecting a selectable Setup feature 106 from main menu 20 102 of FIG. 5. When a user selects a selectable Setup

feature 106 from main menu 102, the program guide client may display a setup screen, such as illustrative setup screen 411 of FIG. 12.

Setup screen 411 may provide a user with an 25 opportunity to set up various guide features, set parental control features, set features of set-top box 28 (FIG. 3), set audio features, set the screen position, set user preference profiles, or to set up any other feature or suitable combination of features. 30 The user may indicate a desire to set up a user

preference profile by, for example, selecting User Profile feature 417. When the user indicates a desire to set up a user preference profile, the program guide

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client may display a user preference profile setup screen, such as the preference profile setup screens shown in FIGS. 13a-13f. This method of defining user profiles is only illustrative, as any suitable method

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5 may be used.

In practice, there may be multiple users associated with each user television equipment 22. The program guide may provide users with the ability to set up multiple user preference profiles. Users may switch 10 between user preference profiles by, for example,

selecting preference profile selector 109 and arrowing right or left to select the desired user preference profile. In FIGS. 13a-13f, for example, the user has selected Preference profile #1, which may correspond to 15 a particular user.

User preference profiles may include criteria such as preference attributes 104 and preference levels 106. Preference attributes 104 may be organized by type. Attribute types and attributes may be programmed 20 into the program guide client, or may be retrieved by the program guide client from program guide server 25. In the former approach, the available attribute types and attributes may remain static until the program guide client is updated. In the latter approach, the

25 available attribute types and attributes may be dynamic. Suitable attribute types and attributes may be provided at any time by main facility 12 or television distribution facility 16. Each time a user indicates a desire to set up a user preference profile, 30 the program guide client may query program guide server 25 for the available attribute types and attributes. When a user indicates a desire to set up a user preference profile in either approach, the program

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guide client may query program guide server 25 for the user preference profiles associated with that program guide client.

FIGS. 13a-13f show six illustrative views of 5 preference profile setup screens in which the user has selected attribute types by, for example, selecting attribute selector 111 and arrowing right or left until a desired preference attribute type is displayed. For example, FIGS. 13a-13f illustrate how the program guide

10 may provide a user with an opportunity to set preference levels for series, genres, channels, actors and actresses, ratings, and other types of preference attributes, respectively. The user may select preference attributes by, for example, arrowing down

15 after selecting an attribute type. The user may then arrow right or left until a desired attribute is displayed. After the desired preference attribute is displayed, the user may, for example, arrow down to set a preference level for the attribute. The user may 20 then, for example, arrow right or left to select a

suitable preference level.

Preference levels that may be used to indicate the user's interest or disinterest in a given preference attribute include strong like, weak like, 25 strong dislike, weak dislike, mandatory (appropriate,

e.g., for closed-captioning for a deaf person), illegal (appropriate, e.g., for R-rated programs for a child) and don't care (neutral). After the user indicates that he or she is finished defining a profile (e.g., by
30 pressing an "OK" key or remote control 40), the program guide client may provide the preference profile data to program guide server 25 for use in providing program

guide data. The user may arrow down again to select

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5 - 34 additional criteria, or arrow up to edit criteria that has already been selected. The user may delete an 10 attribute by, for example, setting its preference level to "don't care." 5 The user may activate or deactivate one or 15 more defined preference profiles by, for example, selecting selectable Profile feature 106 from main menu 102 of FIG. 5. The program guide client may respond by, for example, querying program guide server 25 for 20 10 any defined preference profiles, providing the user with a list of preference profiles, and providing the user with an opportunity to activate or deactivate one or more preference profiles as shown in FIG. 14. A 25 user may deactivate a preference profile by, for 15 example, setting the profile to non-active. A user may set a preference profile as active to varying degrees. For example, a user may set a profile as active by 30 setting the profile to "wide", "moderate", or "narrow" scope. 20 The program guide client may also indicate to program guide server 25 which profiles are activated or 35 deactivated. The program guide server may use, for example, the attributes of one or more user preference profiles as additional criteria when retrieving data in 25 response to data requests from the program guide 40 client. If multiple preference profiles are used simultaneously, program guide server 25 may reconcile any conflicts using any suitable approach. Interactive television program guide systems that resolve conflicts 45 30 among multiple active user preference profiles are described, for example, in above-mentioned Ellis et al. U.S. patent application Serial No. 09/034,934, filed 50 March 4, 1998.

PCT/US99/19051

- 35 -

FIG. 15 is a table containing an illustrative list of programs that might be available to a user. The results that appear under the columns labeled "narrow scope", "moderate scope", and "wide scope",
5 show which programs satisfy the preference attributes and preference levels of, for example, Profile #1 as illustratively defined in FIGS. 13a-13f. In practice, a listings screen generated based on a profile that is set to widest scope may typically include a larger
10 number of program listings depending on the mandatory attributes set by the user.

When the user activates Profile #1 and sets it to the widest scope, program guide server 25 may provide program guide data for programs that have all 15 mandatory attributes and no illegal attributes. For example, Seinfeld, The Shining, ER, Terminator, and My Stepmother is an Alien are included in the widest preference scope because they have the only mandatory attribute that is specified in Profile #1 -- closed-20 captioning (as set in FIG. 13f). In addition, they

have no preference attributes with a preference level of illegal (R rating, TV-MA rating, or NC-17 rating (as set in FIG. 13e). The Night at the Opera is not included because it does not have a mandatory attribute

25 (closed-captioning). Dante's Peak is not included because it has a illegal rating (R). An illustrative program listings screen that may be displayed by the program guide client with such limited data is shown in FIG. 16a (ER has not been listed because, presumably, 30 it would be in a different time block).

When the user activates Profile #1 and sets it to the moderate scope, program guide server 25 may provide program guide data for programs that have no

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- 36 preference attributes with an associated preference level of disliked, that have all mandatory attributes, and that have no illegal attributes. The Shining is not included because horrors have a preference level of 5 "weak dislike" (as set in FIG. 13b). Dante's Peak is not included because it has an R-rating, which has an attribute level of illegal (as set in FIG. 13e). Night at the Opera is not included because it is not closedcaptioned, which is a mandatory attribute (as set in 10 FIG. 13f). The Terminator, for example is not within the moderate scope of Profile #1 because the preference attribute of horror in Profile #1 has an associated preference level of "weak dislike" and the preference attribute of Schwarzenegger (an actor in the program 15 Terminator) has an associated preference level of "strong dislike" (as set in FIGS. 13b and 13d, respectively). Seinfeld and ER are included because they do not have any disliked attributes. When faced with two different preference 20 levels associated with the same program, the program quide uses the stronger of the two. My Stepmother is an Alien is included, for example, because it has a "strong like" preference attribute that outweighs the "weak dislike". An illustrative program listings 25 screen that may be displayed by the program guide client with such limited program guide data is shown in. FIG. 16b. In practice, a listings screen generated based on a profile that is set to moderate scope may typically include a larger number of program listings 30 depending on the mandatory attributes set by the user. When the user activates Profile #1 and sets it to the narrow preference scope, program guide server 25 may provide program guide data for all liked

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programs that are not more disliked and that have all mandatory attributes and no illegal attributes. The Shining is not included because it has a weakly disliked attribute, horror. Terminator is not included 5 because it has a strongly disliked attribute, Arnold Schwarzenegger. My Stepmother is an Alien is included because the strongly liked attribute of comedy has priority over the weakly disliked attribute of horror. Dante's Peak is not included because it has a rating of 10 R. Night at the Opera is not included because it is not closed-captioned. ER is not within the narrow scope because it does not have any liked attributes. It is at best, neutral. An illustrative program listings screen that may be displayed by the program 15 guide client with such limited program guide data is shown in FIG. 16c. The program guide may also provide users with an opportunity to schedule reminders using boolean or natural language expressions having one or more

20 criteria. If desired, program guide server 25 may schedule reminders based on user preference profiles and agents. Reminders may be scheduled for individual programs or series of programs. Systems in which reminders are set for series of programs are described,

25 for example, in Knudson et al. U.S. patent application Serial No. 09/330,792, filed June 11, 1999 (Attorney Docket No. UV-56), which is hereby incorporated by reference herein in its entirety.

A user may indicate a desire to schedule a 30 reminder by, for example, selecting a selectable Reminders feature 106 from main menu 100 of FIG. 5. In response, the program guide may display a criteria screen. Illustrative criteria screens 161 and 169 are

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shown in FIGS. 17a and 17b. The program guide client may display criteria screen 161 of FIG. 17a to provide

a user with an opportunity to set reminders according to a boolean type expression. The user may construct a

attribute types, attributes, and logical operators.

example of FIG. 17a, the user has defined a boolean expression to schedule reminders for comedies that star Gary Shandling and that have a rating less than R. In

defined boolean or natural language expression to

20 reminders for all of the programs that meet the

may process an expression and provide program

30 list of program identifiers and display program

the example of FIG. 17b, the user has defined a similar

program guide server 25 for processing. Program guide server 25 may process the expression and schedule

expression. Program reminders may be scheduled using

In another suitable approach, program guide server 25

identifiers and air times to the program guide client. The program guide client may, for example, maintain a

reminders at an appropriate time before the programs

any suitable approach. In one suitable approach, program guide server 25 may store program identifiers and air times and send messages to the program guide 25 client at an appropriate time before a program starts.

The program guide client may submit the user

The user may make such selections, for example, using any suitable combination of right, left, up, or down arrow key sequences to sequence through the attribute

5 boolean expression by selecting criteria such as

10 types, attributes and logical operators. In the

15 natural language expression.

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PCT/US99/19051

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- 39 -

| 10 | | The program guide may remind a user that a |
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| | | program is airing at the time a program airs. In an |
| | | alternative approach, the program guide may remind a |
| | | user at some predetermined period of time before the 🧳 |
| 15 | . 5 | program airs that a program is going to air. FIGS. 18 |
| | | and 19 show illustrative program reminder lists 171. |
| | | In FIG. 18, reminder list 171 is overlaid on top of the |
| | | currently display television program to provide a user |
| 20 | | with the opportunity to view a reminder while still |
| | 10 | viewing a portion of the television program that a user |
| | | is watching. In FIG. 19, reminder list 171 is shown |
| | | overlaid on top of a program listings display screen. |
| | | The program guide may provide a user with an |
| 25 | | opportunity to scroll through reminder list 171 by, for |
| | 15 | example, using remote control arrow keys. The program |
| | | guide may hide the reminder list when, for example, a |
| 20 | | user selects hide reminder feature 172. The guide may |
| 30 | · | also display reminder list 171 if, for example, the |
| | | user presses an "OK" key at any time while watching TV. |
| | 20 | The program guide may also provide users with |
| 35 | | an opportunity to schedule programs for recording by |
| | | secondary storage device 47 or digital storage device |
| | | 49 (FIG. 4) using boolean or natural language |
| | | expressions. If desired, program guide server 25 may |
| 40 | 25 | schedule programs for recording based on user |
| | | preference profiles or agents. Programs may also be |
| | | scheduled for recording by program guide server 25. |
| | | Program guide systems in which programs are recorded by |
| 45 | | a remote server are described, for example, in Ellis et |
| | 30 | al. U.S. patent application Serial No. 09/332,244, |
| | | filed June 11, 1999 (Attorney Docket No. UV-84), which |
| | | is hereby incorporated by reference herein in its |
| 50 | | entirety. |
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| 10 | | A user may indicate a desire to schedule a program for recording by, for example, selecting a |
| | 5 | selectable Record feature 106 from main menu 102 of FIG. 5. In response, the program guide may display a criteria screen, such as illustrative criteria screens |
| 15 | | 161 and 169 of FIGS. 17a and 17b. The program guide client may display criteria screen 161 of FIG. 17a to provide a user with an opportunity to schedule a |
| 20 | 10 | program for recording according to a boolean type expression. The user may construct a boolean expression by selecting criteria such as attribute types, attributes, and logical operators. The user may |
| 25 | 15 | make such selections, for example, using any suitable combination of right, left, up, or down arrow key sequences to sequence through the attribute types, |
| 30 | | attributes and logical operators. In the example of FIG. 17a, the user has defined a boolean expression to schedule for recording comedies that star Gary Shandling and that have a rating less than R. In the |
| 35 | 20 | example of FIG. 17b, the user has defined a similar natural language expression with similar criteria. The program guide client may submit the user defined boolean or natural language expression to |
| 40 | 25 | program guide server 25 for processing. Program guide server 25 may process the expression and schedule all of the programs that meet the expression for recording. Recording by program guide server 25 may be performed, for example, as described in above-mentioned Ellis et |
| 45 | 30 | al. U.S. patent application Serial No. 09/332,244, filed June 11, 1999 (Attorney Docket No. UV-84). In another suitable approach, program guide server 25 may process the expression and provide program identifiers |
| 50 | | and air times to the program guide client. The program |
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quide client may, for example, maintain a list of program identifiers and program air times and may instruct optional secondary storage device 47 or digital storage device 49 to record the programs.

- 41 -

The program guide may also provide users with an opportunity to parentally control titles, programs, or channels using boolean or natural language expressions. If desired, program guide server 25 may parentally control programs based on user preference 10 profiles. A user may indicate a desire to parentally

control titles, programs, or channels by, for example, selecting a selectable Parents feature 106 from main menu 102 of FIG. 5. In response, the program guide may display a criteria screen, such as illustrative

15 criteria screens 161 and 169 of FIGS. 17a and 17b. The program guide client may display criteria screen 161 of FIG. 17a to provide a user with an opportunity to control programs, for example, according to a boolean type expression. The user may construct a boolean type

20 expression by selecting criteria such as attribute types, attributes, and logical operators. The user may make such selections, for example, using any suitable combination of right, left, up, or down arrow key sequences to sequence through the attribute types,

25 attributes and logical operators. In the example of FIG. 17a, the user has defined a boolean expression to lock out comedies that star Gary Shandling and that have a rating less than R. In the example of FIG. 17b, the user has defined a similar natural language 30 expression with similar criteria.

The program guide client may submit the user defined boolean or natural language expression to program guide server 25 for processing. Program guide

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server 25 may process the expression, determine all of the programs that meet the expression, and indicate the programs that are locked to the program guide client when providing program listings to the program guide

5 client using a suitable indicator (e.g., "locked" tag contained in the listings information). The program guide client may, for example, indicate that a program is locked by displaying lock indicator 161 when displaying locked listings in a listing screen, as

10 shown, for example, in FIG. 7. By placing the processing and storage burdens of locking programs on program guide server 25 instead of user television equipment 22, more titles may be locked than would otherwise because of the limited processing and storage

15 resources of user television equipment 22. If desired, titles, programs, or channels may also be locked using conventional parental control techniques. Program guide systems that provide users with an opportunity to parentally control titles, programs, or channels are

20 described, for example, in above-mentioned Knudson et al. U.S. patent application Serial No. 09/357,941 filed July 16, 1999 (Attorney Docket No. UV-114).

Program guide server 25 may also record the viewing histories of users on storage device 56.

25 Viewing histories may be created using any suitable approach. The program guide client may, for example, keep track of all of the programs that a user watches for longer than a predefined time, and record the household that the guide client is running in, the 30 current active preference profile or profiles, the

program (or its identifier), and how long the user watched the program. The program guide client may also track when users order pay-per-view programs, record

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programs, and schedule reminders for programs, and may also provide this information to program guide server 25 as part of the viewing histories. Other types of information may also be included in the viewing

5 histories. User defined expressions, for example, may be stored by program guide server 25 to track what types of programs users search for. In addition, user demographic values may be calculated by program guide server 25 and used to more accurately target

10 advertisements or recommend programs. Systems in which user demographic values are calculated are described, for example, in Knudson et al. U.S. patent application Serial No. 09/139,777, filed August 25, 1998 (Attorney Docket NO. UV-58), which is hereby incorporated by

15 reference herein in its entirety.

The program guide client may provide the viewing history information to program guide server 25 continuously (e.g., each time the program guide client determines that a user has watched a program for the 20 predefined time), periodically, in response to polls or

requests from program guide server 25, or with any other suitable frequency. If desired, the program guide client may also monitor advertisement usage, such as what selectable advertisements users have selected.

25 Program guide systems in which user viewing activities and advertisement usage are tracked are described, for example, in Thomas et al. U.S. patent application Serial No. 09/139,798, filed August 25, 1998 (Attorney Docket No. UV-57), which is hereby incorporated by 30 reference herein in its entirety.

The program guide may process user profiles along with the viewer histories to present a more customized viewing experience to the user. The program

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guide may, for example, identify which programs or series episodes users have watched. Program guide server 25 may, for example, identify episodes that users have not yet watched and may indicate such

5 episodes to the program guide client when the program guide client requests program listings. The program guide client in turn may indicate that a program is new to a household by, for example, displaying a suitable icon or changing the display characteristics of a

10 listing (e.g., changing its color). FIG. 7 shows, for example, the display of New indicator 159 in list 129 to indicate to a user that the user has not seen a particular episode of Saturday Night Live. Program guide server 25 may also calculate ratings, such as 15 Nielsen ratings, based on the viewing histories and

provide such information to interested parties. The program guide may also use the viewing

history and user preferences to target the user with advertisements. Program guide systems in which users 20 are targeted with advertisements are described, for example, in Knudson et al. U.S. patent application Serial No. 09/034,939, filed March 4, 1998 (Attorney Docket No. UV-42), which is hereby incorporated by reference herein in its entirety. Targeted

25 advertisements may contain text, graphics, or video. Targeted advertisements may also be active objects containing various user-selectable options. For example, a targeted advertisement may allow the user to request that additional information on a product be 30 mailed to the user's home, may allow the user to

purchase a product, or may allow the user to view additional information on a product using the program guide. Targeted advertisements may be displayed in any

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PCT/US99/19051

- 45 suitable program guide display screen. The program guide client may, for example, display targeted advertisements in criteria or profile screens based on a displayed criteria, profile, or agent. Selectable 5 advertisements 108 and advertisement banner 110, for example, may be targeted advertisements. The program guide may make personalized viewing recommendations based on the viewing histories, preference profiles, or any suitable combination 10 thereof. Program guide server 25 may, for example, construct relational database expressions from the viewing histories that define expressions for the program categories and ratings for programs that users have watched, scheduled reminders for, searched for, or 15 ordered the most. Program guide server 25 may then apply user preference profile criteria to the programs, and generate personal viewing recommendations. In still another suitable approach, program guide server 25 or the program guide client may filter viewing 20 recommendations that are generated by main facility 12 or television distribution facility 16 based on similar expressions, profiles, viewing histories, etc. Assume, for the purpose of illustration, that a user has run the expression illustrated in FIGS. 9a 25 and 9b, and has set the user profiles of FIGS. 13a-13f, program guide server 25 may determine that the movie Armageddon meets the criteria of the expression that was run, and also meets the criteria of the current user profile. Armageddon is a movie (strong like), an 30 action (strong like), and does not have an illegal rating (it is rated PG-13). Program guide server 25 may indicate the movie Armageddon (or its identifier) and its air time to the program guide client and

PCT/US99/19051

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| 10 | indicate to the client (e.g., using a second identifier) that a viewer recommendation for the movie is to be displayed. The program guide client may |
| | display a viewer recommendation overlay, such as 5 overlay 2111 shown in FIGS. 20a and 20b, over a program |
| 15 | the user is watching or over a program guide display screen, respectively. The user may press a suitable key on remote control 40 (e.g., an "info" key) to |
| 20 | access additional information for a recommended 10 program. An illustrative additional information screen is shown in FIG. 20c. Additional program information |
| 25 | screens are described, for example, in above-mentioned Knudson et al. U.S. patent Application Serial No. 09/357,941 filed July 16, 1999 (Attorney Docket 15 No. UV-114). The program guide client may tune user |
| 30 | television equipment 22 to the channel on which a recommended viewing is aired when, for example, a user selects "Yes". If desired, recommendations may include |
| | a suitable graphic, such as a graphic indicating the 20 recommended program. FIGS. 21-24 show flowcharts of illustrative |
| 35 | steps involved in performing various aspects of the present invention. The steps shown in FIGS. 21-24 are only illustrative, and may be performed in any suitable |
| 40 | 25 order. FIG. 21 shows a flowchart of illustrative steps involved in storing preference profiles on |
| 45 | program guide server 25. If desired, the steps shown may be performed in a client-server interactive program 30 guide system in which users are not required to |
| 50 | navigate the Internet. At step 2000, the program guide client running on user television equipment 22 provides a user with an opportunity to define a preference |
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PCT/US99/19051

- 47 -

profile. The preference profile may include user selected or defined levels of desirability of various program characteristics, such as genre and rating. Users may define preference profiles by, for example,

5 selecting a profile (step 2002) and selecting criteria (step 2004) such as attribute types (step 2006) and attributes (step 2008). Preference profiles may, for example, be created as database files (e.g., SQL files) containing suitable database expressions that are 10 provided to program guide server 25. Program guide server 25 may store the preference profiles at step 2012.

Program guide data is provided from program guide server 25 to the program guide client and is 15 displayed by the program guide client at steps 2020 and 2030, respectively. Program guide server 25 or the program guide client may use preference profiles to filter out undesirable program guide data. This may be accomplished using any suitable approach. Program

20 guide server 25 may, for example, only provide program listings information or other program guide data that meets the preference profile or profiles to the program guide client (step 2025). Alternatively, program guide server 25 may provide program guide data, other

25 information, or videos to the program guide client and the program guide client may filter the data, other information, or videos by displaying only those elements that meet the preference profile or profiles (step 2035).

Program guide server 25 may perform additional functions based on preference profiles if desired. Program guide server 25 may, for example, lock programs according to preference profiles (step

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PCT/US99/19051

5 - 48 -2040), automatically record programs according to preference profiles (step 2050), schedule reminders 10 based on preference profiles (step 2060), or target advertising based on preference profiles (step 2070). . . . 15 viewing recommendations based on preference profiles at step 2080. Step 2080 may also include filtering viewing recommendations based on preference profiles provided by main facility 12 or television distribution 20 10 facility 16 (step 2085). FIG. 22 is a flowchart of illustrative steps involved in providing users with an opportunity to search program guide data in accordance with the 25 principles of the present invention. If desired, the 15 steps shown may be performed in a client-server interactive program guide system in which users are not required to navigate the Internet. At step 2100, the 30 program guide client provides a user with an opportunity to define an expression, such as a boolean 20 or natural language expression. This may include, for example, providing a user with an opportunity to select 35 attribute types, attributes, and logical operators (steps 2102, 2104, and 2106, respectively). The user may also be provided with an opportunity to save the 25. expression as an agent (step 2110). The program guide 40 client provides the expression to program guide server 25 for processing at step 2120. The program guide client may for example, provide a boolean or natural language expression in a text file. Alternatively, the 45 30 program guide client may construct suitable database expressions and provide the expressions to program guide server 25 as one or more suitable database files 50 (e.g., as SQL files).

- 49 -

If the user indicated a desire to save an expression as an agent at step 2110, program guide server 25 may save the expression as an agent at step 2130. Otherwise, program guide server 25 may process 5 the expression (step 2140) using any suitable approach. This may depend on how the expression was provided by the program guide client. If boolean or natural language expressions were provided as text files, for example, program guide server 25 may parse the 10 expressions and construct a suitable database

expression. Alternatively, database expressions may have been provided by the program guide client. In either approach, program guide server 25 may search its database or databases at other facilities for program

15 guide data (e.g., program listings, additional program information, etc.), other information (e.g., software, Internet links, etc.), or videos (e.g., video-on-demand videos) and may provide the results to the program guide client at step 2150. At step 2160 the program 20 guide client may display the results on user television equipment 22.

If the user indicated a desire to save the expression as an agent at step 2110. Program guide server 25 may save the expression as an agent using any 25 suitable approach. Agents may be maintained, for example, in a database that program guide server 25 monitors periodically. If desired, the agent may be forwarded to other servers at other facilities, thereby providing a user with the ability to monitor multiple 30 databases for program guide data, other information, or videos. Agents may be run automatically (e.g., databases may be queried) on one or more servers at step 2145. Step 2145 may be performed periodically,

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PCT/US99/19051

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each time a database is updated, or with any other suitable frequency. Program guide server 25 may provide its results and the results of other servers (if desired) to the program guide client at step 2155.

5 The program guide client may display the results at 2165. The results may be displayed, for example, in the form of reminders for which reminder information was provided at step 2155.

FIG. 23 shows a flowchart of illustrative 10 steps involved in processing and using expressions on program guide server 25 in accordance with the principles of the present invention. If desired, the steps shown may be performed in a client-server interactive program guide system in which users are not

15 required to navigate the Internet. The program guide client provides users with an opportunity to define an expression (e.g., boolean or natural language expressions) at step 2100. This may include, for example, providing a user with an opportunity to select

20 attribute types, attributes and logical operators (steps 2102, 2104, and 2106, respectively). The program guide client provides the expression to program guide server 25 for processing at step 2210 as any suitable type of file. The program guide client may

25 for example, provide a boolean or natural language expression in a text file. Alternatively, the program guide client may construct suitable database expressions and provide the expressions to program guide server 25 as one or more suitable database files 30 (e.g., as SQL files).

Program guide server 25 may process the expression (step 2220) using any suitable approach depending on how the expression was provided to program

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WO 00/11869 PCT/US99/19051 - 51 quide server 25 from the program quide client. Tf boolean or natural language expressions were provided as text files, for example, program guide server 25 may parse the expressions and construct a suitable database 5 expression. Alternatively, database expressions may have been provided to program guide server 25 from the program quide client. In either approach, program quide server 25 may search its database or databases at other facilities and may provide the results to the 10 program guide client or use the results to perform any suitable program guide function. Reminders may be scheduled based on the results of the search (step 2230). Program guide server 25 may, for example, store reminder information 15 (e.g., program identifiers and air times) at step 2235 and send messages to the program guide client at an appropriate time before a program starts. In another suitable approach, program guide server 25 may process an expression and provide program identifiers and air 20 times to the program guide client. The program guide client may, for example, maintain a list of program identifiers and display program reminders at an appropriate time before the programs start. Programs may also be automatically recorded 25 by program guide server 25 or user television equipment 22 based on the results of the expression (step 2240). Program guide server 25 may, for example, provide program identifiers and air times to the program guide client. The program guide client may, for example, 30 maintain a list of program identifiers and program air times and may instruct optional secondary storage device 47 or digital storage device 49 to record the programs at the appropriate time.

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PCT/US99/19051

- 52 -

Programs may be parentally locked based on 10 the expression results (step 2250). Program guide server 25 may, for example, store parental control information (e.g., program identifiers in a database, 5 table, or list of programs to be locked) at step 2260. Program guide server 25 may indicate to the program guide client that programs are locked when providing program listings to the program guide client. Alternatively, program guide server 25 may indicate to 10 the program guide client the programs that were found as a result of the expression. The program guide client may lock the programs locally using any suitable approach. The program guide client may, for example, indicate that a program is locked by displaying lock 15 indicator 161 when displaying locked listings in a listing screen, as shown, for example, in FIG. 7. FIG. 24 shows a flowchart of illustrative steps involved in tracking and using viewing histories in accordance with the principles of the present 20 invention. If desired, the steps shown may be performed in a client-server interactive program guide system in which users are not required to navigate the Internet. Viewing histories are tracked at step 2300. This may include tracking programs that users watch 25 (step 2310), tracking reminders scheduled by a user with program guide server 25 or using conventional techniques (step 2320), tracking pay-per-view programs that the user orders (step 2330), advertisement usage (step 2335), track recorded programs (step 2337), track 30 any other suitable user activity, or any suitable combination thereof. The program guide client may provide the viewing history information to program guide server 25 continuously (i.e., each time the

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program guide client determines that a user has watched a program for the predefined time), periodically, in response to polls or requests from program guide server 25, or with any other suitable frequency.

5 The viewing history tracked in steps 2310-2335 may be stored on program guide server 25 at step 2340. If desired, user-defined expressions that are processed by program guide server 25 may also be stored on program guide server 25 (step 2345). User

10 demographic values may be calculated by program guide server 25 at step 2347. The viewing history and its expressions and user demographic values may be used by program guide server 25 to perform any suitable function. Program guide server 25 may, for example, 15 collect program rating information (step 2350), or

target advertising (step 2360).

Program guide server 25 may search its or another server's database for programs that are consistent with the viewing history (step 2370). If

20 desired, program guide server 25 may find programs that are also consistent with preference profiles stored by program guide server 25 (step 2375). Program guide server may perform any suitable function using the results of the search. Program guide server 25 may,

25 for example, identify episodes of programs that are new to a user (step 2380), or provide viewing recommendations in the form of, for example, reminders or recommendations for non-program items (e.g., software, Internet links, etc.) (step 2390).

The foregoing is merely illustrative of the principles of this invention and various modifications can be made by those skilled in the art without departing from the scope and spirit of the invention.

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Claims

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PCT/US99/19051

WO 00/11869

5 - 54 -What is claimed is: 10 1. A method for use in a client-server interactive television program guide system comprising: providing a user with an opportunity to define user preferences using an interactive television 15 program guide client that is implemented on user television equipment, without requiring the user to navigate the Internet; providing the user preferences to a 20 program guide server; and providing program guide data to the program quide client according to the user preferences. 25 The method defined in claim 1 further 2. comprising: generating a viewing recommendation based on the user preferences with the program guide 30 server; and displaying the user preferences with the interactive television program guide client on the user television equipment. 35 The method defined in claim 1 wherein 3. providing a user with an opportunity to define user preferences comprises providing a user with an 40 opportunity to designate a preference level for a plurality of preference attributes. 45 4. The method defined in claim 1 further comprising providing software to the program guide client according to the user preferences. 50 55

PCT/US99/19051

5 - 55 -5. The system defined in claim 1 further comprising providing Internet links to the program 10 guide client according to the user preferences. 6. A method for use in a client-server 15 interactive television program guide system for scheduling reminders according to user defined expressions, comprising: providing a user with an opportunity to 20 define an expression with an interactive television program guide client implemented on user television equipment without requiring the user to navigate the Internet: 25 storing the expression on a program quide server; processing the expression with the program guide server to find programs that satisfy the 30 expression; and scheduling with the program guide server reminders for programs that satisfy the expression. 35 7. The method defined in claim 6 wherein scheduling with the program guide server reminders for programs that satisfy the expression comprises providing at least one message from the program guide 40 server to the program guide client before each of the programs that satisfy the expression begin. 8. The method defined in claim 6 wherein 45 scheduling with the program guide server reminders for programs that satisfy the expression comprises providing program identifiers for each of the programs 50 55

PCT/US99/19051

5 - 56 that satisfy the expression from the program guide server to the program guide client. 10 9. A method for use in a client-server interactive television program guide system for 15 scheduling programs for recording according to user defined expressions, comprising: providing a user with an opportunity to define an expression with an interactive television 20 program guide client implemented on user television equipment without requiring the user to navigate the Internet; storing the expression on a program 25 quide server; processing the expression with the program guide server to find programs that satisfy the expression; and 30 scheduling with the program guide server the programs that satisfy the expression for recording. 10. The method defined in claim 9 wherein 35 scheduling with the program guide server the programs that satisfy the expression for recording comprises scheduling with the program guide server the programs that satisfy the expression for recording by the user 40 television equipment. 11. The method defined in claim 9 wherein scheduling with the program guide server the programs 45 that satisfy the expression for recording comprises scheduling with the program guide server the programs that satisfy the expression for recording by the 50 program guide server. 55

PCT/US99/19051

- 57 -

12. A method for use in a client-server interactive television program guide system for parentally controlling programs according to user defined expressions, comprising:

providing a user with an opportunity to define an expression with an interactive television program guide client implemented on user television equipment without requiring the user to navigate the Internet;

storing the expression on a program guide server;

processing the expression with the program guide server to find programs that satisfy the expression; and

locking with the program guide server programs that satisfy the expression.

13. The method defined in claim 12 wherein locking with the program guide server programs that satisfy the expression comprises indicating to the program guide client that the programs that satisfy the expression are locked.

14. A method for use in a client-server interactive television program guide system for tracking a user's viewing history, comprising: tracking a user's viewing history; storing the user's viewing history on a program guide server;

finding programs with the program guide server that are consistent with the user's viewing history; and

indicating on user television equipment the programs found by the program guide server that are consistent with the user's viewing history and that the

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user has not watched, with an interactive television program guide client implemented on the user television equipment.

15. The method defined in claim 14 wherein storing the user's viewing history comprises storing a user defined expression with the program guide server.

16. The method defined in claim 14 wherein storing the user's viewing history comprises calculating user demographic values with the program guide server.

17. The method defined in claim 14 further comprising:

providing a user with an opportunity to define a user preference profile with the interactive television program guide client implemented on user television equipment;

storing the user preference profile on a program guide server; and

finding programs with the program guide server that are consistent with the user preference profile, wherein:

indicating on user television equipment the programs found by the program guide server that are consistent with the user's viewing history and that the user has not watched comprises indicating on user television equipment the programs found by the program guide server that are consistent with the user's viewing history and the user preference profile and that the user has not watched.

18. The method defined in claim 14 further comprising:

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5 - 59 targeting advertising with the program quide server based on the user's viewing history; and 10 displaying the advertising with the interactive television program guide client on the user television equipment. 15 19. The method defined in claim 14 further comprising collecting program ratings information with the program guide server based on the user's viewing 20 history. 20. A client-server interactive television program guide system comprising: 25 means for providing a user with an opportunity to define user preferences using an interactive television program guide client that is implemented on user television equipment, without 30 requiring the user to navigate the Internet; means for providing the user preferences to a program guide server; and means for providing program guide data 35 from the program guide server to the program guide client according to the user preferences. 21. The system defined in claim 20 further 40 comprising: means for generating a viewing recommendation based on the user preferences with the program guide server; and 45 means for displaying the user preferences with the interactive television program guide client on the user television equipment. 50 22. The system defined in claim 20 wherein the means for providing a user with an opportunity to 55