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(54) **APPARATUS AND METHOD FOR LOCALIZING SOUND SOURCE IN ROBOT**

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(57) **ABSTRACT**

An apparatus and method for localizing a sound source in a robot are provided. The apparatus includes a microphone unit implemented by one or more microphones, which picks up a sound from a three-dimensional space. The apparatus also includes a sound source localizer for determining a position of the sound source in accordance with Time-Difference of Arrivals (TDOAs) and a highest power of the sound picked up by the microphone unit. Thus, the robot can rapidly and accurately localize the sound source in the three-dimensional space with minimum dead space, using a minimum number of microphones.

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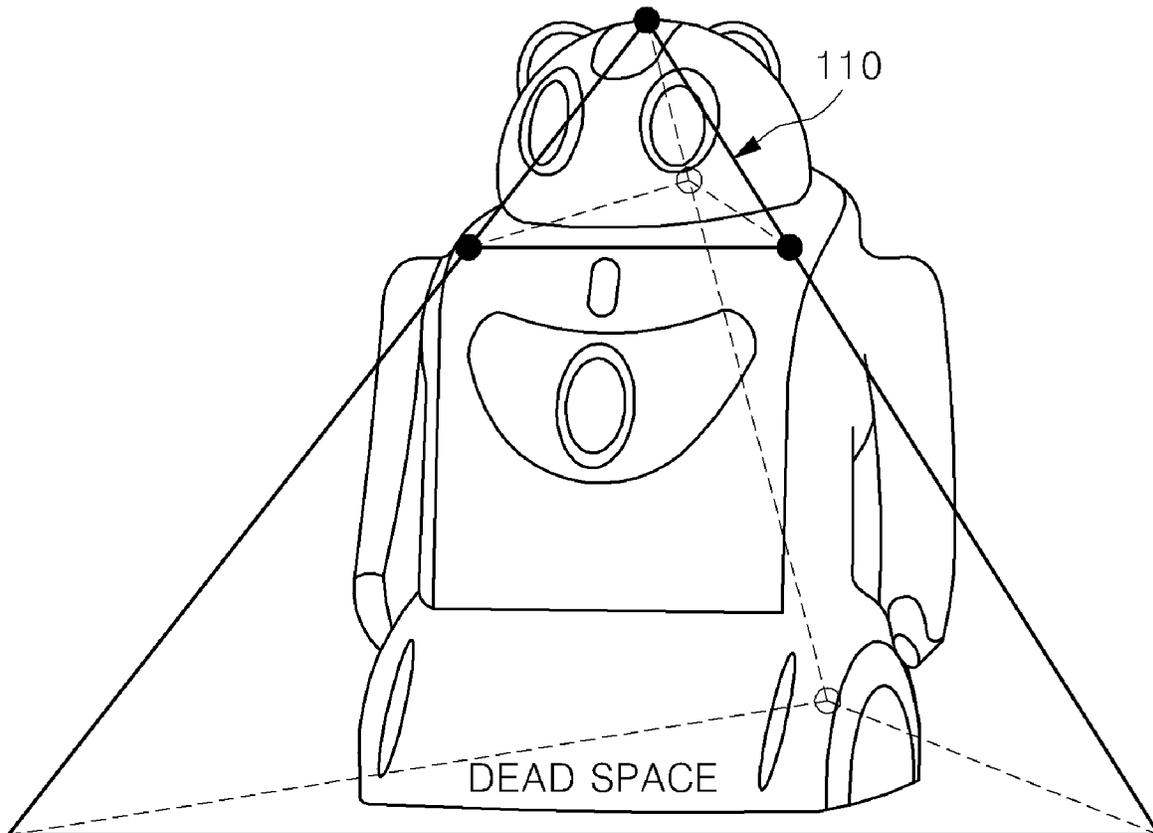


FIG. 1

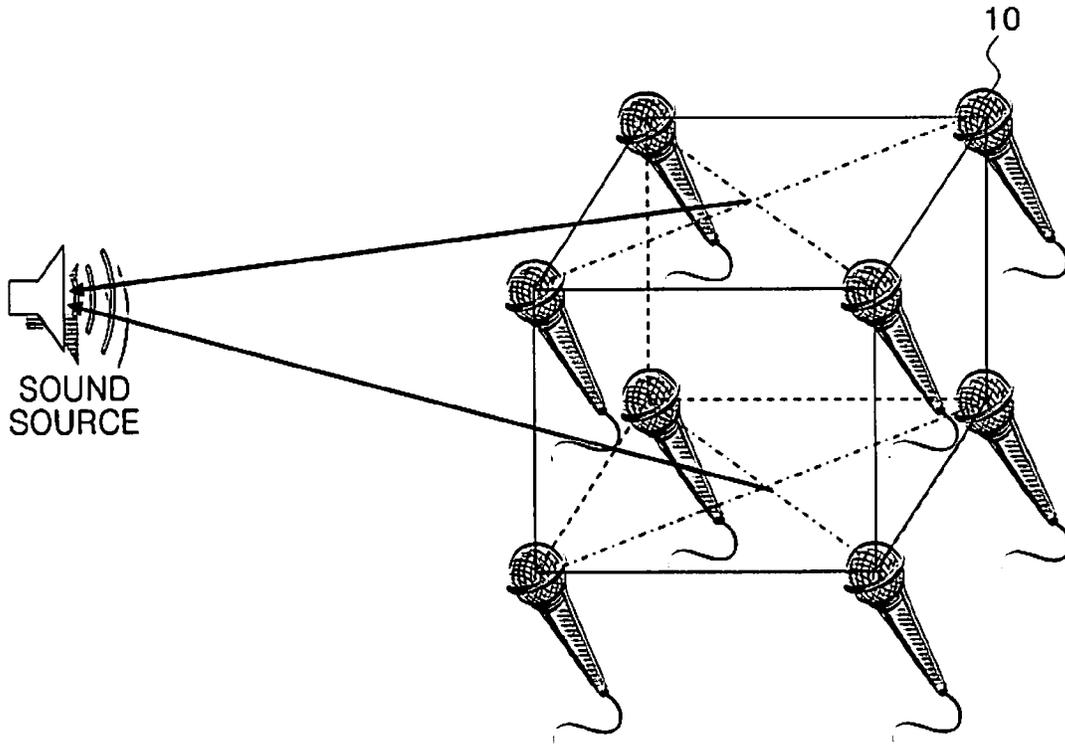


FIG. 2

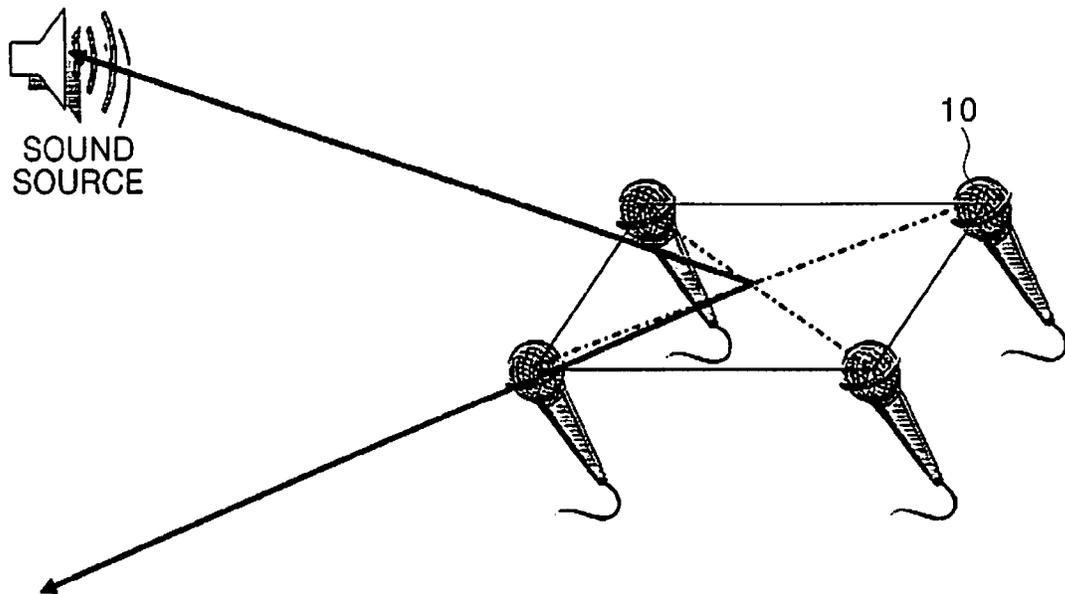


FIG.3

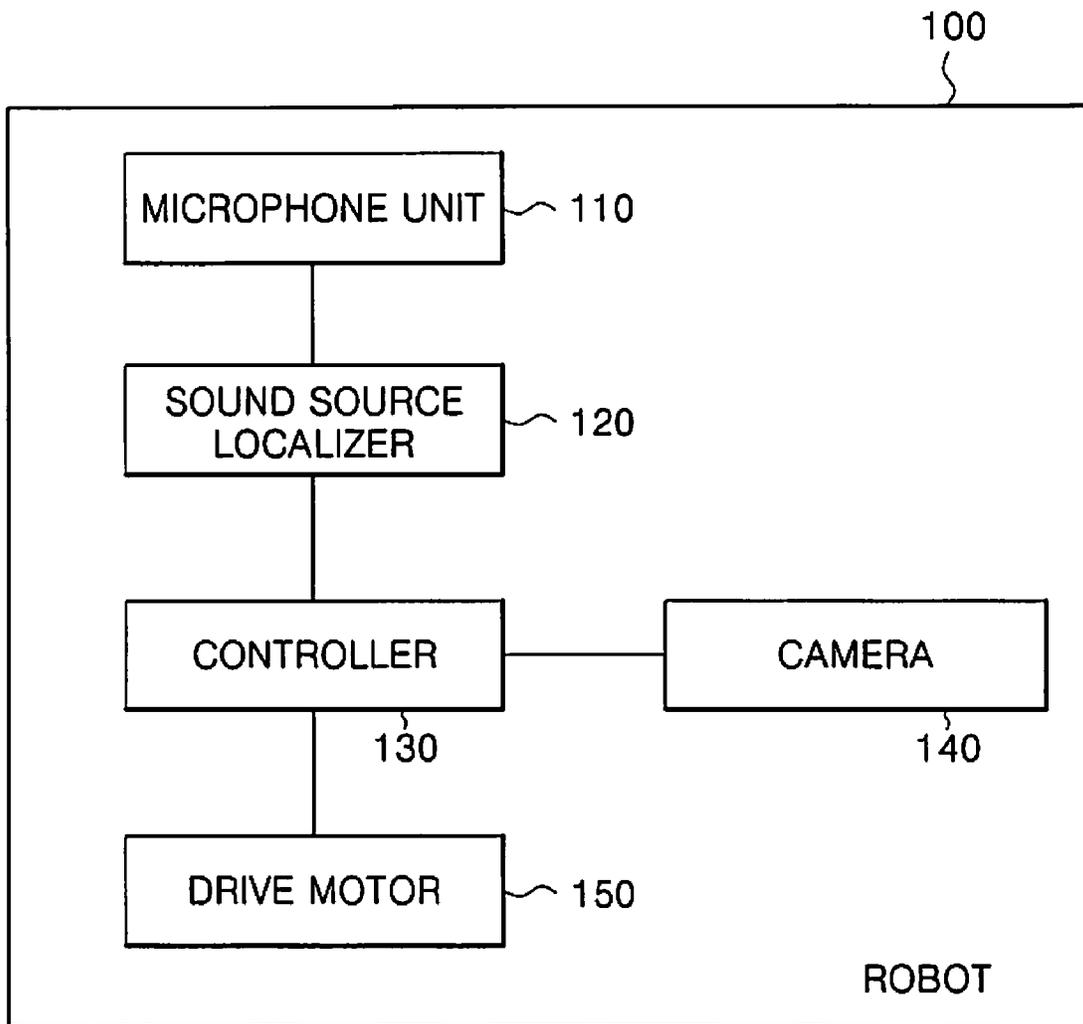


FIG. 4A

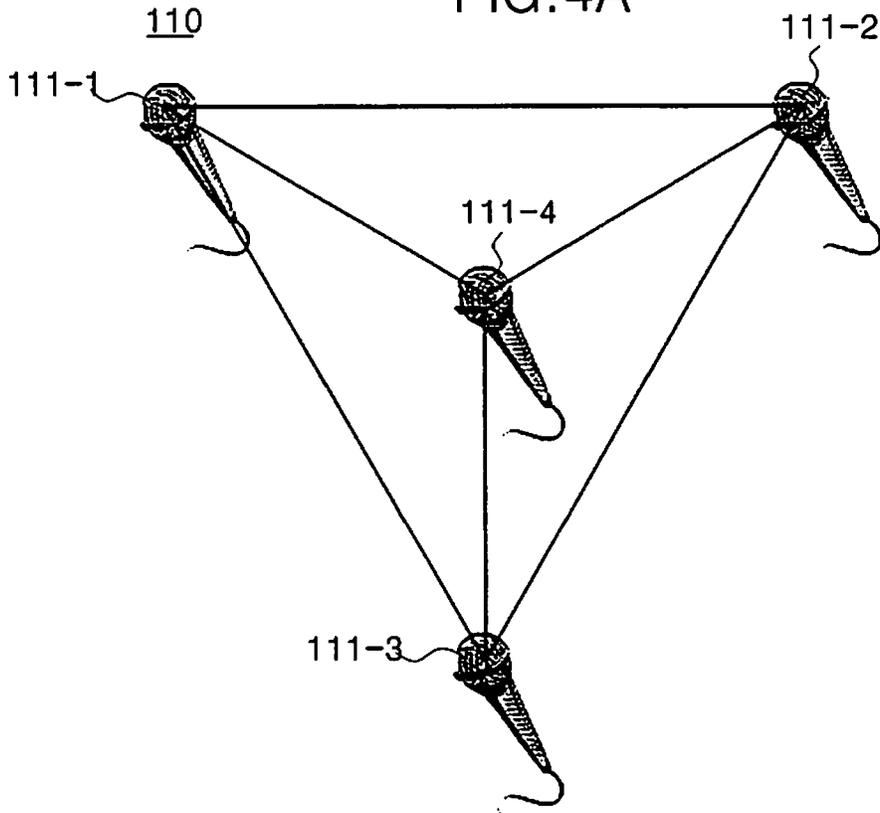


FIG. 4B

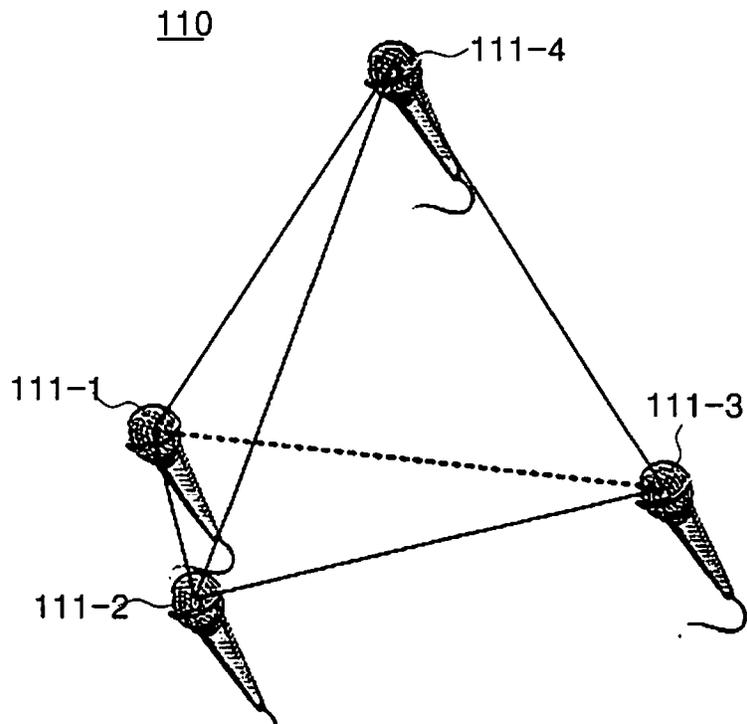


FIG. 5A

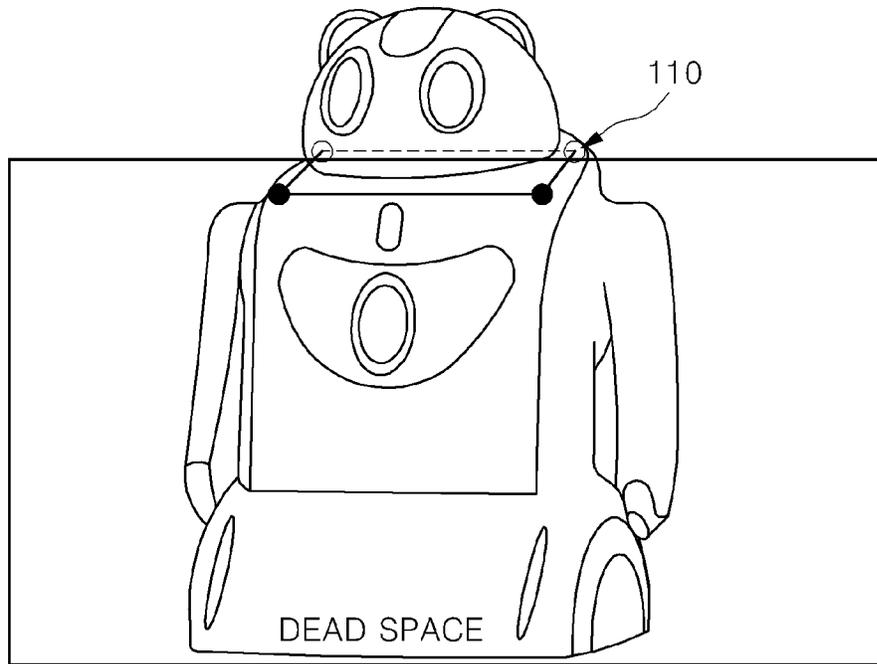
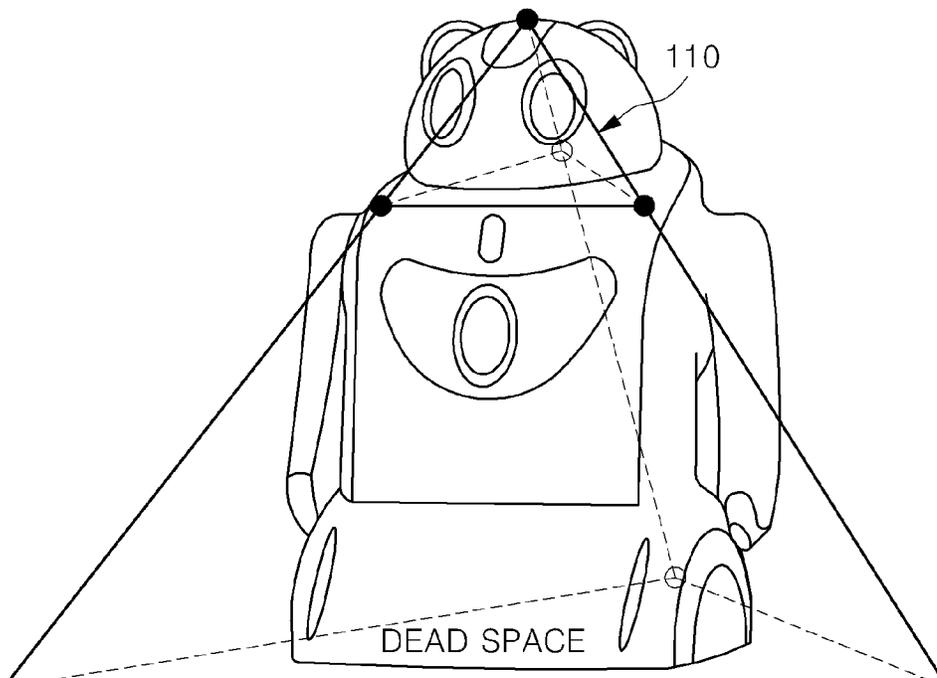


FIG. 5B



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